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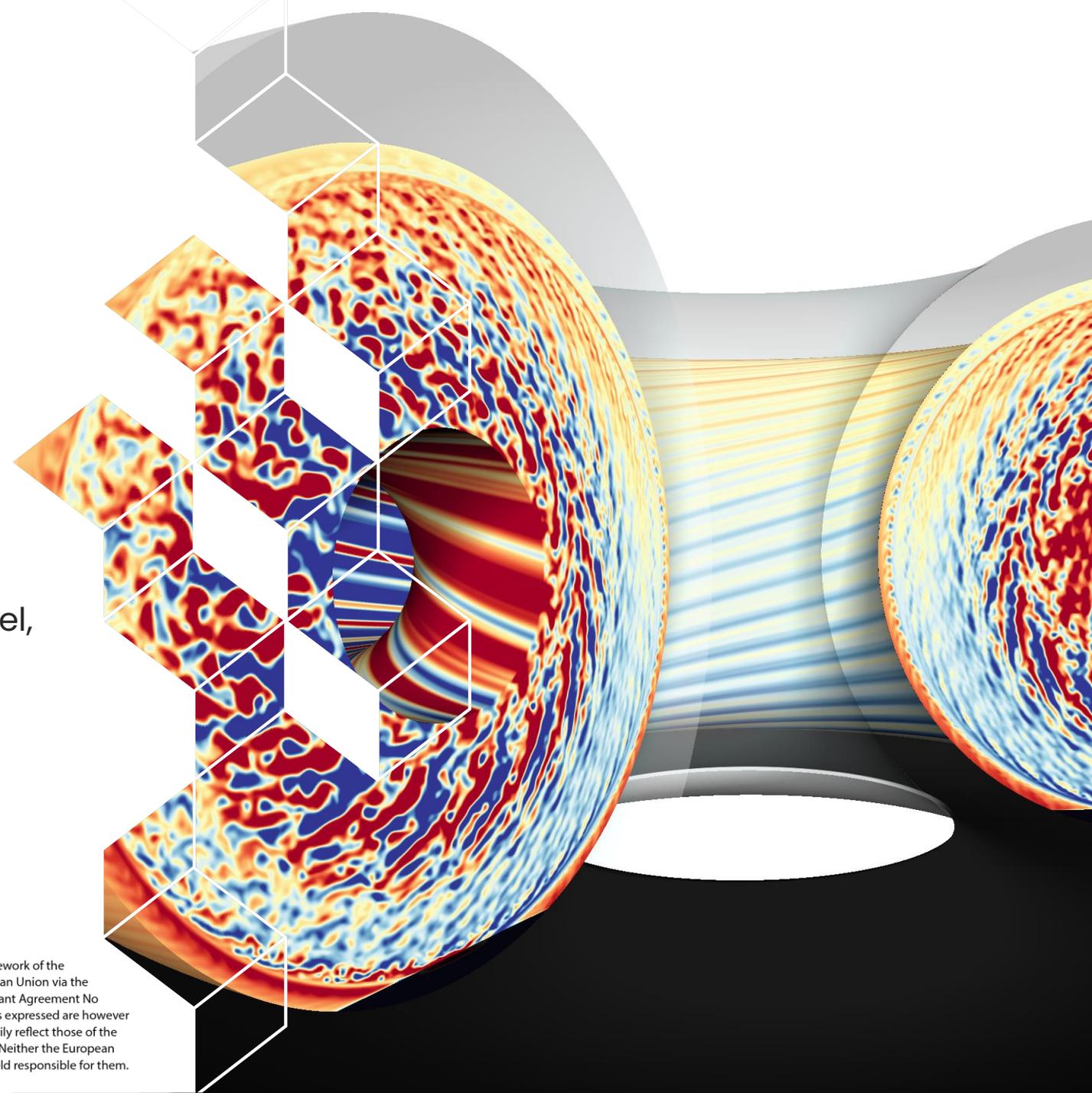
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## Plasma-wall interaction: comparison between kinetic simulations and fluid theory

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Ack. : GYSELA team, TSVV4

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Conference*



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# Core-edge-wall interaction influences tokamak confinement quality

- Microscale turbulence  $\Rightarrow$  cross-field transport  $\Rightarrow$  degrades the confinement unless a transport barrier exists

[Wagner1982]

- Turbulence regulated by ExB sheared flow at LCFS

$$\text{core } E_r \propto \frac{\nabla P}{en} \quad \text{SOL } E_r \propto -\frac{\nabla T_e}{e}$$

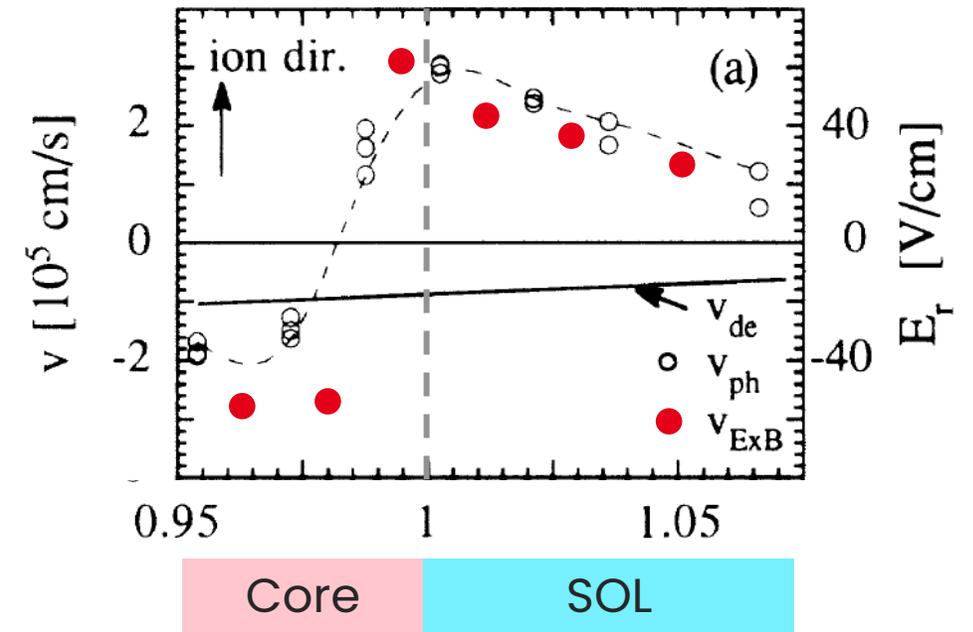
## $E_r$ in SOL influenced by plasma-wall interaction

[Stangeby]

- Goals : 1) study of kinetic plasma wall interaction  
2) implementation in GYSELA gyrokinetic code (WIP)

[Ritz 1991]

- ExB velocity in DIII-D tokamak



# Plasma wall interaction results from absorbing wall and inertia difference between ions and electrons

[Stangeby 2000, ...Ghendrih 2011 and many more]

- Electrons: low inertia compared to ions
- Positively charged layer: Debye sheath (Poisson)

$$\lambda_D = \sqrt{\frac{\epsilon_0 T_0}{n_0 e^2}} \approx 10^{-5} m$$

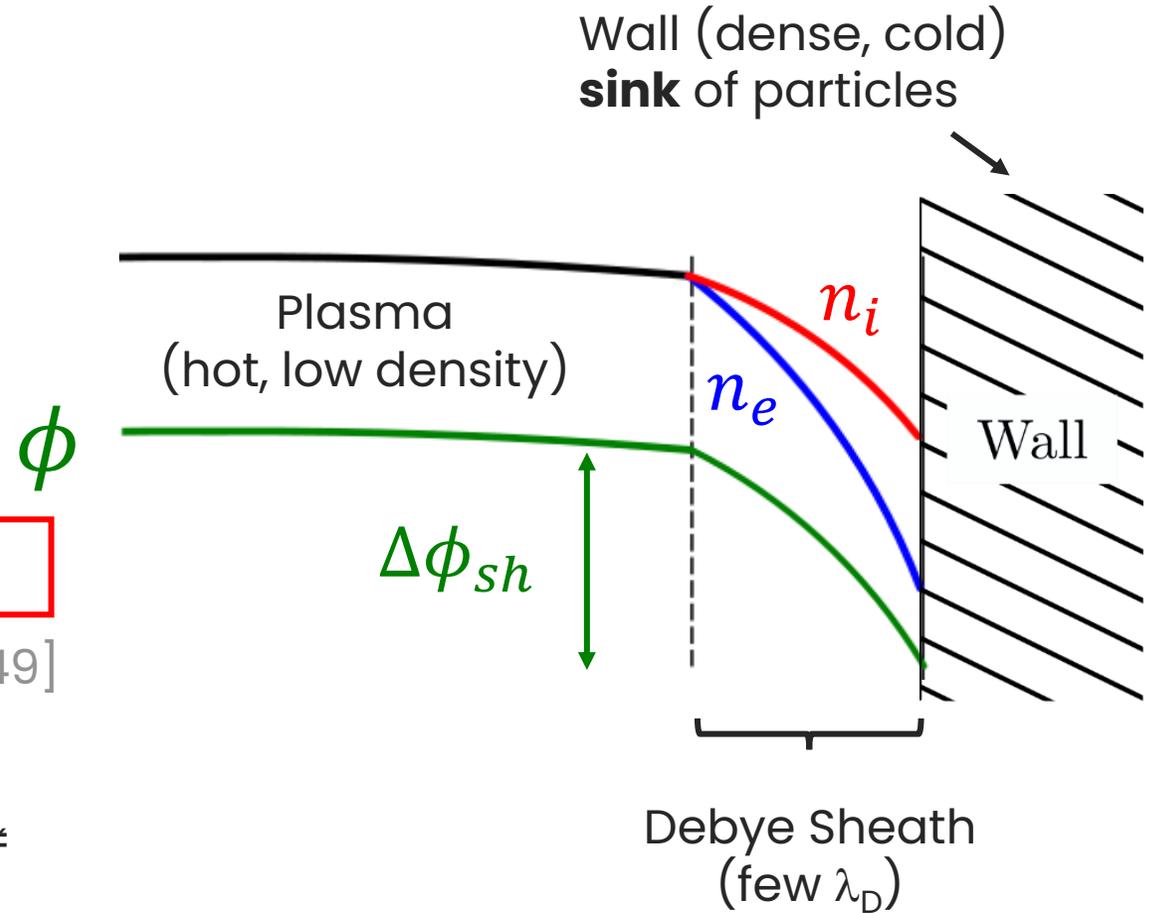
- Main properties of sheath:

Repels slow electrons

Accelerates ions

⇒ In avg. no net current at wall [Bohm1949]

- $\lambda_D \ll \rho_c$  turbulent scale → sheath difficult to describe in turbulence code, GK quasineutrality ≠ Poisson eq. (no  $\parallel$  Laplacian)

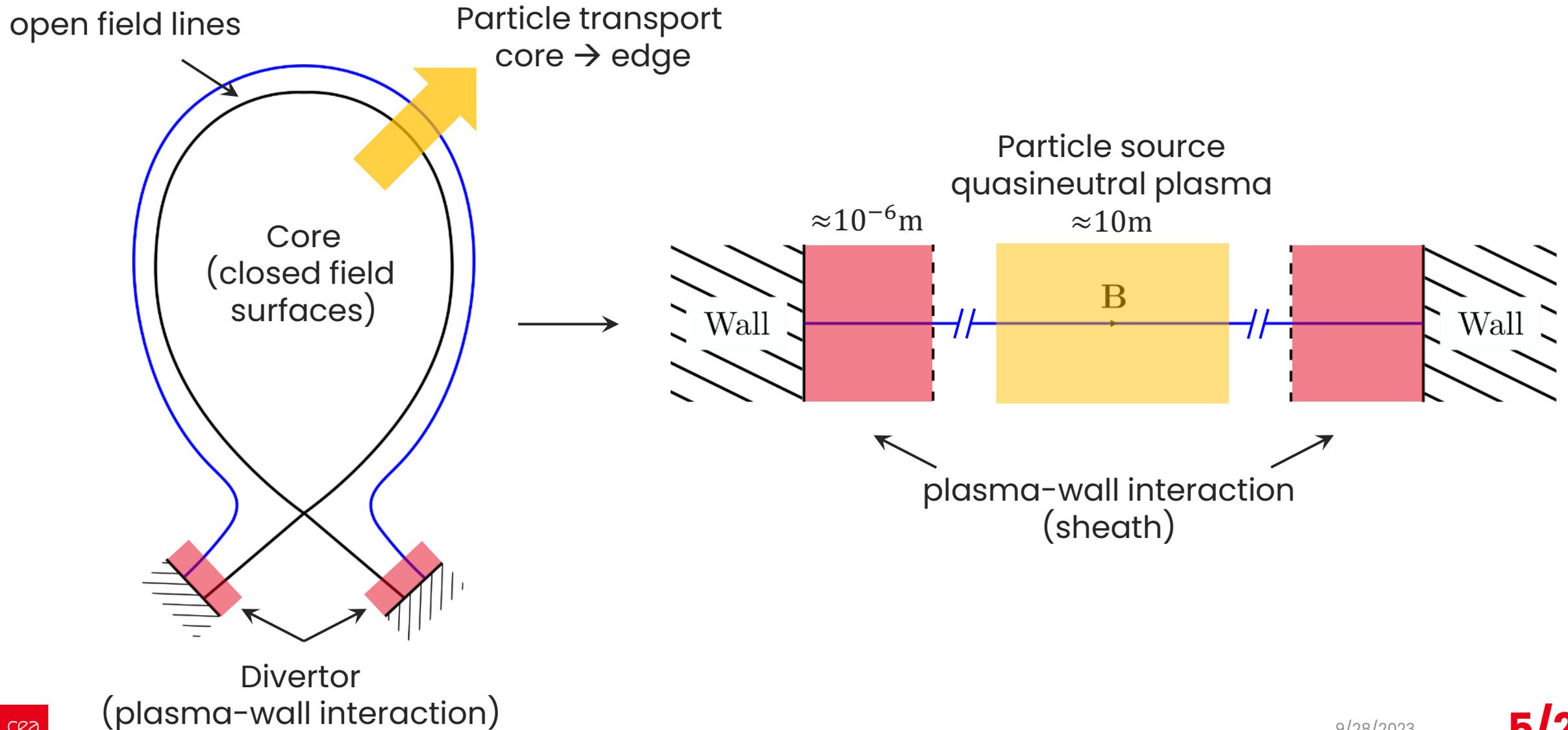




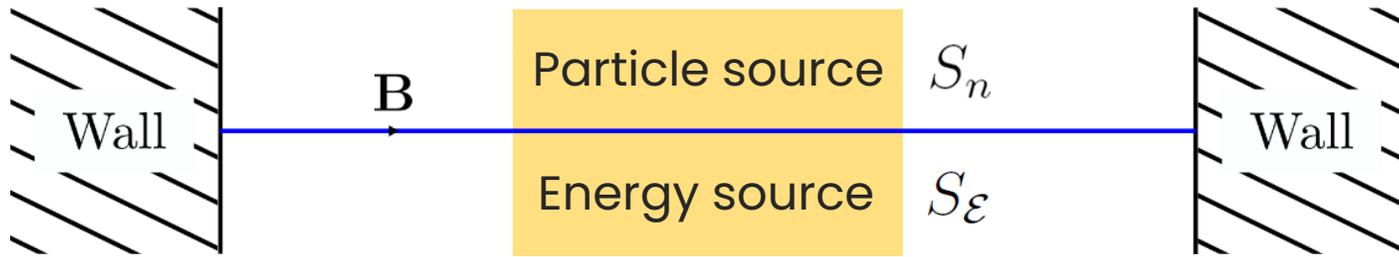
# **1 ■ Fluid theory of plasma-wall interaction**

## **2 ■ Comparison with kinetic simulations**

# Simplified 1D geometry: single magnetic field line, no curvature



# 1D fluid model to describe plasma along a magnetic field line



$x$  : position along magnetic field line

$a \in \{e, i\}$  ions and electrons

Density  $n_a$

particle flux  $\Gamma_a$

momentum flux  $\Pi_a = n_a T_a + m_a n_a u_a^2$

## Conservation of density

$$\partial_t n_a + \nabla_x \Gamma_a = S_n$$

## Conservation of energy

$$m_a \partial_t \Pi_a / 2 + \nabla_x Q_a = -e_a \Gamma_a \nabla_x \phi + S_E$$

## Conservation of momentum

$$m_a \partial_t \Gamma_a + \nabla_x \Pi_a = -e_a n_a \nabla_x \phi$$

Energy flux

$$Q_a = u_a \left( \frac{3}{2} n_a T_a + \frac{1}{2} m_a n_a u_a^2 \right) + Q_a^{\text{heat}}$$

Heat flux

$$Q_a^{\text{heat}} = \int_{-\infty}^{+\infty} dv \frac{1}{2} m_a (v - u_a)^3 f_a$$

Closure required !  
(zero for a maxwellian)

# Particle flux governed by the source

## Total pressure constant in quasineutral limit

**Steady state eq.**

$$\nabla_x \Gamma = S_n$$

$$\nabla_x \Pi = -e(n_i - n_e) \nabla_x \phi$$

$$\Gamma = \Gamma_e = \Gamma_i$$

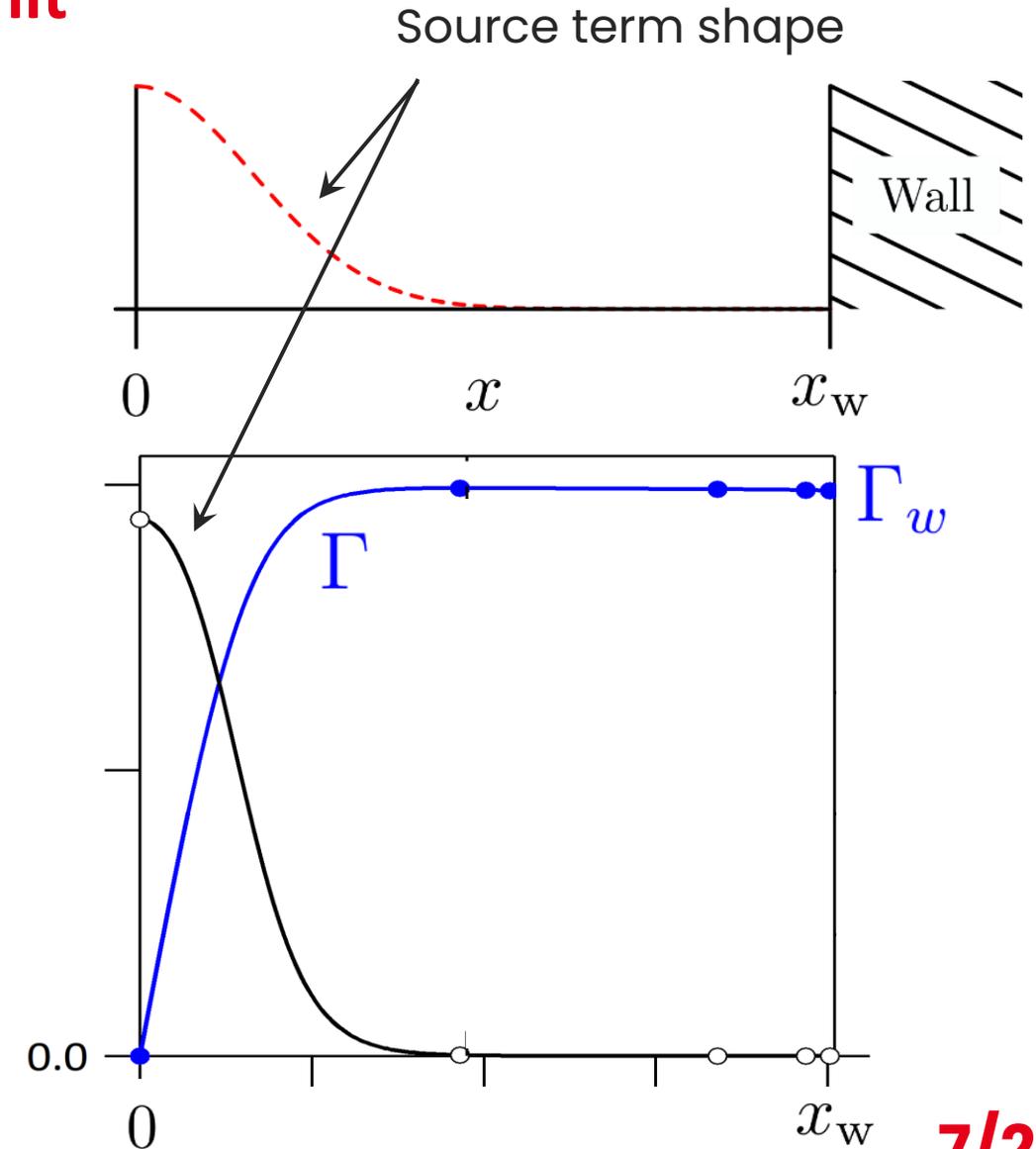
$$\Pi = \Pi_e + \Pi_i$$

Total pressure

- Quasineutral limit:  $n_i - n_e \approx 0$

$$\Pi = \text{constant} \quad \Gamma = \int_0^x ds S_n$$

- Rq:  $\Pi \approx \text{cte.}$  at sheath entrance



# Quasineutral plasma flow is necessarily subsonic

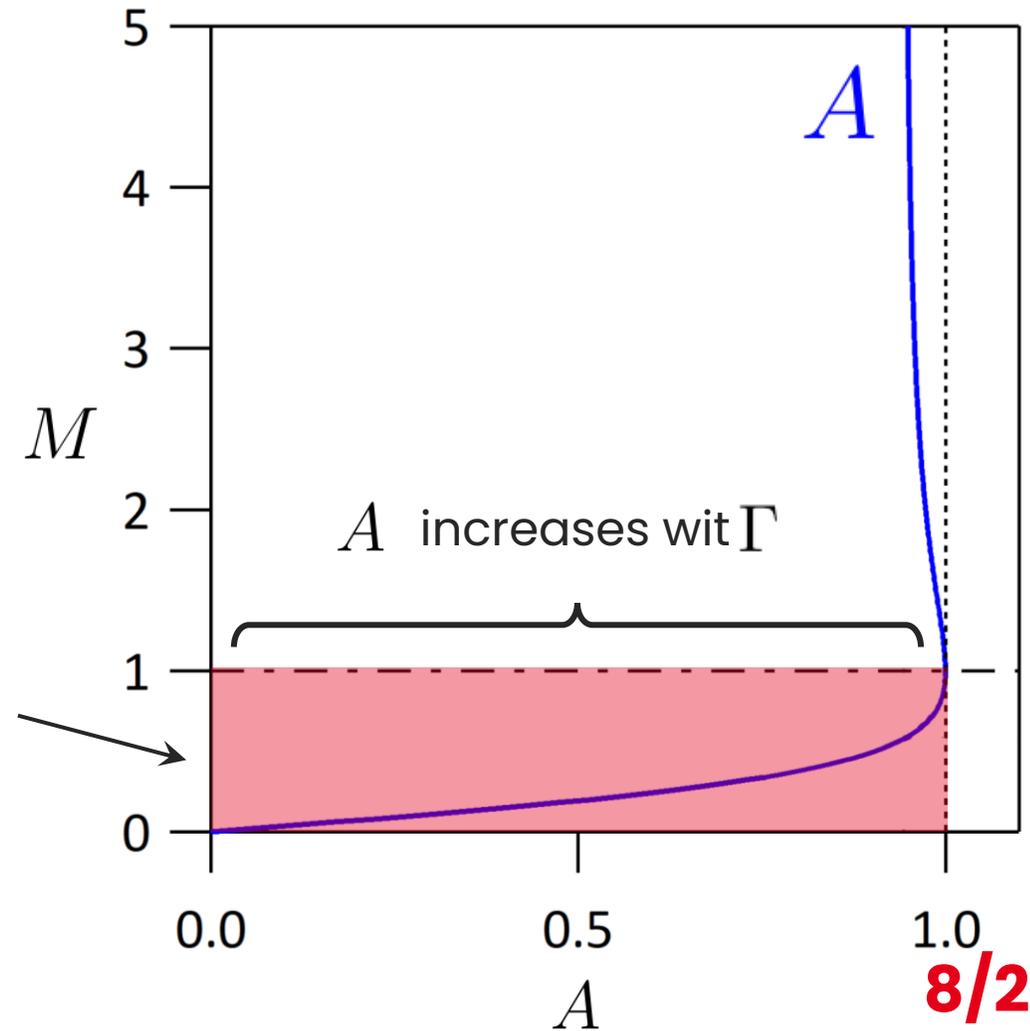
- Control parameter  $A = \frac{4\sqrt{m_i T_s} \Gamma}{3(\Pi + (n_i - n_e)T_e)} = \frac{\sqrt{8(1+M^2)}M}{(1+3M^2)}$

Constant  
(quasineutral plasma)  $\nearrow$

$$\Gamma = \int_0^x ds S_n \longrightarrow \begin{cases} A \text{ is maximum after} \\ \text{source region} \\ A \text{ increases} \end{cases}$$

Mach number  $M = u_i/c_s \leq 1$  in quasineutral plasma

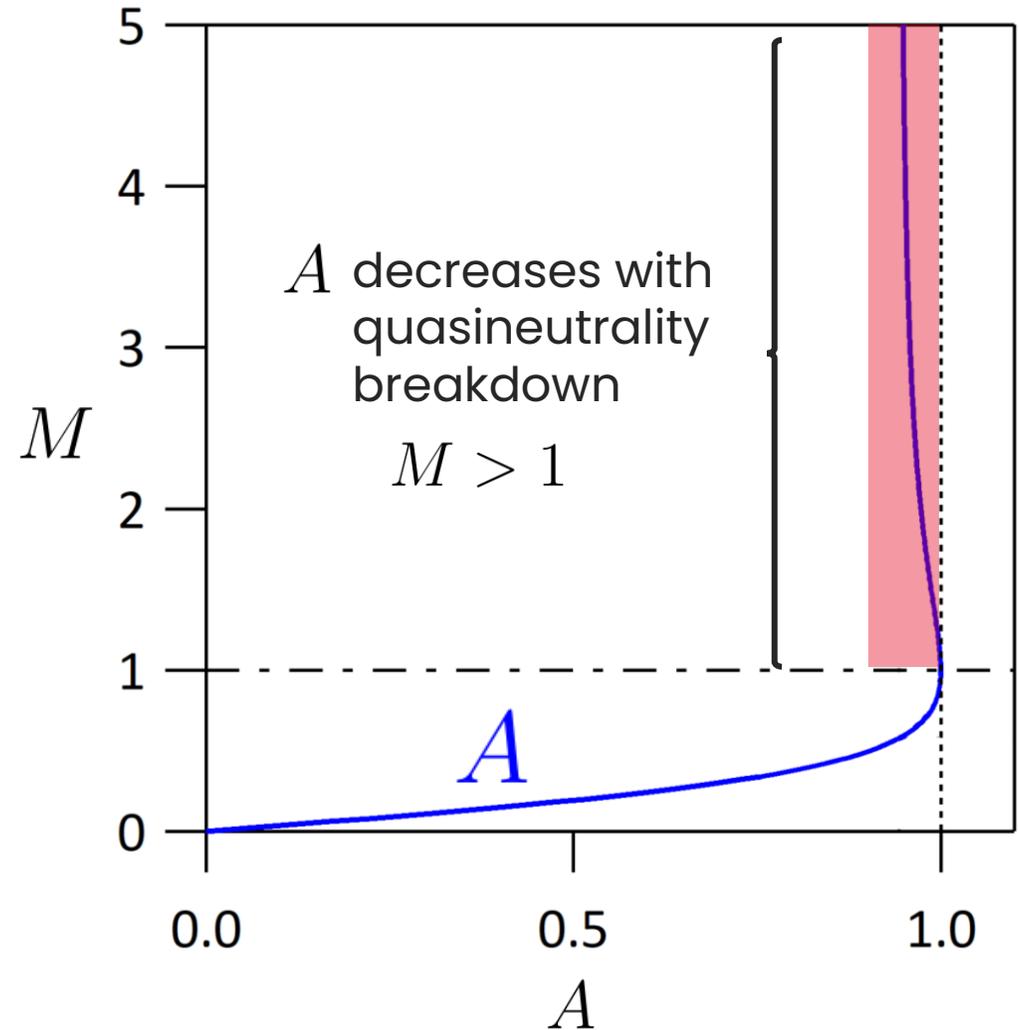
$c_s = \sqrt{3T/m_i}$  from Maxwellian closure



# Supersonic transition driven by quasineutrality breakdown

$$A = \frac{4\sqrt{m_i T_s} \Gamma}{3(\Pi + (n_i - n_e)T_e)} = \frac{\sqrt{8(1 + M^2)}M}{(1 + 3M^2)}$$

- Outside source region  $\Gamma = \text{constant}$
  - At the sheath entrance  $n_i - n_e > 0$
  - $\partial_x \Pi \ll \partial_x \{(n_e - n_i)T_e\}$
- Decrease of A driven by quasineutrality breakdown
- Scale separation sheath size  $\ll$  plasma size  
 $\rightarrow M > 1$  in sheath



# Sound speed critically depends on the chosen closure

- $M = 1$  At sheath entrance  $M = u_i/c_s$   $c_s$  **closure-dependent !**
- Isothermal** closure  $T_a = cst$   $c_s = \sqrt{T/m_i}$   $\longrightarrow$ 

$$\left\{ \begin{array}{l} \text{Similar expression for } A_s \\ A = 2\sqrt{m_i T_0} \frac{\Gamma}{\Pi} = \frac{2M}{1+M^2} \end{array} \right.$$
 [Ghendrih2011]
- Maxwellian** closure  $Q_a^{\text{heat}} = 0$   $c_s = \sqrt{3T/m_i}$
- Polytropic** closure  $\frac{dp}{p} - \gamma_p \frac{dn}{n} = 0$   $c_s = \sqrt{\gamma_p p/m_i n}$
- High order** linear closure  $N_\ell = 0$   $c_s = \left( \ell \frac{N_{\ell-1}}{n} \right)^{1/(\ell-1)}$  with  $N_\ell = \int dv (v-u)^\ell f$



**1** ■ **Fluid theory of plasma-wall interaction**

**2** ■ **Comparison with kinetic simulations**

# Boltzmann-Poisson system 1D in space and 1D in velocity to study kinetic plasma wall interaction

## Normalized Boltzmann eq.

$$\partial_t f_a + \sqrt{A_a} (v_a \partial_x f_a - Z_a \partial_x \phi \partial_{v_a} f_a) = \mathcal{C}(f_a) + \mathcal{S}(f_a)$$

Electrons & ions  
distribution function

$$f_a(x, v_a, t)$$

mass ratio

$$A_a = \frac{m_e}{m_a}$$

## Normalized Poisson eq.

$$\partial_x^2 \phi = -\rho$$

$$\rho = \sum_{\text{species}} Z_a n_a$$

$$n_a = \int_{-\infty}^{+\infty} dv f_a$$

- Normalizations:

$$\text{time } \omega_{pe0} = \sqrt{\frac{\varepsilon_0 T_0}{n_0 e^2}}$$

$$\text{length } \lambda_{D0} = \sqrt{\frac{\varepsilon_0 T_0}{n_0 e^2}}$$

$$\text{velocity } v_{T0a} = \sqrt{\frac{T_0}{m_a}}$$

Single species collisions → Fokker-Planck operator

Inter species collisions → fluid-like momentum/energy exchange

$$Df_a/Dt = \mathcal{S}(f_a) + \mathcal{C}(f_a) \longrightarrow \mathcal{C}_{\text{intra}}(f_a) + \mathcal{C}_{\text{inter}}(f_a) \quad [\text{Dif-Pradalier2011, Estève 2015}]$$

**Intra species Fokker-Planck collision operator**

$$\mathcal{C}_{\text{intra}}(f_a) = \partial_v \left[ D_v f_M \partial_v \left( \frac{f_a}{f_M} \right) \right]$$

$D_v \propto 1/v^3$  Collisionality decreases with velocity

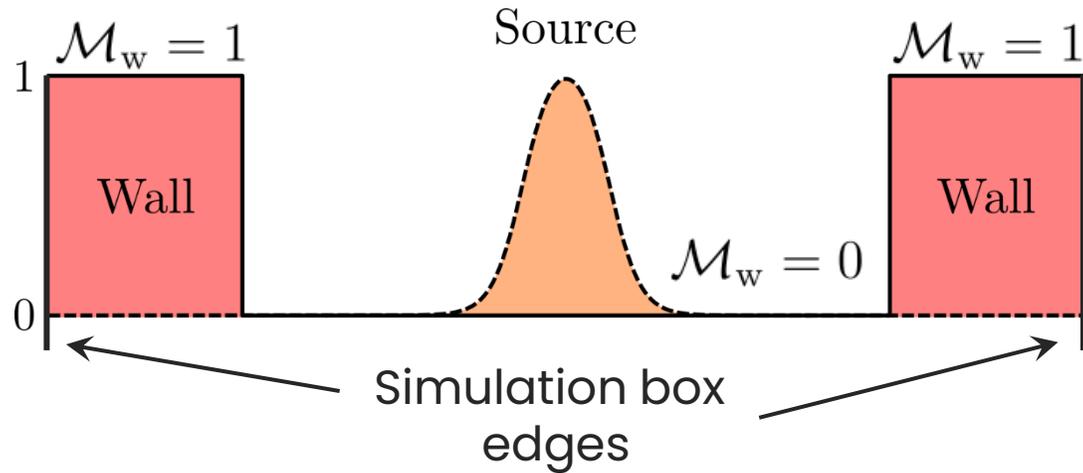
**Inter species collision operator**

$$\mathcal{C}_{\text{inter}}(f_a) = \frac{2Q_{ab}}{n_a T_a} \left[ \frac{m_a}{2T_a} (v_a - u_a)^2 - \frac{1}{2} \right] F_M + \frac{\mathcal{R}_{ab}}{n_a T_a} (v_a - u_a) F_M$$

$Q_{ab}$   $\mathcal{R}_{ab}$  Momentum & energy exchange terms

# Wall = particle, momentum, energy sink immersed in plasma

$$Df_a/Dt = \mathcal{C}(f_a) + \mathcal{S}(f_a) \longrightarrow \mathcal{S}_{\text{src}}(f_a) + \mathcal{S}_{\text{sink}}(f_a)$$



- Relaxation of  $f_a$  towards  $g$  in the wall

$$\mathcal{S}_{\text{sink}}(f_a) = -\nu \mathcal{M}_w(x) (f_a - g)$$

$$g(v) = \frac{n_w}{\sqrt{2\pi T_w}} e^{-\frac{v^2}{2T_w}}$$

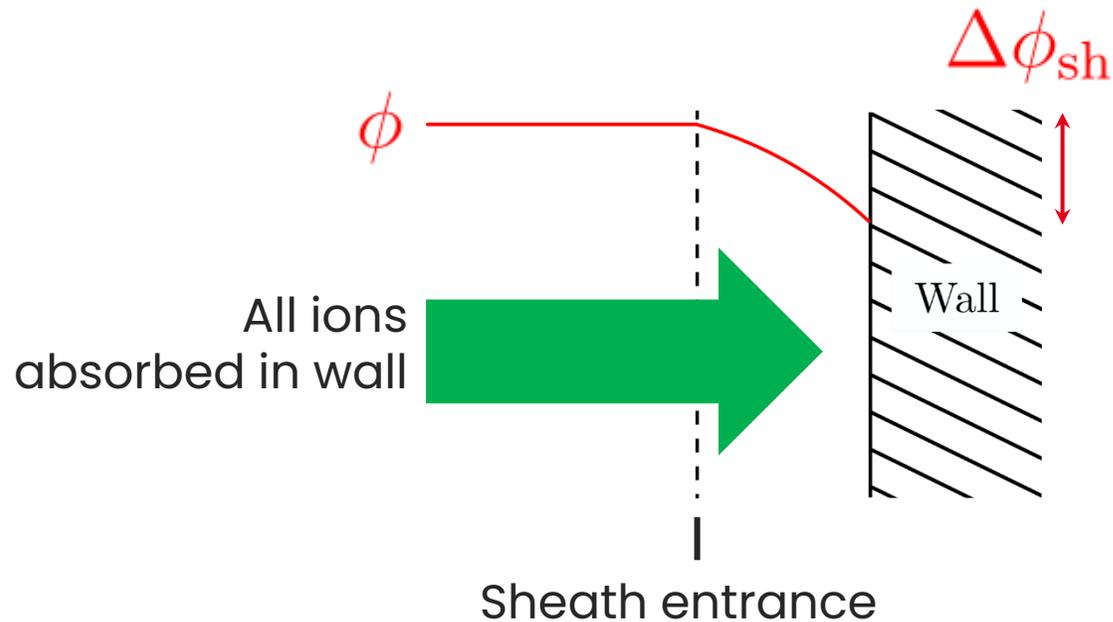
$$\begin{aligned} n_w &\approx 10^{-9} \ll 1 \\ T_w &< T_{\text{src}} \end{aligned}$$

- Particles, momentum energy absorption in wall
- Wall **immersed** inside simulation domain

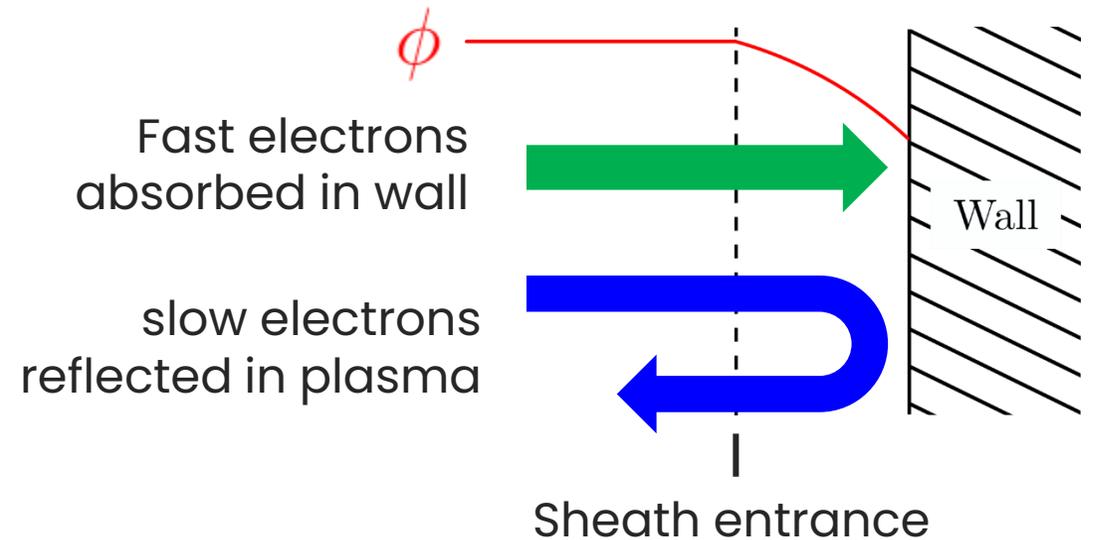
- No boundary condition @ plasma-wall transition
- Decorrelate sheath physics from numerical BC

# Expected kinetic physics: ion accelerated towards the wall slow electrons reflected back to plasma

- Acceleration of ions



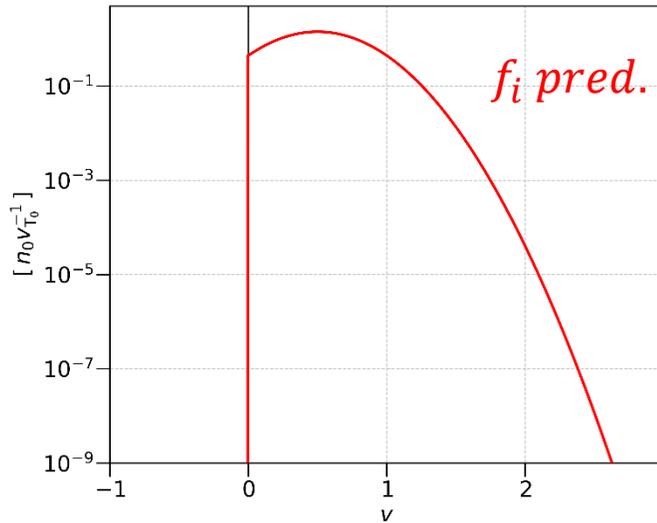
- Reflection of slow electrons



- Cut-off velocity between fast and slow electrons  $v_c = \sqrt{\frac{2e|\Delta\phi_{sh}|}{m_e}}$
- Steady state at wall:  $\Gamma_i = \Gamma_e$

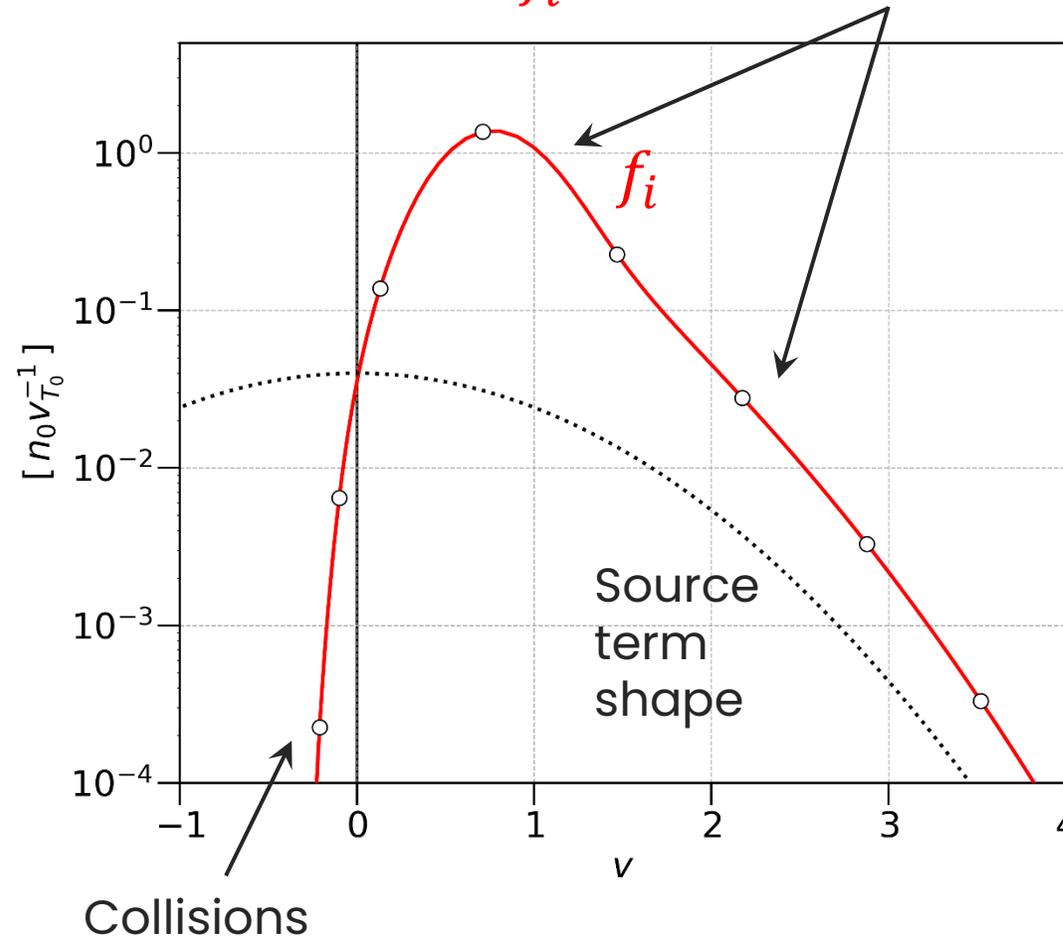
# Ion distribution function at sheath entrance: acceleration & no ions coming back from the wall

- **Prediction** for  $f_i$



- Positive mean velocity (Bohm criterion ?)
- No ions coming back from wall

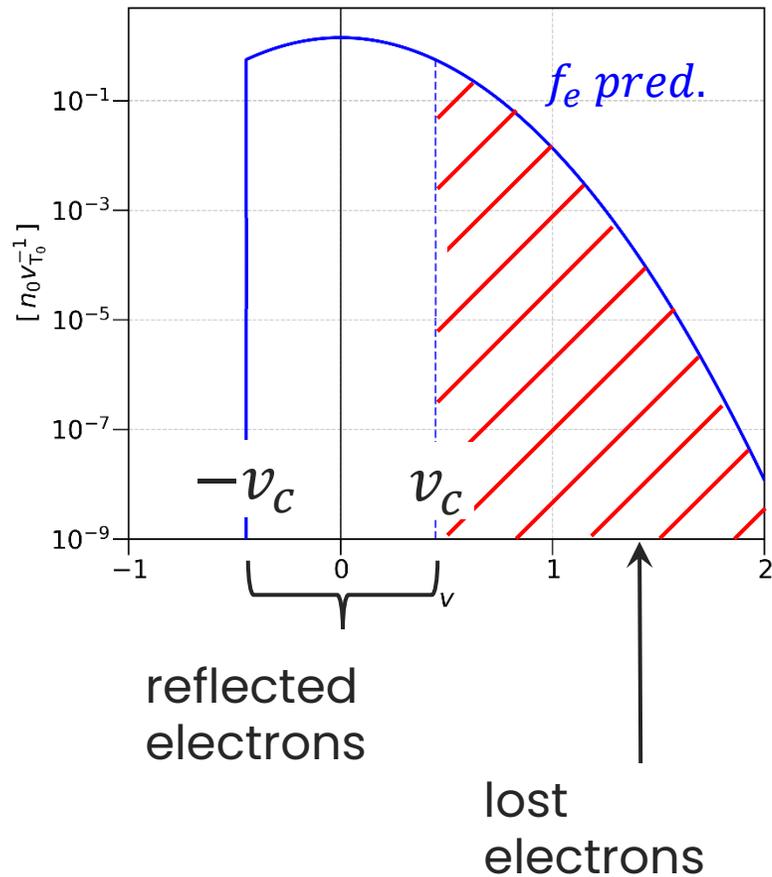
- **Simulation**  $f_i$



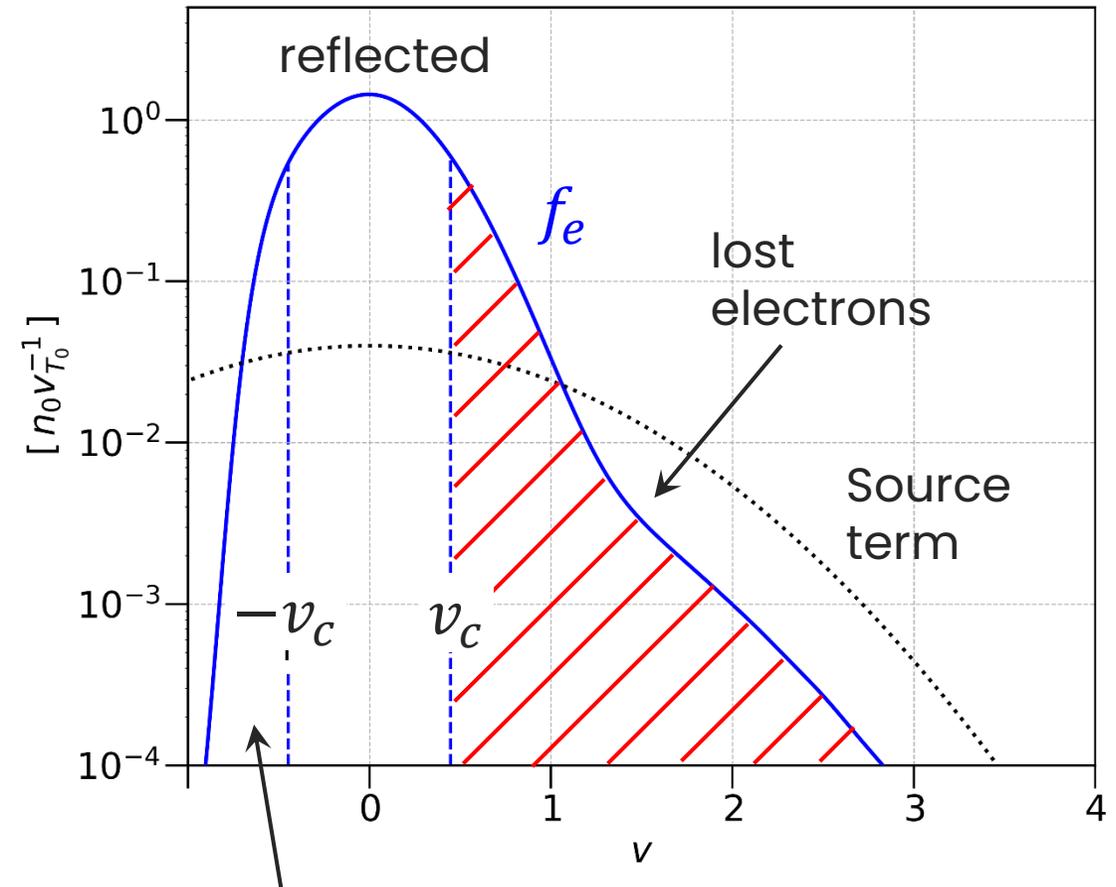
# Electron distribution function at sheath entrance: slow electrons reflected into plasma, fast ones absorbed

$$v_c = \sqrt{\frac{2e |\Delta\phi_{sh}|}{m_e}}$$

- Prediction for  $f_e$



- Simulation  $f_e$

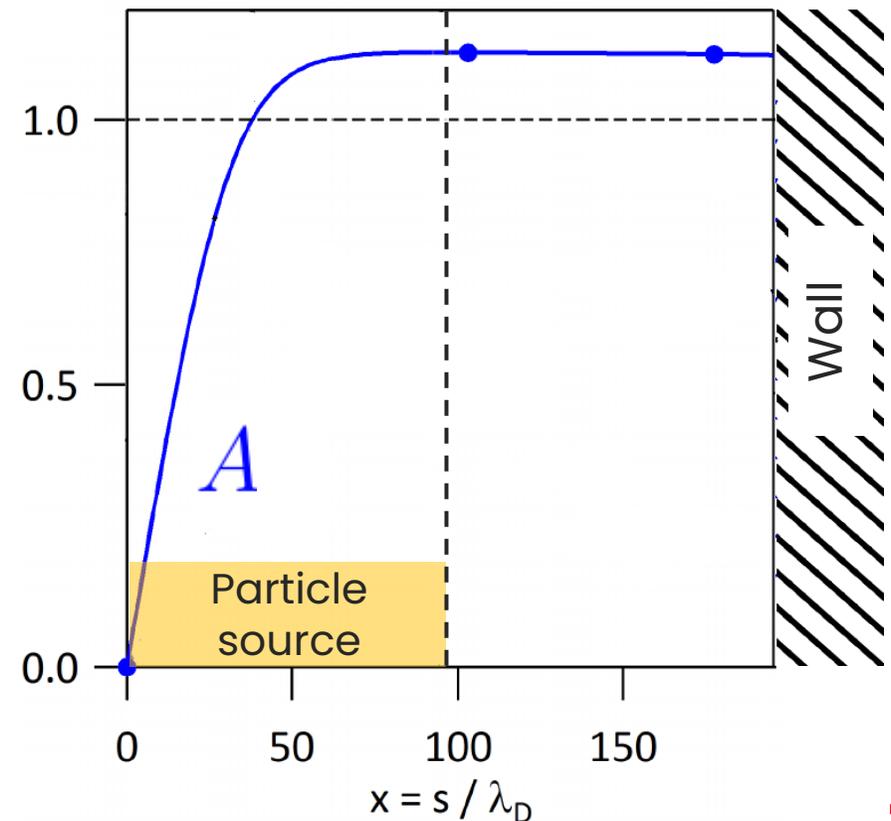
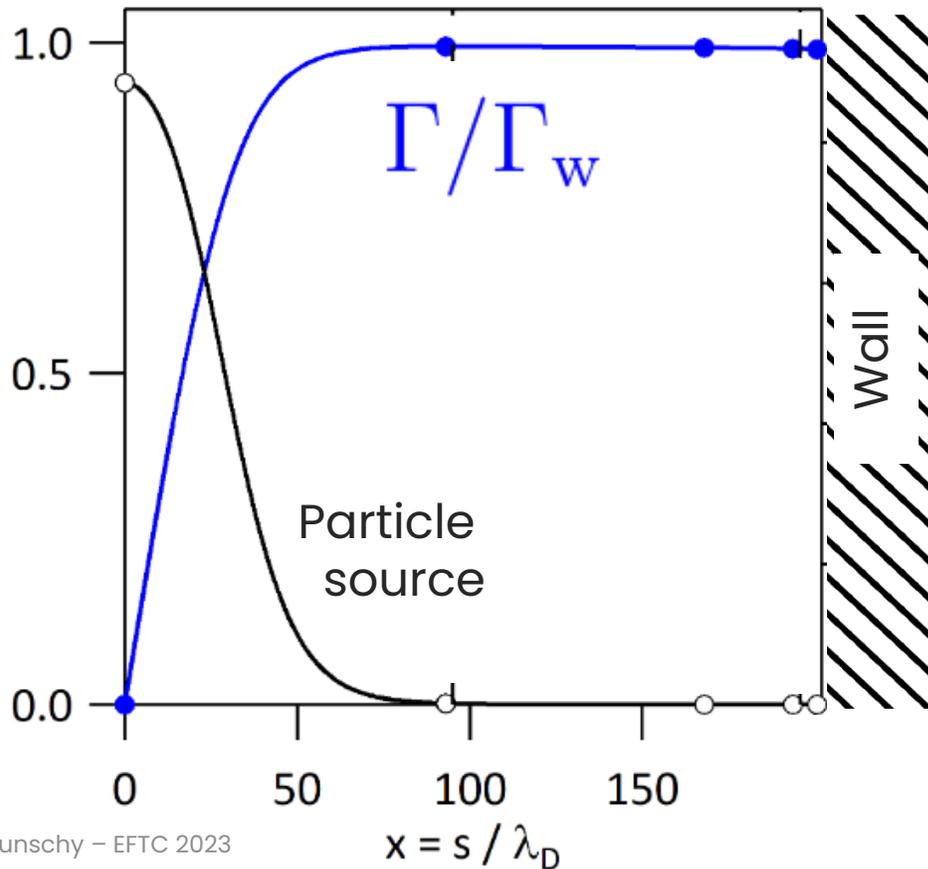


Finite strength of penalization  
& collisions

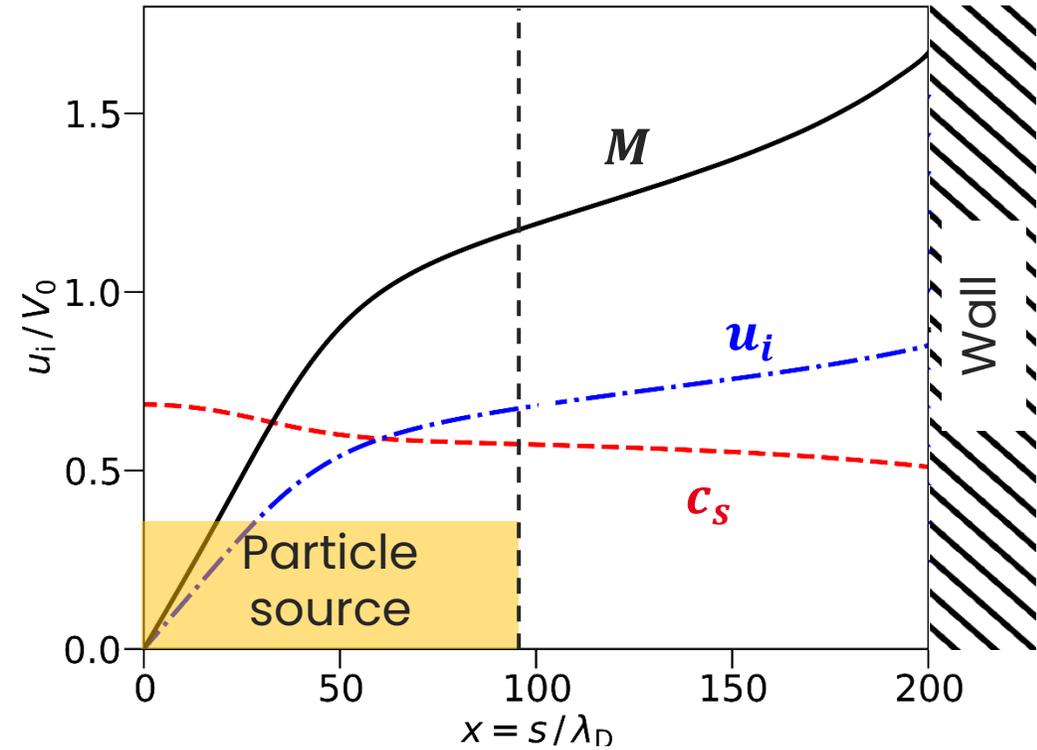
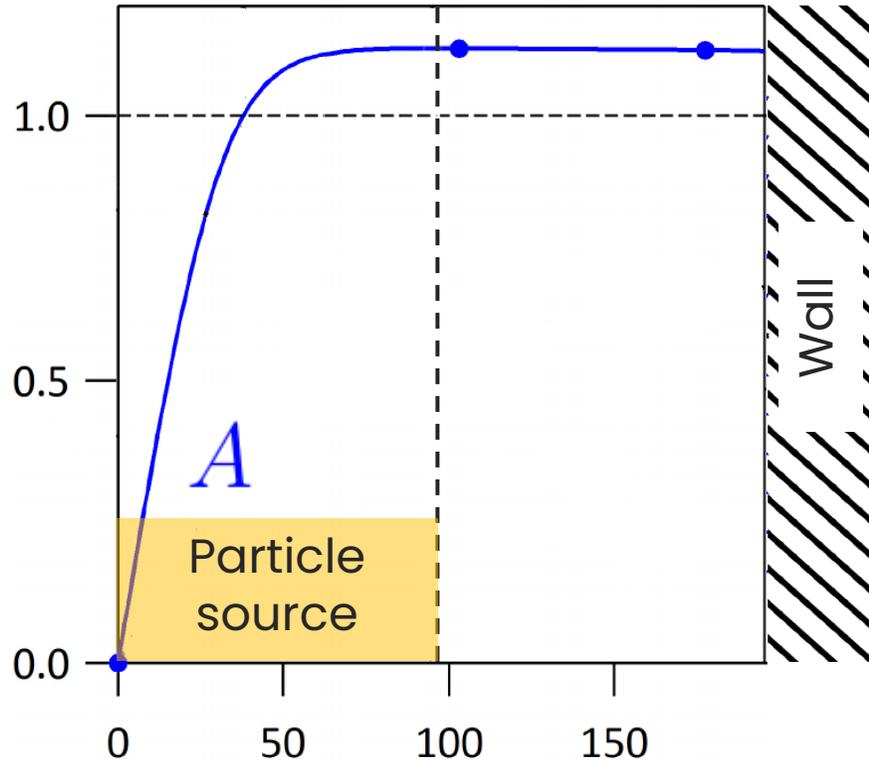
# A parameter constant after source region → fluid theory suggests subsonic regime

- Maxwellian closure
 
$$\begin{cases} \Pi = \text{constant} \\ \Gamma = \int_0^x ds S_n \end{cases}$$

$$A^2 = \frac{16m_i T_s \Gamma^2}{9(\Pi + (n_i - n_e)T_e)^2}$$



# Limit of fluid theory : Mach number cannot only depend on $A$



$$A = \frac{4\sqrt{m_i T_s} \Gamma}{3(\Pi + (n_i - n_e)T_e)} = \frac{\sqrt{8(1+M^2)}M}{(1+3M^2)}$$

From closure

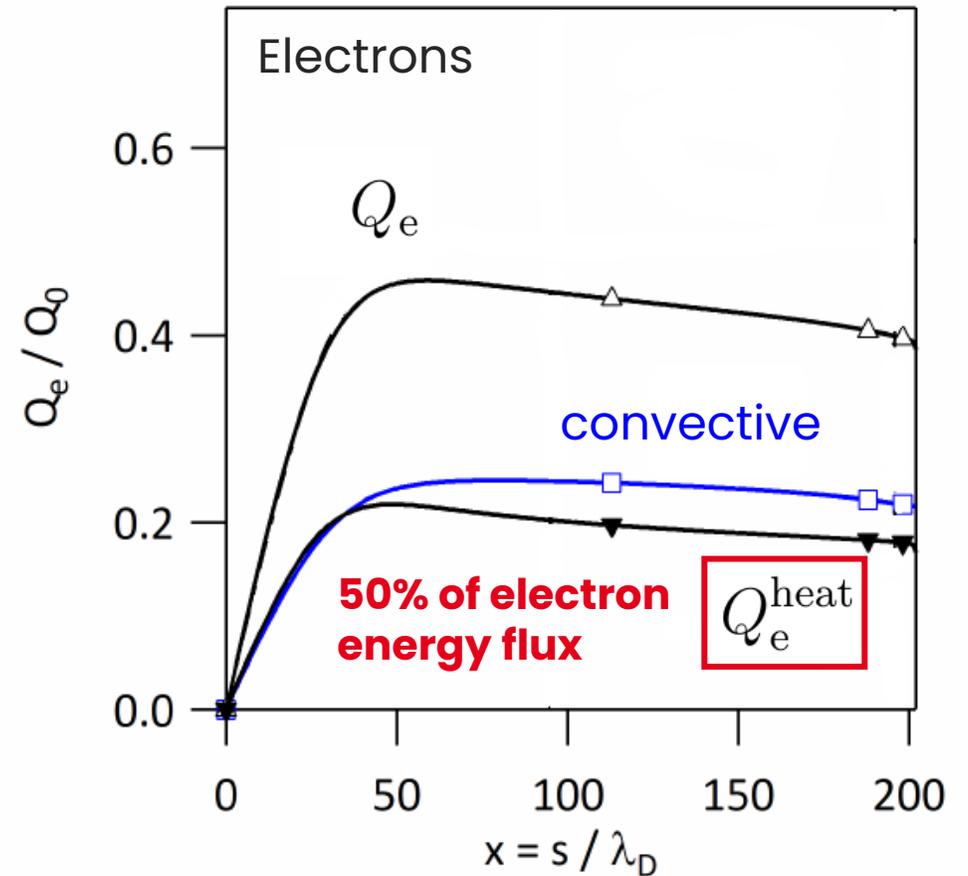
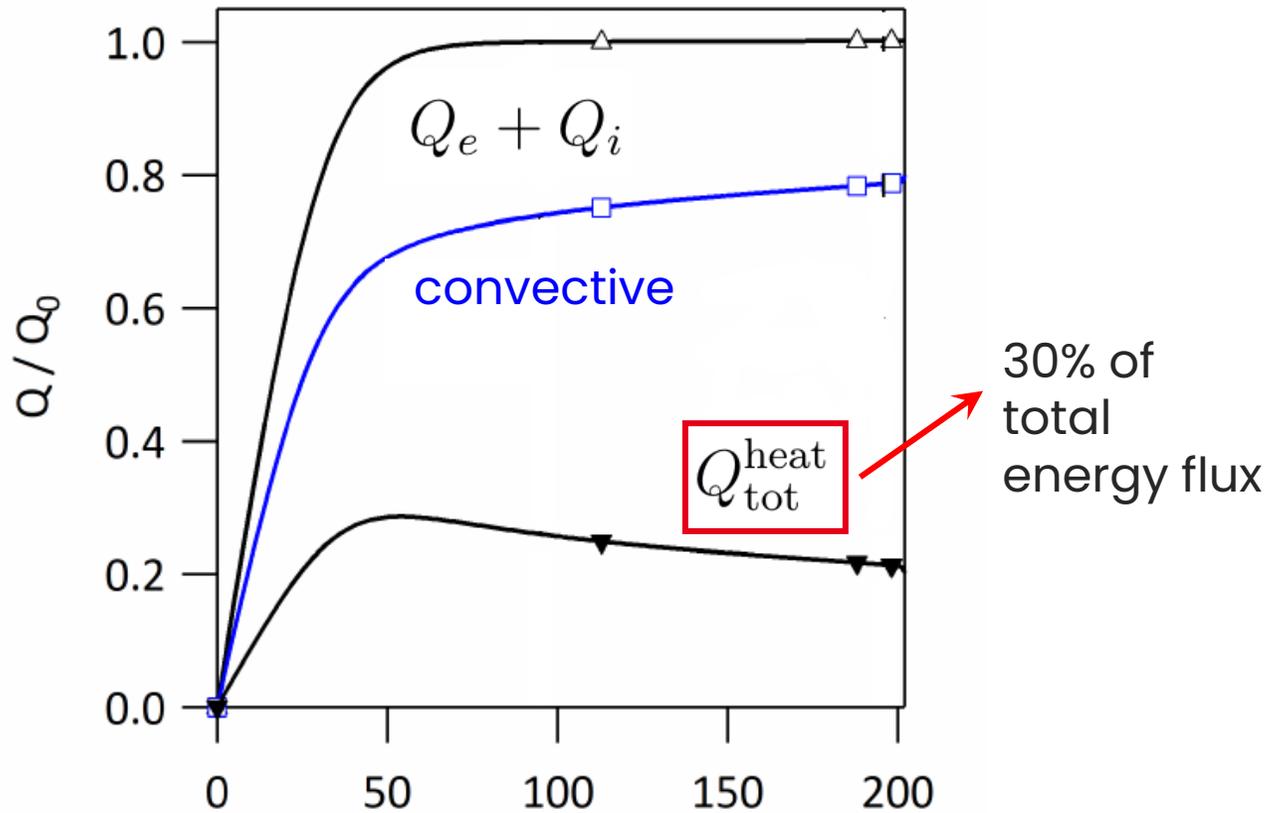
$M$  increases with constant  $A$

$$M = u_i/c_s \quad c_s = \sqrt{3T/m_i}$$

**Incompatible with fluid theory**

# Non vanishing electron heat flux: $Q_e^{\text{heat}} \approx Q_e/2$

Energy flux = convective + heat



$Q^{\text{heat}} \neq 0$  Maxwellian closure irrelevant

No known closure leads to correct prediction of heat flux

# Conclusion

- Comparison of kinetic simulation of plasma-wall interaction with fluid theory
- Trajectories of particles in plasma highlight kinetic sheath physics at play :
  - Acceleration of ions, reflection of slow electrons
  - Collisions
- Reduced fluid model fails to predict plasma behavior :
  - Sound speed critically depends on closure : **Bohm's criterion is unoperational**
  - Vanishing heat flux closure not relevant
  - Validity of **other closures can be questioned** : isothermal, zero collisional flux, high order moments...
  - Sheath heat transmission factor in good agreement with predictions (6% difference)

[Munschy et al. 2023] *Kinetic plasma-sheath self organization*

[Munschy et al. 2023] *Kinetic plasma-wall interaction using immersed boundary conditions*



# Sheath heat transmission factor: good agreement with predictions

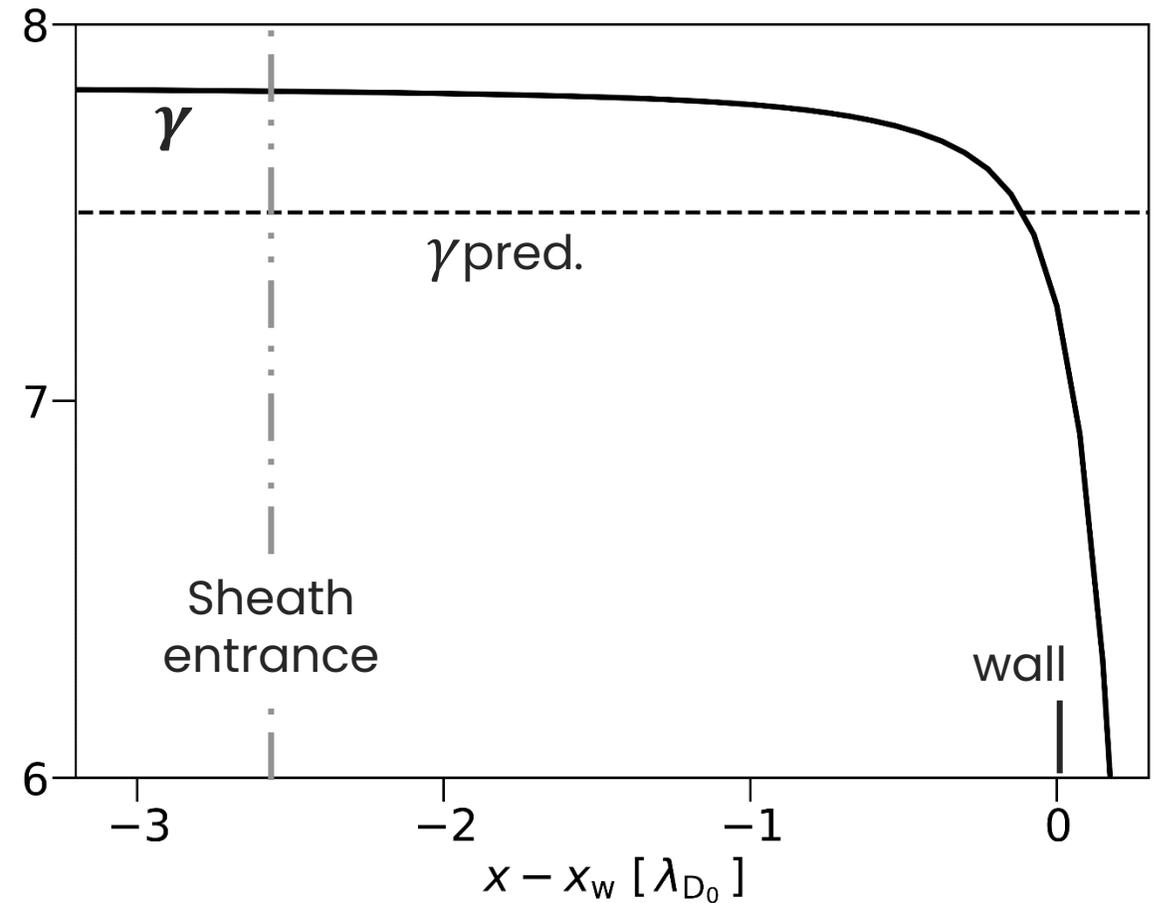
- $\Gamma$  and  $T_e$  measured experimentally (Langmuir probes)

$$Q = \gamma \Gamma T_e$$

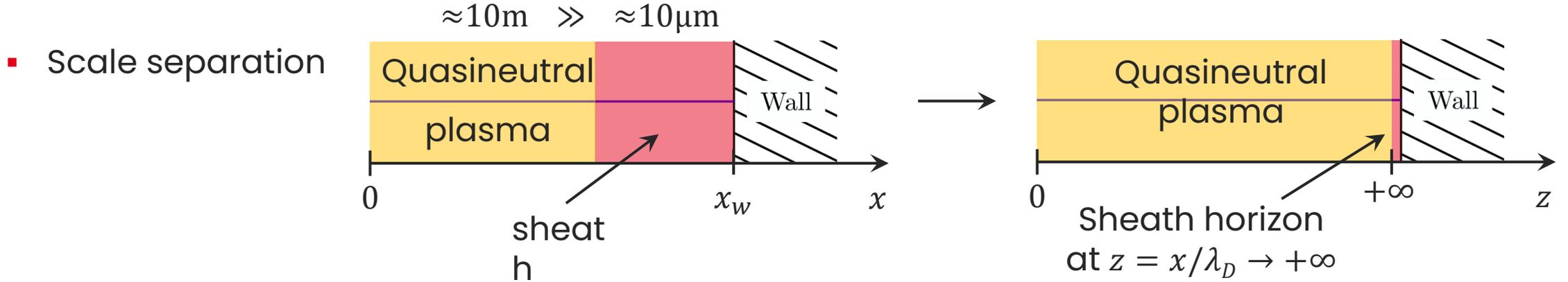
$\gamma$  gives an estimation of deposited power on divertor plates

- Usual value  $\gamma = \gamma_i^{\text{isoth.}} + \gamma_e \approx 7.5$ .
- Good agreement with kinetic code

$$\gamma_{\text{code}} \approx 7.9$$



# Scale separation $\Rightarrow$ supersonic transition at sheath entrance



- Expansion in powers of  $1/z$ 
  - Adiabatic electrons  $n_e = n_\infty e^{\phi - \phi_\infty}$        $\phi_\infty, n_\infty$  : taken at sheath horizon  $z \rightarrow +\infty$
  - Poisson equation  $n_i = n_\infty (1 + F(\phi - \phi_\infty) - \Delta\phi)$ 

$$F(\phi - \phi_\infty) = e^{\phi - \phi_\infty} - 1 = \frac{1}{z^K} A_K^F + \dots \quad K > 0$$

- $\forall z \geq 0 \quad \Pi(z) = \Pi_\infty$       gives  $M_\infty = 1$   
 and  $c_s = \sqrt{3T/m_i}$  : taken at sheath horizon  $z \rightarrow +\infty$
- Supersonic transition at sheath horizon  
Bohm's criterion

# Robust physics with respect to the choice of the penalization term

## 1. Constant coefficients : **conducting wall**

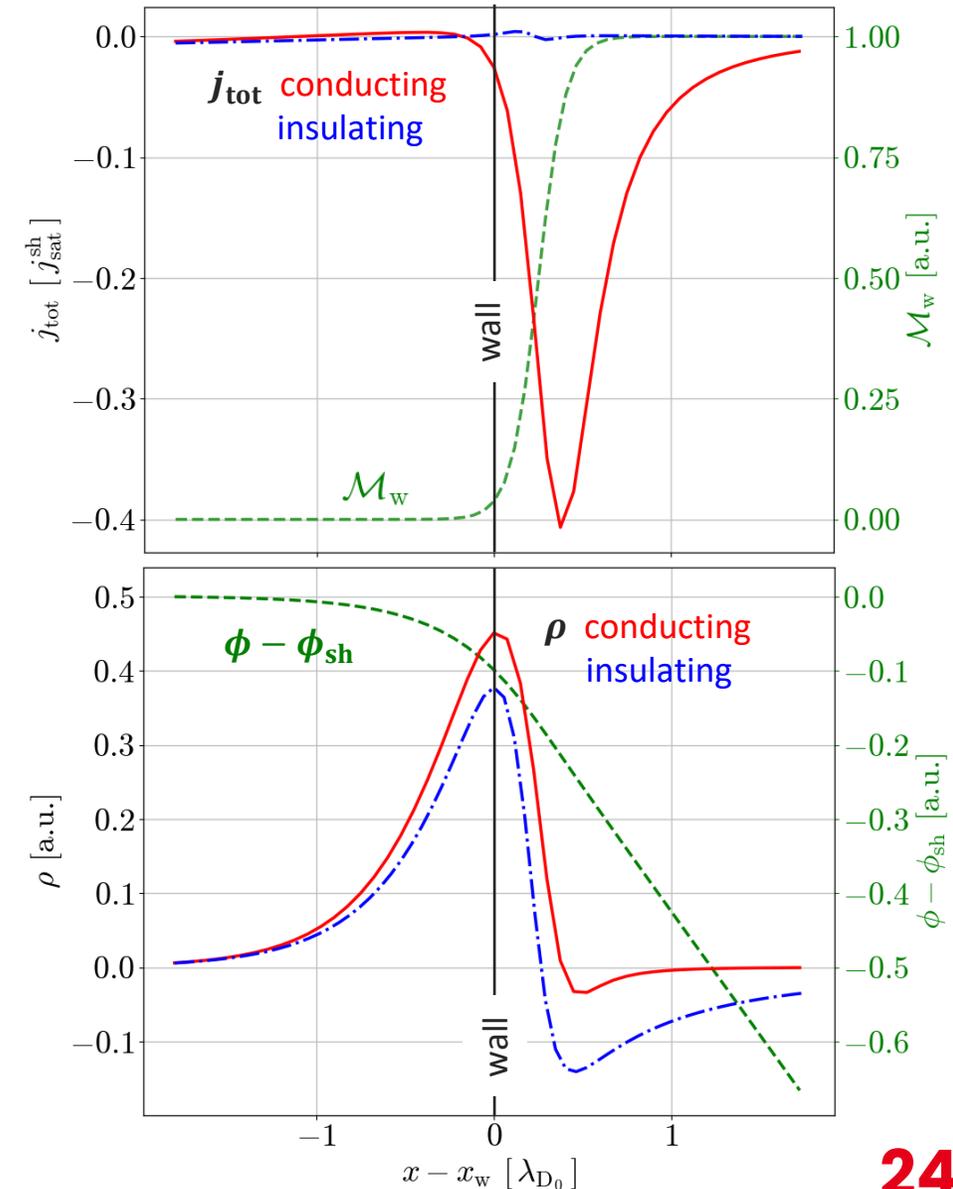
Charge conservation from Boltzmann eq.

$$\underbrace{\partial_t \rho + \partial_x j_{\text{tot}}}_{j_e + j_i} = -\mathcal{M}_w \{v_{iw}(n_i - n_w) - v_{ew}(n_e - n_w)\} \rightarrow \text{currents in wall}$$

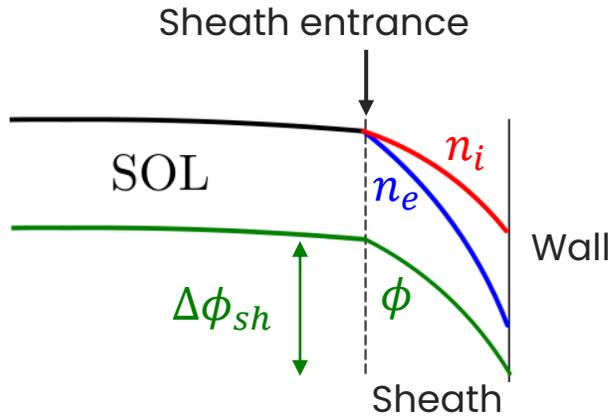
## 2. Adaptive coefficients : **insulating wall**

$$v_{iw} = \text{constant} \quad v_{ew}(x, t) = v_{iw} \frac{n_i - n_w}{n_e - n_w} \rightarrow \text{Rhs. vanishing} \\ \rightarrow \text{no net current in wall}$$

- Robust physics : almost identical potential drop in the sheath in both cases : focus on the conducting case in the following



# Distribution functions at sheath entrance

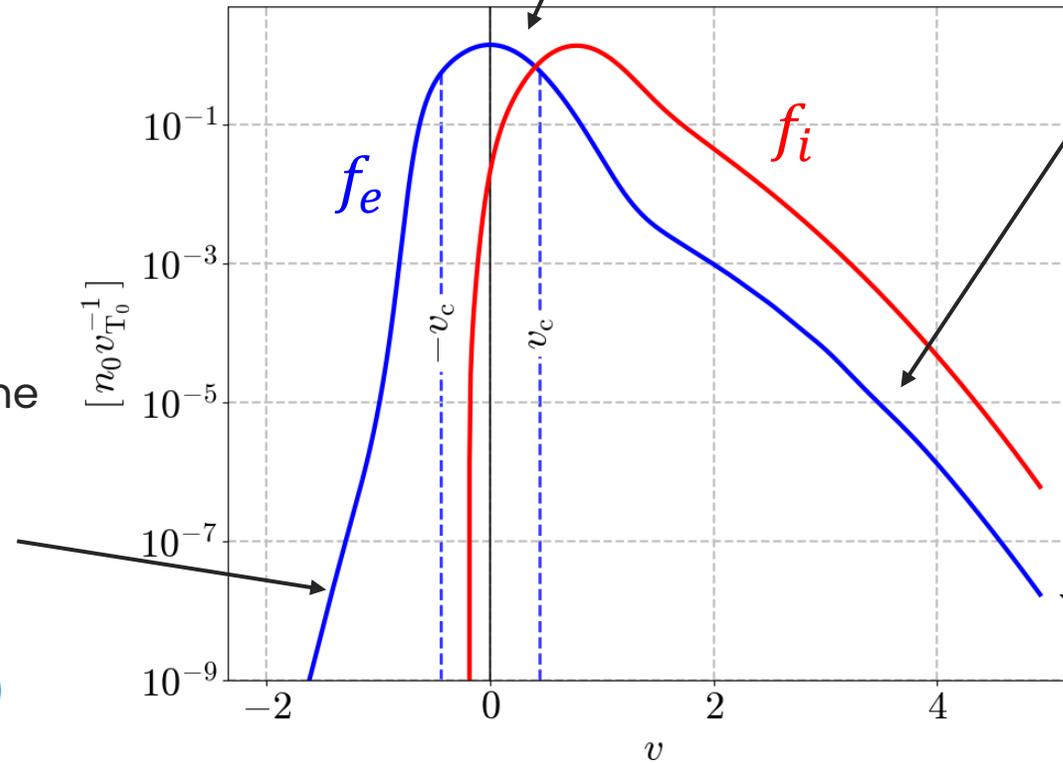


Escaping velocity:

$$v_c = \sqrt{\frac{2e|\Delta\phi_{sh}|}{m_e}}$$

Bulk electrons **reflected** into the plasma

Fast electrons **absorbed** in the wall



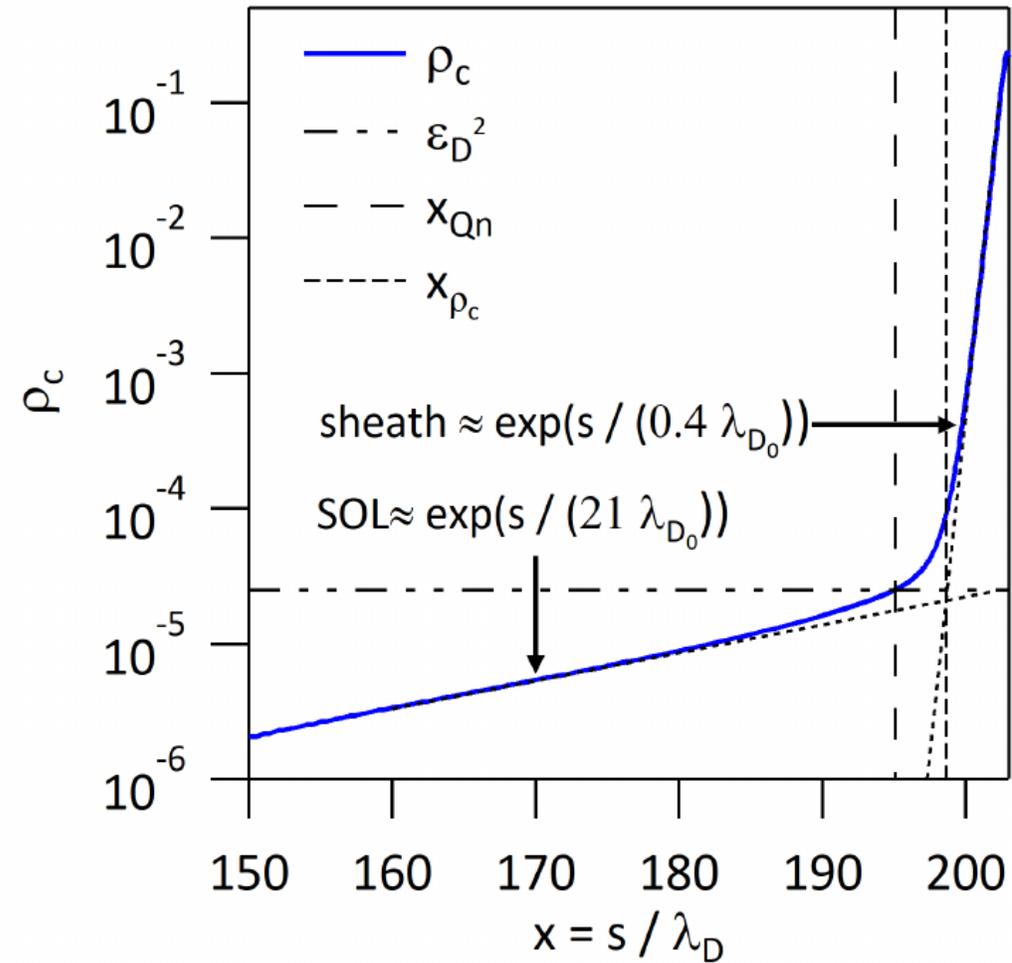
Electron **reemission** from the wall

- finite strength of penalization & collisions

$$sink = -\mathcal{M}_w \nu_{wa} (f_a - g_w)$$

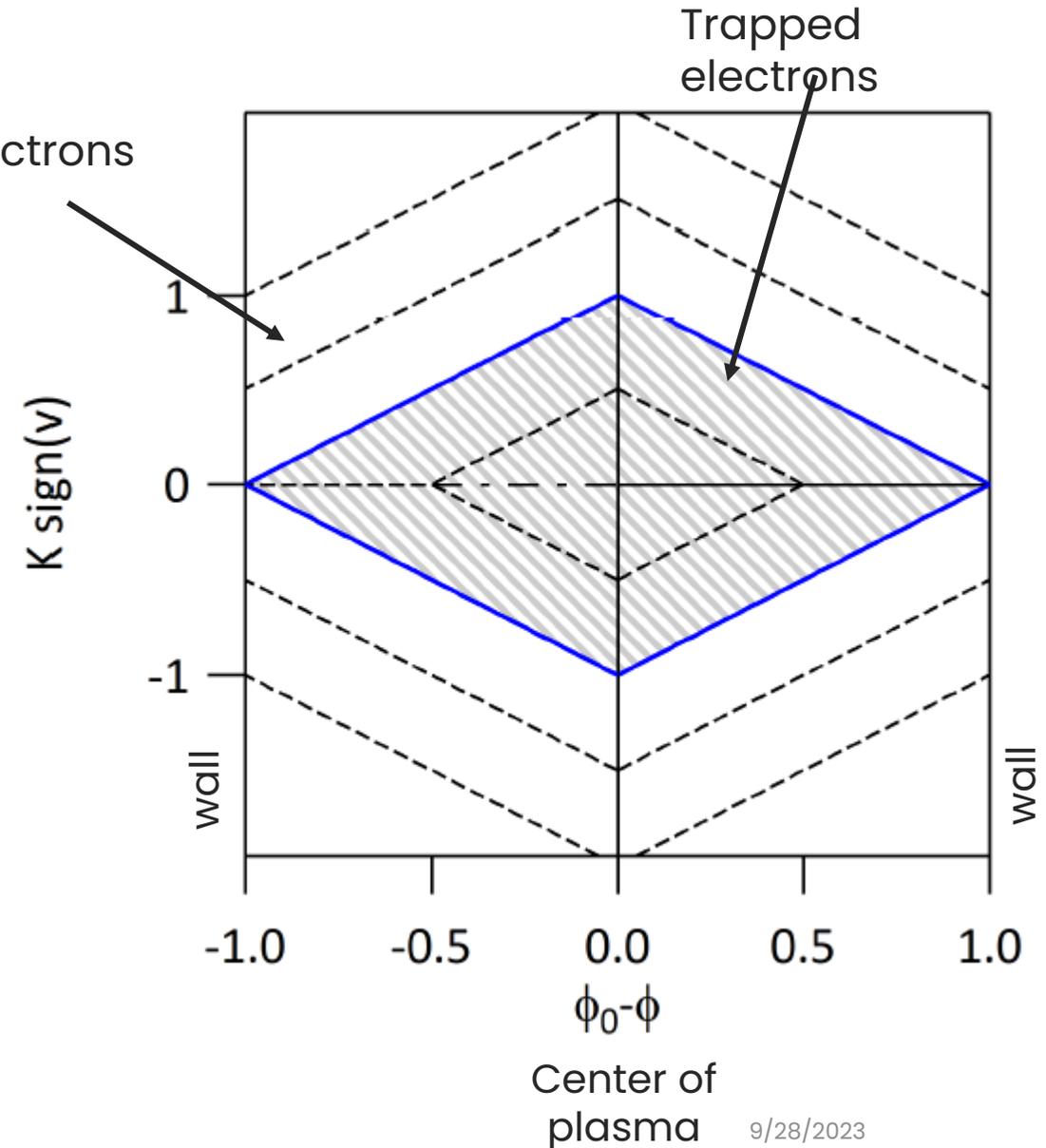
Shape resembles sum of two Maxwellian with different temperatures : collisions vs. injection of particles by the source

# Sheath entrance definition

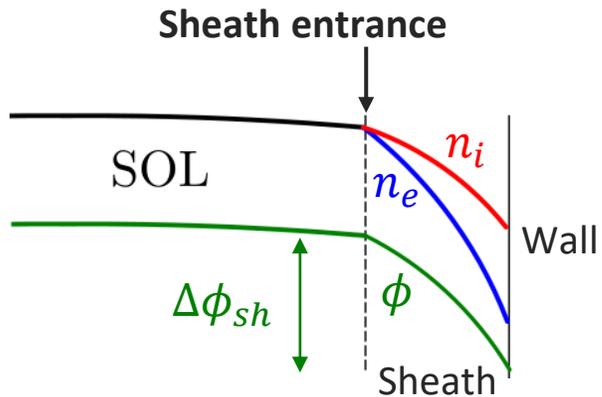


# Collisions = detrapping mechanism trapped and passing

- Phase space characteristics for electrons in the whole plasma
- Particle source fraction injected in passing region : 1% for a typical value of sheath potential drop
- Without collisions trapped particles stay trapped while passing are absorbed in the wall
- Collisions : necessary transfer mechanism between trapped and passing, and necessary condition to reach steady state (the particle source must be compensated by the sink in the wall region)

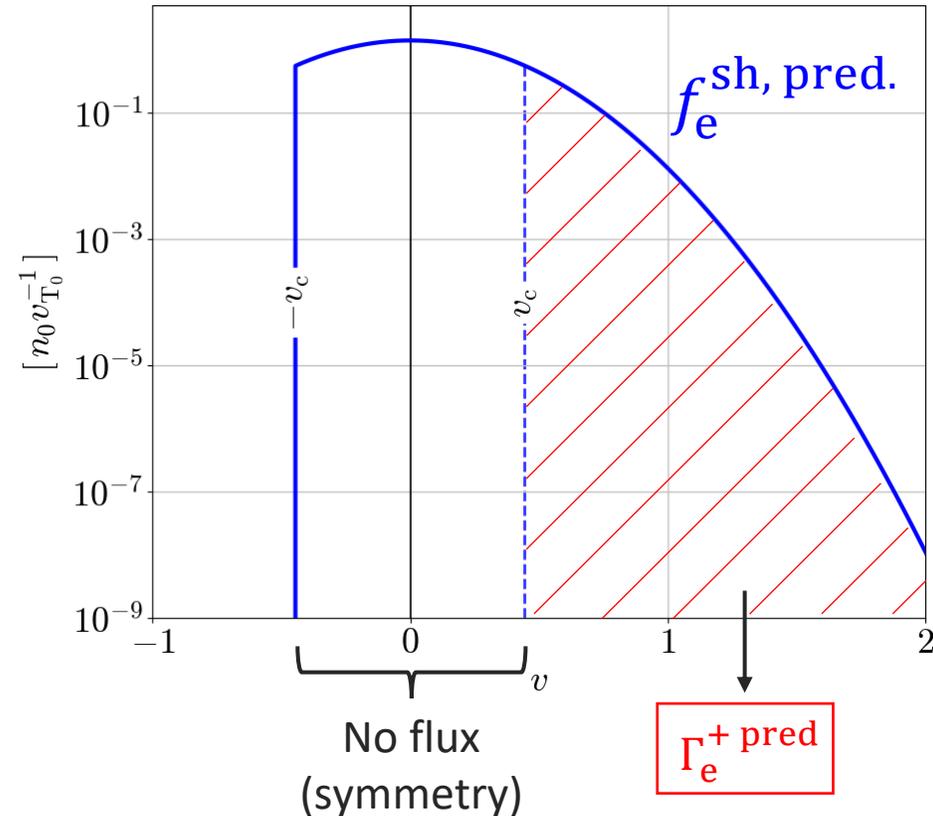


# Using Stangeby's prediction of the sheath potential drop to explain parametric dependencies



Escaping velocity:

$$v_c = \sqrt{\frac{2e|\Delta\phi_{sh}|}{m_e}}$$



Potential drop prediction [Stangeby]

$$\Delta\phi_{sh}^{pred.} = \frac{T_e^{sh}}{e} \log \left( \sqrt{2\pi \frac{m_e}{m_i} M^2 \left( 1 + \frac{T_i^{sh}}{T_e^{sh}} \right)} \right)$$

-> Comes from  $\Gamma_i^{sh} = \Gamma_e^+ pred$

$$\Gamma_e^+ pred = \int_{v_c}^{+\infty} dv v f_e^{sh, pred.}$$

With  $f_e^{sh, pred.}$  truncated Maxwellian of temperature  $T_e^{sh}$

# Correction terms for the potential drop prediction

Potential drop prediction [Stangeby]

$$\Delta\phi_{sh}^{pred.} = \frac{T_e^{sh}}{e} \log \left( \sqrt{2\pi \frac{m_e}{m_i} M^2 \left( 1 + \frac{T_i^{sh}}{T_e^{sh}} \right)} \right)$$

**Correction term 1:**

- electron reemission from the wall due to finite penalization strength

$$\Gamma_i^{sh} = \Gamma_e^+ + \boxed{\Gamma_e^-} \leq \Gamma_e^+ \quad \boxed{\Gamma_e^-} = \int_{-\infty}^{-v_c} dv v f_e^{sh}$$

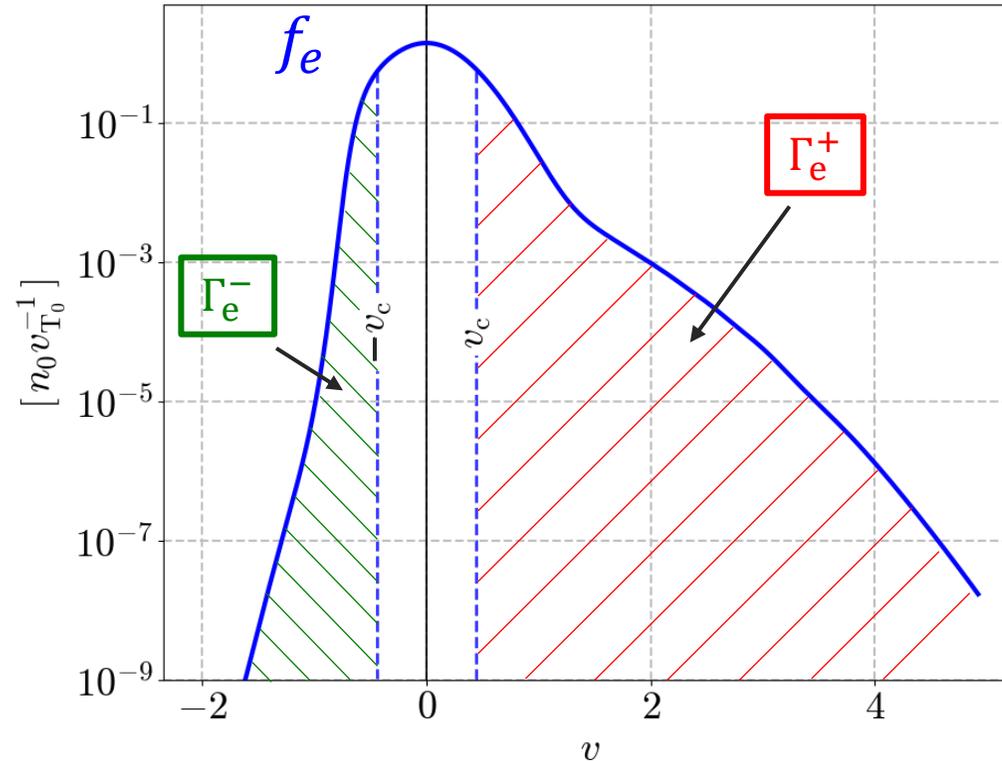
**Correction term 2:**

- Effective temperature to match forward flux to predicted Maxwellian flux

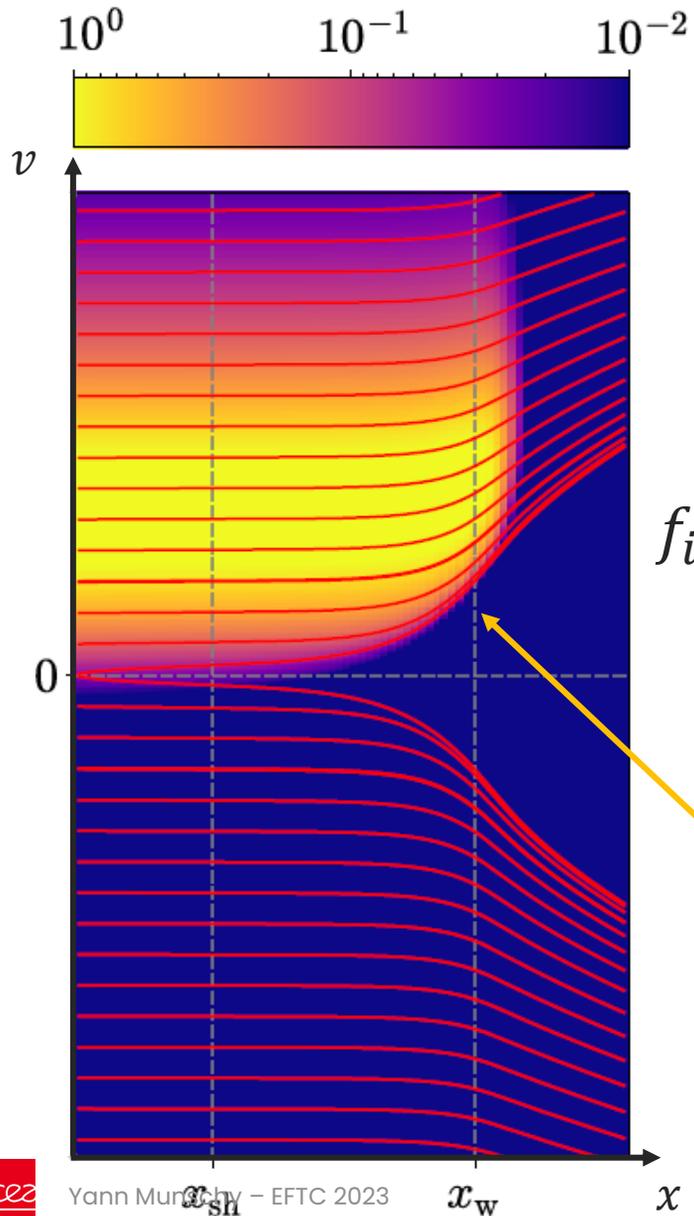
$$\Gamma_e^{+ pred} = \int_{v_c}^{+\infty} dv v \maxw. (T_e^{sh}) \neq \boxed{\Gamma_e^+} \longrightarrow \int_{v_c}^{+\infty} dv v \maxw. (\tilde{T}_e^{sh}) = \boxed{\Gamma_e^+}$$

**Corrected potential drop prediction**

$$\Delta\phi_{sh}^{pred.} = \frac{\tilde{T}_e^{sh}}{e} \log \left( \sqrt{2\pi \frac{m_e}{m_i} M^2 \left( 1 + \frac{T_i^{sh}}{\tilde{T}_e^{sh}} \right) \left( 1 + \frac{\boxed{\Gamma_e^-}}{\Gamma_i^{sh}} \right)} \right)$$



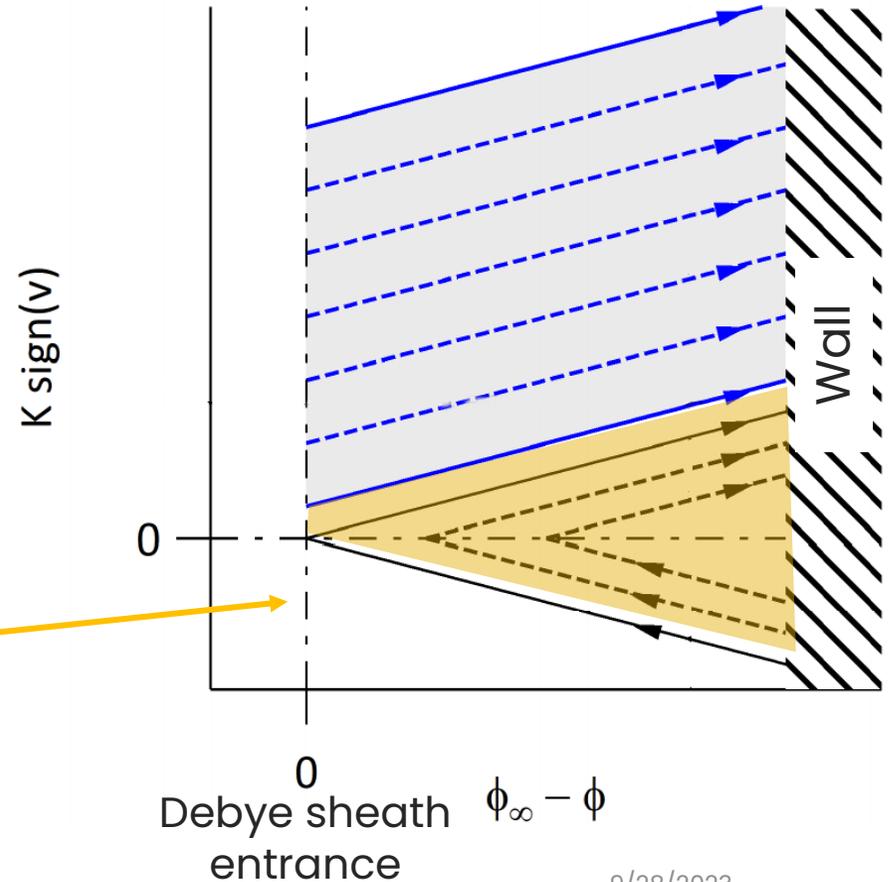
# Ions trajectories in phase space: acceleration & gap



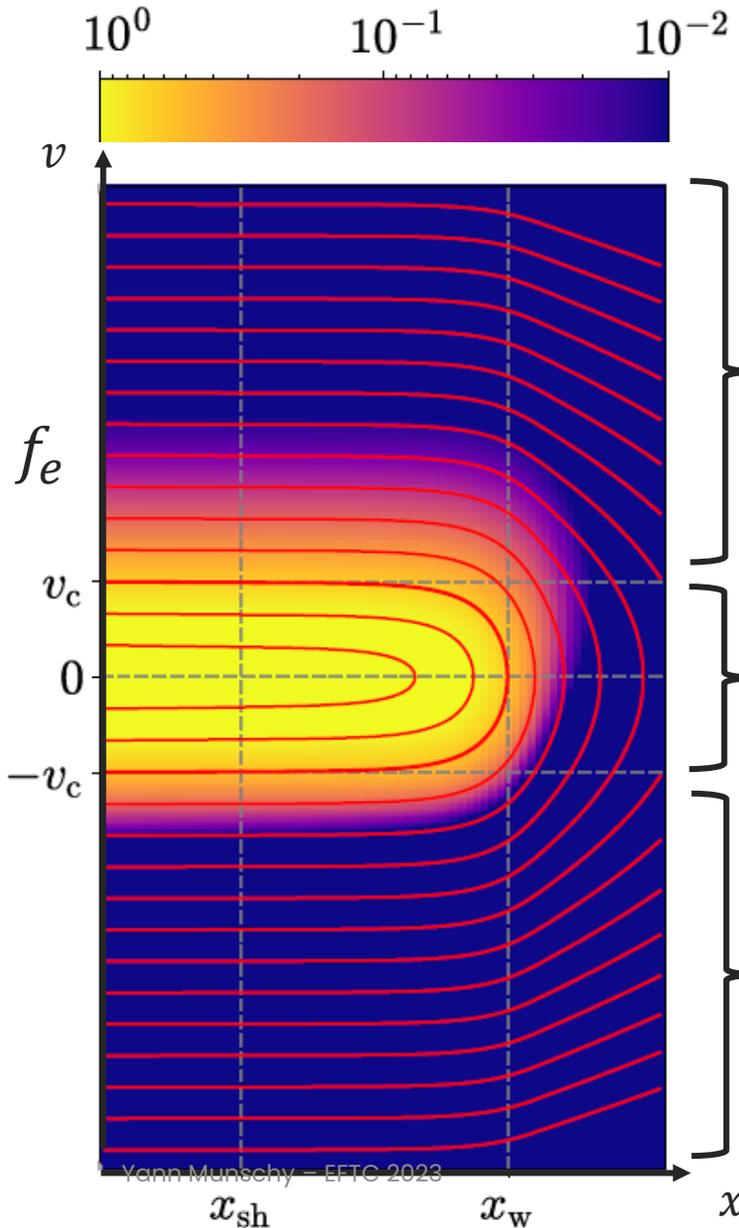
- kinetic energy  $K = H_a - e_a \phi$
- No collisions  $\rightarrow$  Hamiltonian invariant

Acceleration creates gap

(Filled by collisions in 1D, Electric field as well in higher dimensions)



# Fast electrons overcome the sheath potential barrier

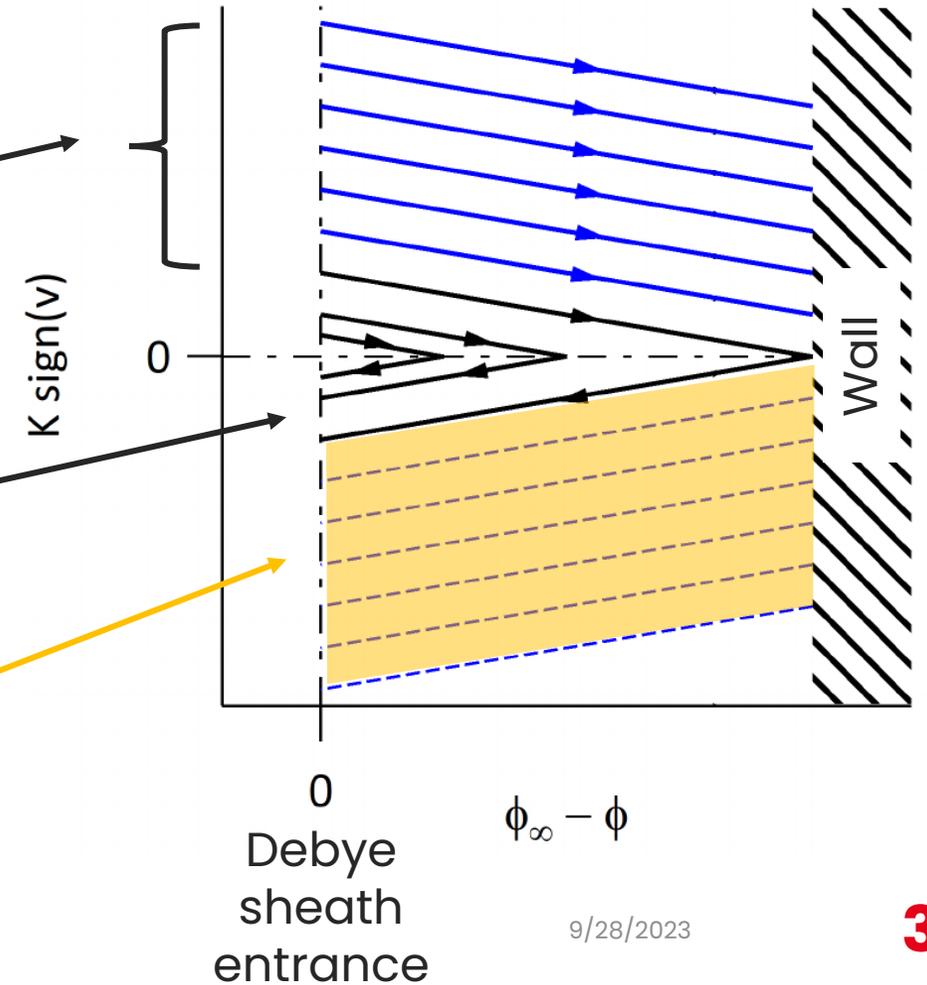


- kinetic energy  $K = H_a + e_a \phi$
- No collisions  $\rightarrow$  Hamiltonian invariant

fast electrons  
(absorbed in wall)

Trapped electrons  
(reflected in the plasma)

Empty phase space region



# Ion-to-electron mass ratio dependency recovered

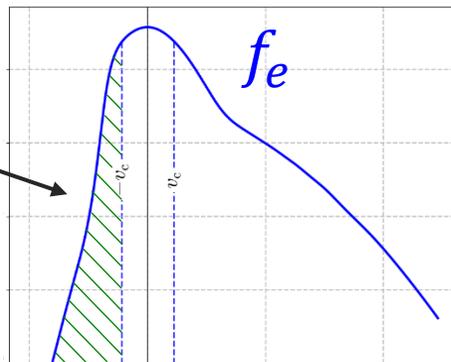
$$\Delta\phi_{sh}^{\text{pred.}} = \frac{T_e^{\text{sh}}}{e} \log \left( \underbrace{\sqrt{2\pi M^2 \left(1 + \frac{T_i^{\text{sh}}}{T_e^{\text{sh}}}\right) \left(1 + \frac{\Gamma_e^-}{\Gamma_i^{\text{sh}}}\right)}_{\Theta} \times \sqrt{\frac{m_e}{m_i}} \right)$$

$$\Delta\bar{\phi}_{sh}^{\text{pred.}} = \frac{e\Delta\phi_{sh}^{\text{pred.}}}{T_e^{\text{sh}}} - \log(\Theta) = \frac{1}{2} \log\left(\frac{m_e}{m_i}\right)$$

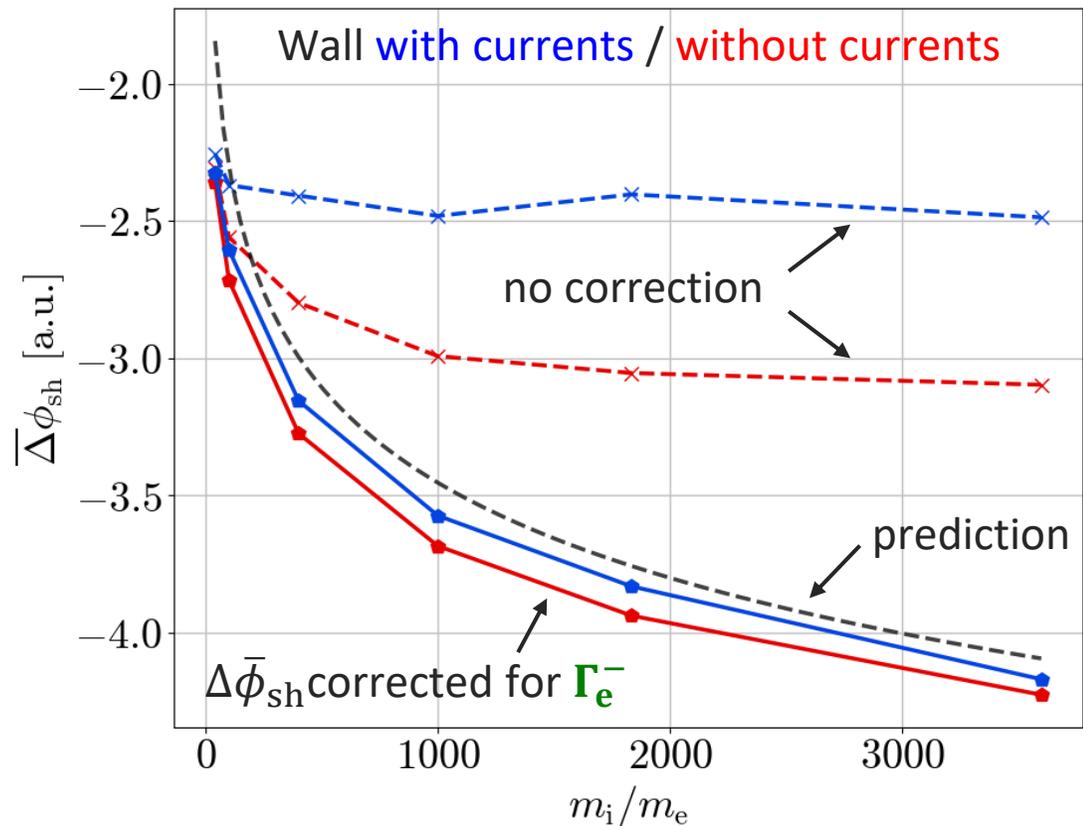
Relation  $\Delta\bar{\phi}_{sh} \propto \log\left(\frac{m_e}{m_i}\right)$  verified

- Electron reemission from the wall explains the difference observed between theory and simulation

$$\Gamma_e^- = \int_{-\infty}^{-v_c} dv v f_e^{\text{sh}}(v)$$



- Electron reemission : finite steepness of penalization mask & absorption of electrons in wall not perfect

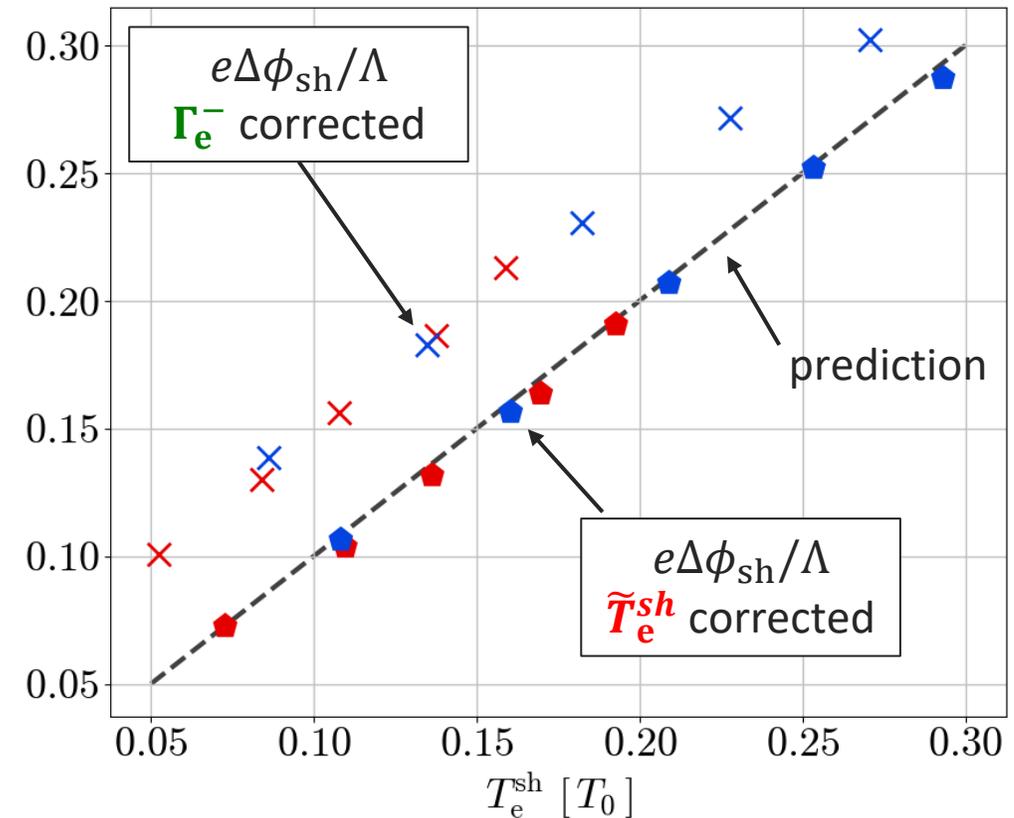
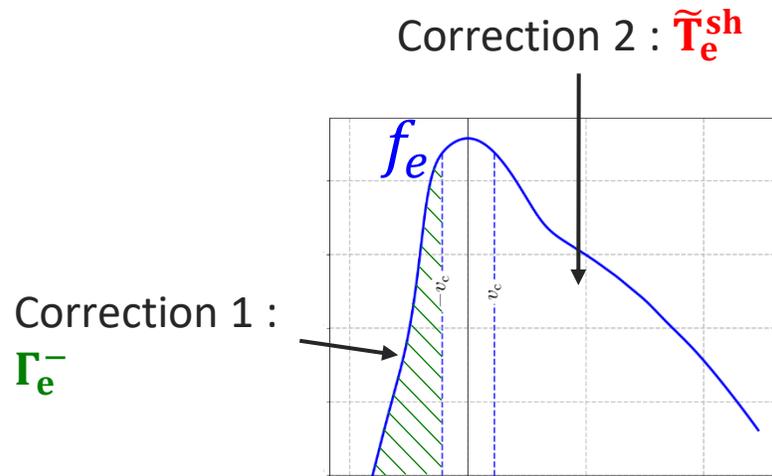


# Electron temperature dependency $\Delta\phi_{sh} \propto T_e^{sh}$ recovered

$$\Delta\phi_{sh}^{pred.} = \frac{T_e^{sh}}{e} \log \left( \underbrace{\sqrt{2\pi \frac{m_e}{m_i} M^2 \left(1 + \frac{T_i^{sh}}{T_e^{sh}}\right) \left(1 + \frac{\Gamma_e^-}{\Gamma_i^{sh}}\right)}}_{\Lambda} \right) \longrightarrow \boxed{\frac{e\Delta\phi_{sh}^{pred.}}{\Lambda} = T_e^{sh}}$$

## Linear relation $\Delta\phi_{sh} \propto T_e^{sh}$ recovered

- The faster the electrons, the greater the potential drop



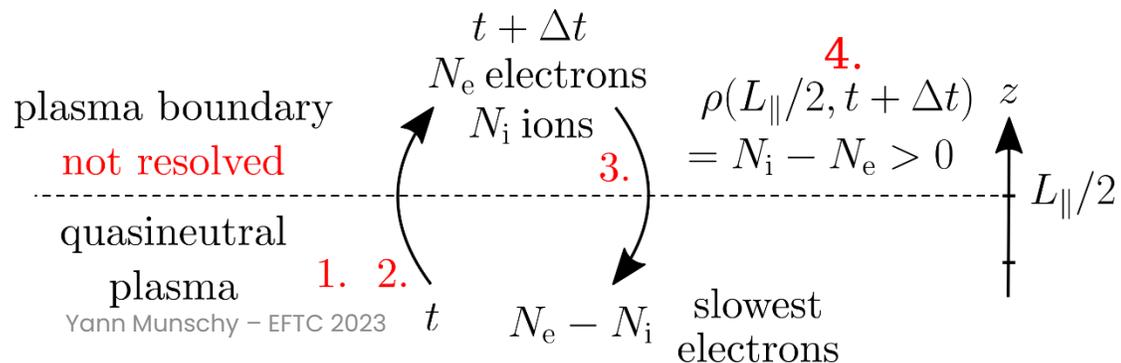
# Existing solution for including sheath physics in GK codes

## ➤ Logical sheath

- At a point of the simulation / plasma boundary
- Count the number of ions going out of the plasma
- Absorb an equal number of the fastest electrons
- Reflect the other electrons back into the plasma

- Equality of ion and electron fluxes at plasma boundary
- Equality of fluxes defines the electron threshold velocity

$$\int_0^\infty dv v f_i(x, y, L_{\parallel}/2, v, \mu) = \int_{v_c}^\infty dv v f_e(x, y, L_{\parallel}/2, v, \mu).$$



## ➤ Conducting sheath

- define electron threshold velocity is defined with the electric potential

$$\frac{1}{2} m_e v_c^2 = e \phi_{boundary}$$

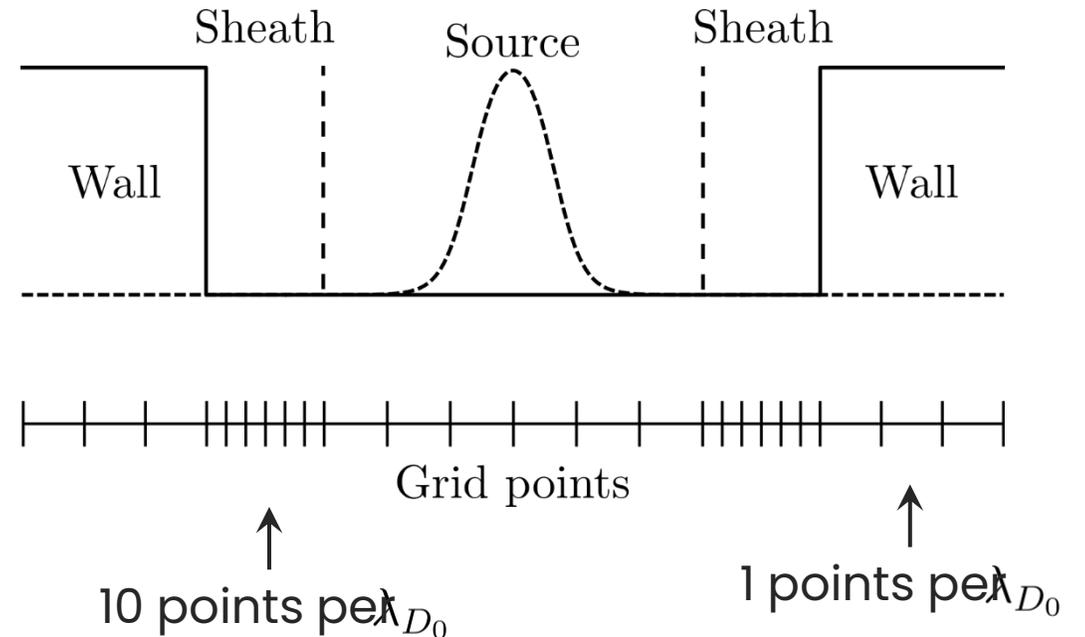
- Absorb all outgoing ions, and electrons faster than  $v_c$
- No direct constraint on electron and ion fluxes
- Idea : the potential at plasma boundary reacts to the current

# 1D1V code parallelized on GPU with non equidistant grid points to mesh Debye length

- Backward semi Lagrangian scheme for Boltzmann eq.

[Bourne2022]

- Cubic spline interpolation on **non equidistant mesh**
  - Test bench for C++ version of GYSELA (5D gyrokinetic code)
- GPU parallelization
- 1 simulation: ~20h on NVIDIA Tesla V100 (5120 CUDA cores)



# Collisions

$$\text{Intra species: } C_{aa}(f_a) = \partial_{v_a} \left[ D_v f_{Ma} \partial_{v_a} \left( \frac{f_a}{f_{Ma}} \right) \right] ; f_{Ma} = \frac{n_a}{\sqrt{2\pi T_{Ma}}} \exp \left\{ \frac{1}{2T_{Ma}} (v_a - u_{Ma})^2 \right\}$$

[Dif-Pradalier2011]

$$\text{Conservation of density: } \int dv C_{aa}(f_a) = 0$$

$$\left. \begin{aligned} \text{Conservation of momentum: } \int dv v_a C_{aa}(f_a) &= 0 \\ \text{Conservation of energy: } \int dv v_a^2 C_{aa}(f_a) &= 0 \end{aligned} \right\} \text{ Gives } T_{Ma}(x, t) \text{ and } u_{Ma}(x, t)$$

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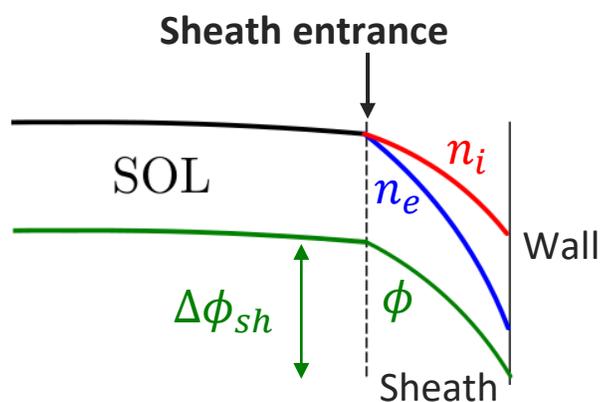
$$\text{Inter species: } C_{ab}(f_a) = \frac{2Q_{ab}^M}{n_a T_a} \left[ \frac{m_a}{2T_a} (v_a - V_a)^2 - \frac{1}{2} \right] F_{Ma} + \frac{R_{ab}^M}{n_a T_a} (v_a - V_a) F_{Ma}$$

[Esteve2015]

$$R_{ab}^M = -n_a v_{ab} \left( u_a - \sqrt{\frac{A_b}{A_a}} u_b \right) \text{ friction force (momentum transfer)}$$

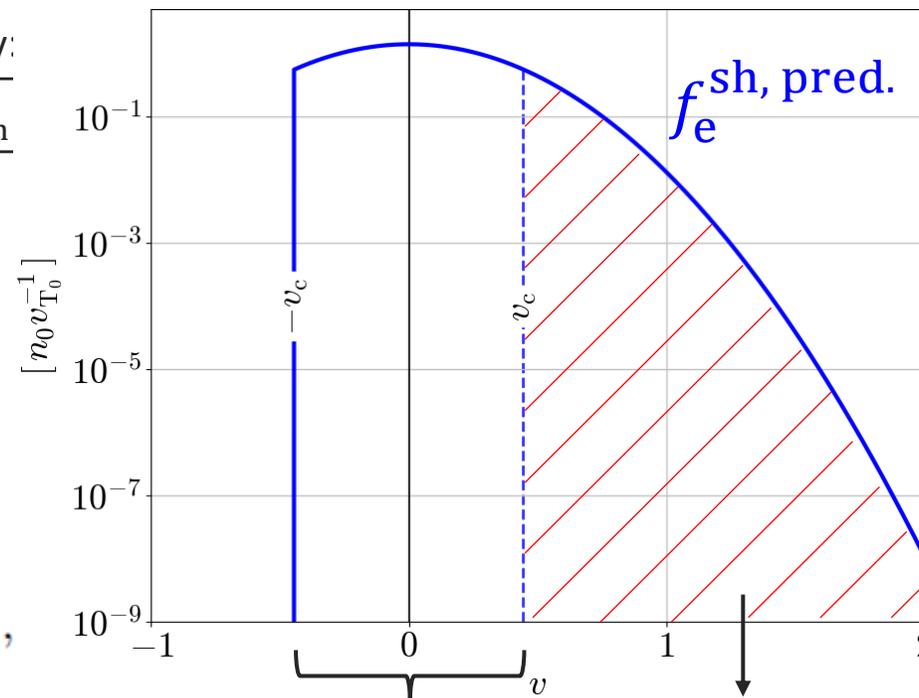
$$Q_{ab}^M = -3n_a \frac{A_b}{A_b + A_a} v_{ab} (T_a - T_b) - u_a R_{ab}^M \text{ energy transfer}$$

# Prediction for potential drop in the sheath region



Escaping velocity:

$$v_c = \sqrt{\frac{2e|\Delta\phi_{sh}}{m_e}}$$



$$\Gamma_i^{sh} = n_i^{sh} M c_s.$$

$$f_e(x_{sh}, v) = \bar{n}_e \sqrt{\frac{m_e}{2\pi T_e^{sh}}} e^{-\frac{m_e v^2}{2T_e^{sh}}} \mathbb{1}_{v \geq -v_c(v)},$$

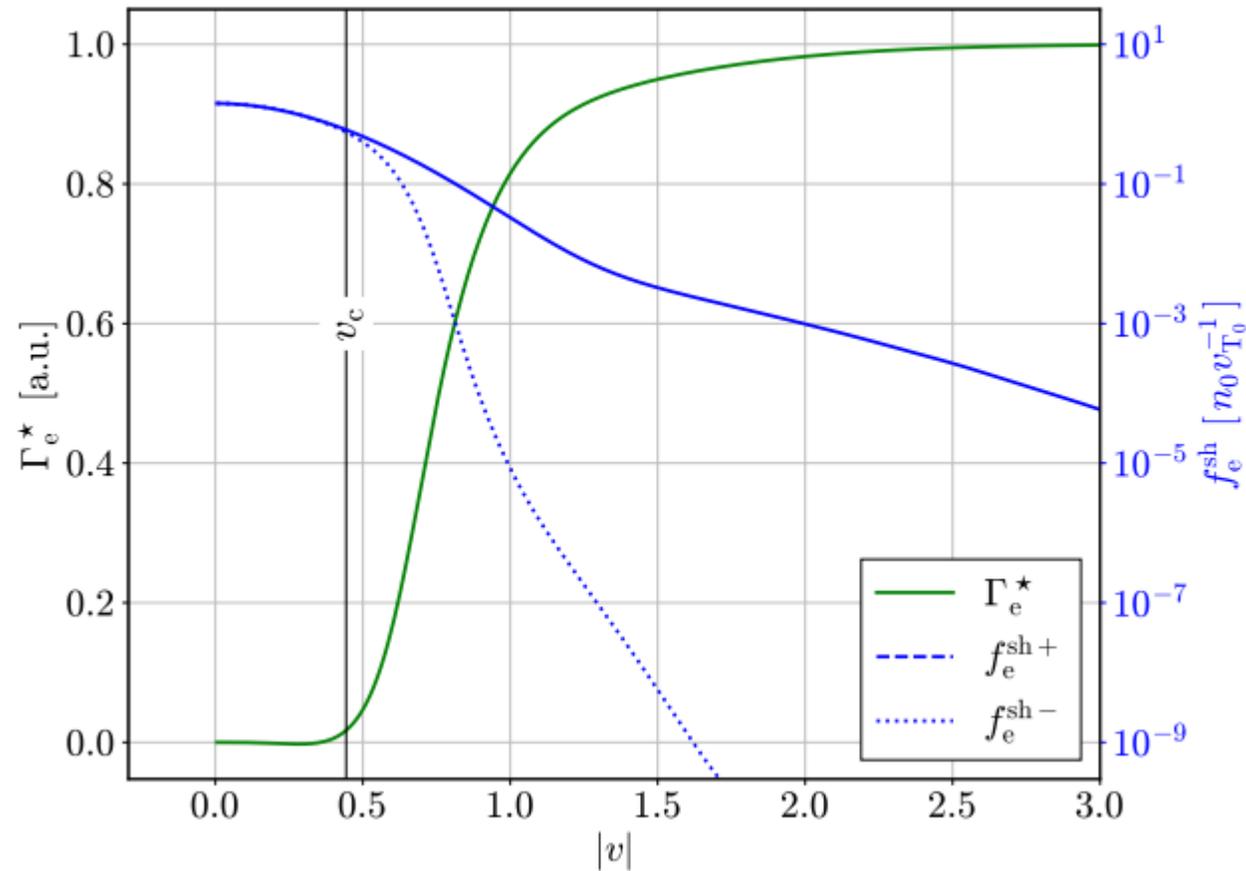
$$\begin{aligned} \Gamma_e^{sh} &= \int_{-v_c}^{+\infty} dv v n_e^{sh} \sqrt{\frac{m_e}{2\pi T_e^{sh}}} e^{-\frac{m_e v^2}{2T_e^{sh}}} \\ &= n_e^{sh} e \frac{e\Delta\phi_{sh}}{T_e^{sh}} \sqrt{\frac{T_e^{sh}}{2\pi m_e}}. \end{aligned}$$

$$v(x_w)^2 = v(x_{sh})^2 + \frac{2e\Delta\phi_{sh}}{m_e}.$$

No flux  
(symmetry)

$\Gamma_e^+$  pred

# Breakdown of electron flux at sheath entrance

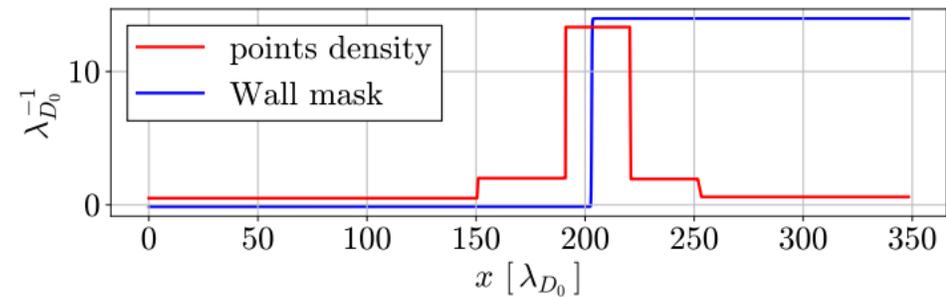


$$\Gamma_e^*(v) = \frac{1}{\Gamma_e^{\text{sh}}} \int_{-v}^v dv' v' f_e^{\text{sh}}(v'),$$

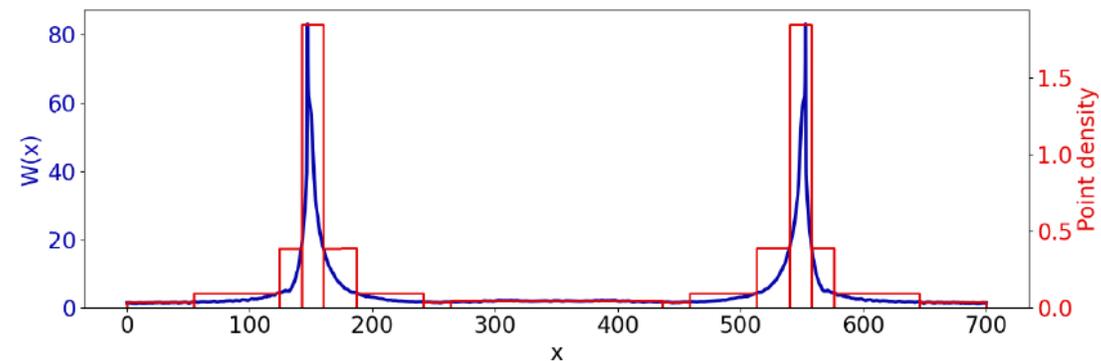
# Numerical parameters for reference simulation

TABLE I. Reference simulation parameters.

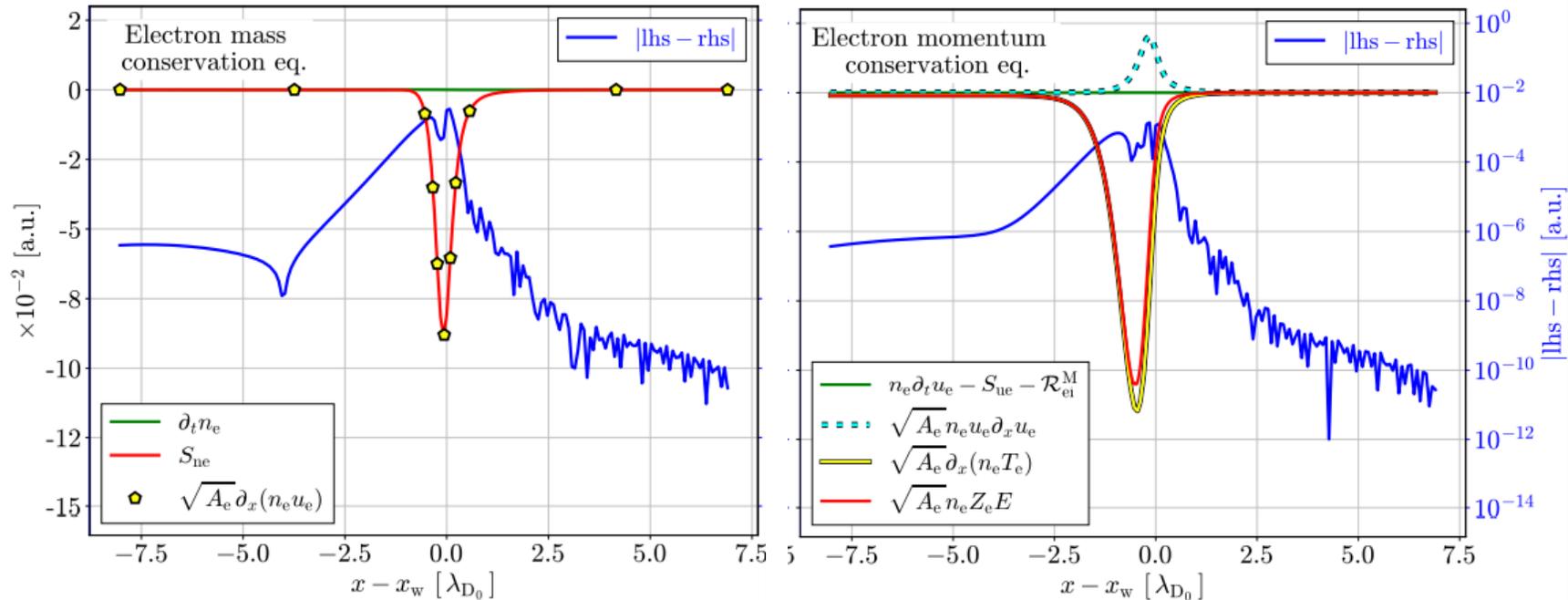
$L_x$	$L_{\parallel}$	$d_w$	$n_w$	$\nu_0^*$
700	406	0.2	$10^{-9}$	0.1



[Bourne 2022]



# Code verification : fluid conservation equations



$$\partial_t n_a + \sqrt{A_a} \partial_x (n_a u_a) = S_{na}, \quad (B1)$$

$$\begin{aligned} n_a (\partial_t u_a + \sqrt{A_a} u_a \partial_x u_a) + \sqrt{A_a} \partial_x (n_a T_a) \\ = n_a Z_a E + S_{ua} + \mathcal{R}_{ab}^M, \end{aligned} \quad (B2)$$

$$\begin{aligned} \partial_t (n_a T_a) + \sqrt{A_a} u_a \partial_x (n_a T_a) \\ + \sqrt{A_a} (\partial_x Q_a + 3n_a T_a \partial_x u_a) \\ = S_{ha} + 2Q_{ab}^M, \end{aligned} \quad (B3)$$

# Effect of collisions on the distribution function shape

