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A PENALIZED MODEL FOR PLASMA-WALL INTERACTION VALID IN THE GYROKINETIC FRAMEWORK

Context: gyrokinetic edge modelling requires plasma-wall interaction

- turbulent transport degrades tokamak confinement quality [Wootton 1990]
- Turbulence regulation mechanism: ExB sheared flows [Diamond 2005]
- Transport barriers formation at the separatrix is related to sheared flows [Wagner 1982]
- Global gyrokinetic codes need plasma-wall interaction to describe edge plasmas

Penalized sheath model valid in gyrokinetic framework

- Limiter included in simulation domain (immersed/penalized BC)
- Ion absorption in limiter using infinite penalization [Caschera 2018]

 $F_s(r, \theta, \varphi, v_{\parallel}, \mu) = F_s(1 - M_{lim}) + F_T M_{lim}$ $F_T \ll 1$ Maxwellian $M_{lim} = 1$ in limiter

Slow electrons reflected taking advantage of backward semi-Lagrangian method

Plasma-wall interaction triggers turbulence in edge plasma [Dif-Pradalier 2022]

> Plasma-wall interaction influences the SOL radial electric field $E_r \propto -\nabla T_e/e$ [Stangeby]

Difficulty: plasma-wall interaction is subgrid for gyrokinetic codes

Debye sheath

Gyrokinetic theory

(usual sheath-limited SOL values)

Length scale $\lambda_D = \sqrt{\frac{\varepsilon_0 T}{ne^2}} \approx 10 \ \mu m$

Length scale $\rho_i = \frac{m_i v_\perp}{\rho_B} \approx 100 \ \mu m$ <

Timescale $\omega_{pe} = \sqrt{\frac{ne^2}{m_e \varepsilon_0}} \approx 200 \text{ GHz}$

Timescale
$$\Omega_{ci} = \frac{eB}{m_i} \approx 100 \text{ MHz}$$

Debye sheath **positively charged**

 \neq Quasineutral plasma

Plasma-wall interaction model must ensure quasineutrality

 \gg

Preliminary study of plasma wall interaction : 1D1V kinetic model using Voice code

$$\begin{split} X_{GC} & X_{GC}^{\delta\star} \text{ time } t \\ t + \Delta t & plasma \\ M_{lim} = 0 \\ \\ M_{lim} = 1 \\ \langle \Gamma_i \rangle_{lim} = \langle \Gamma_e \rangle_{lim} - \int_{S_{lim}} d^2S \int_{-\infty}^{-v_c} d\bar{v}_{\parallel} \int_{0}^{+\infty} d\mu J_v J_0 F_i \left(\bar{v}_{\parallel} \mathbf{b}_{\parallel}^* + \mathbf{v}_{\perp} \right) \cdot \mathbf{n} \end{split}$$

- Fast electrons absorbed during reflection procedure
- Cutoff v_c computed to ensure vanishing current on spatial average over limiter surface

$$\langle \Gamma_i \rangle_{\lim} = \langle \Gamma_e \rangle_{\lim} - \int_{S_{\lim}} d^2 S \int_{-\infty}^{-\nu_c} d\nu_{\parallel} \int_{0}^{+\infty} d\mu J_{\nu} F_e (\nu_{\parallel} \boldsymbol{b}_{\parallel}^* + \boldsymbol{\nu}_{\perp}) \cdot \boldsymbol{n}$$

Results

 $\langle ... \rangle_{lim}$ limiter spatial avg.

n limiter normal vector

- Electron distribution function from GYSELA code (after few iterations, fixed v_c)
- ➢ Reflection slow electrons
- Smoothing procedure applied



[Munschy et al. 2024 Nucl. Fusion **64** 056027 & **64** 046013]

- ID plasma along field line, with two penalized models for the wall region: with / without currents in the wall;
- in both cases: equality of ion and electrons fluxes at the plasma boundary

Logical and conducting sheath approaches

- Methods applied on last grid point (≠ penalization)
 - > Limiter **not included** in simulation domain



Logical sheath [Parker 2015]

 $\Gamma_e = \Gamma_i$

Imposed on each point of limiter

surface determines v_c

Conducting sheath [Shi2015] $v_c = \sqrt{2e\phi_w/m_e}$ $\phi_w(r,\theta,\varphi)$ electric potential on limiter surface

The 5D global full-f Gysela code

With Strang splitting for gyrokinetic equation, advections with backward semi-Lagrangian scheme



> Currents are not matched precisely enough on limiter surface



- Absorption of ions & fast electrons, reflection of slow electrons : with penalized limiter;
- Electron and ion fluxes matched on spatial average over limiter surface;
- Kinetic electron response required in SOL;
- Apparition of negative charge on limiter surface to investigate. Possible causes: Numerical implementation « cleanliness »(limiter not aligned with mesh); > QN solver operates on whole plasma + limiter domain ;

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