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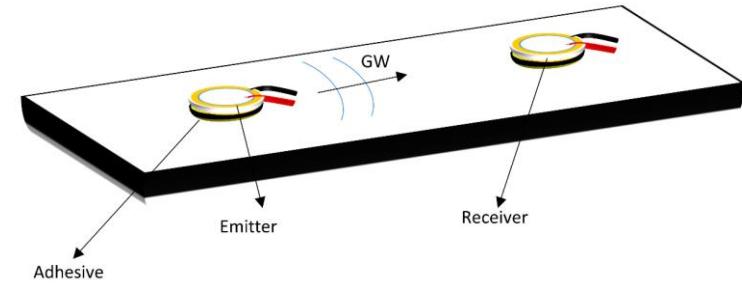
An Improved Sensor Model for Efficient Guided Wave Based Structural Health Monitoring Simulation

Sanjay SHARMA, Olivier MESNIL, Arnaud RECOQUILLAY and Bastien CHAPUIS

University Paris-Saclay, CEA, List, F-91120; Palaiseau; France

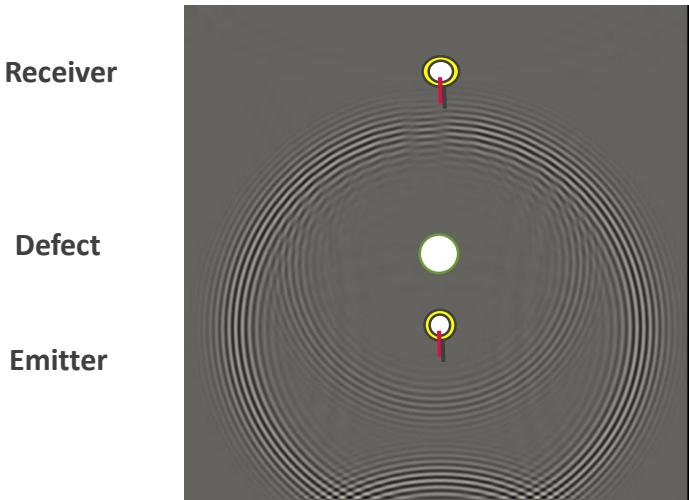
Guide Wave-SHM:

- Permanently installed sensors on the structure to monitor structural health.
- Towards condition-based maintenance.
- Long range propagation
- Applications : Aerospace, Oil&Gas, Nuclear



Challenges:

- Extensive research has been done but still not undertaken by the industry, especially in **Aerospace**.
- Multimode and sensitive to operational conditions.
- Difficult to describe the damage signature.
- Need of performance demonstration similar to **NDT Probability of Detection (POD)**.



Performance demonstration:

- Need lots of **repeated experiments for POD computation**.
- Correct interpretation of damage in the signals.

Objective :

- To construct a general methodology and framework to demonstrate the performance of GW-SHM such as NDT via simulations.

Simulation tools for GW-SHM

- Mesnil, O. et al, *ASME J Nondestructive Evaluation* “Experimental Validation of Transient Spectral Finite Element Simulation Tools Dedicated to Guided Wave-Based Structural Health Monitoring” **2021**

Objective of this presentation :

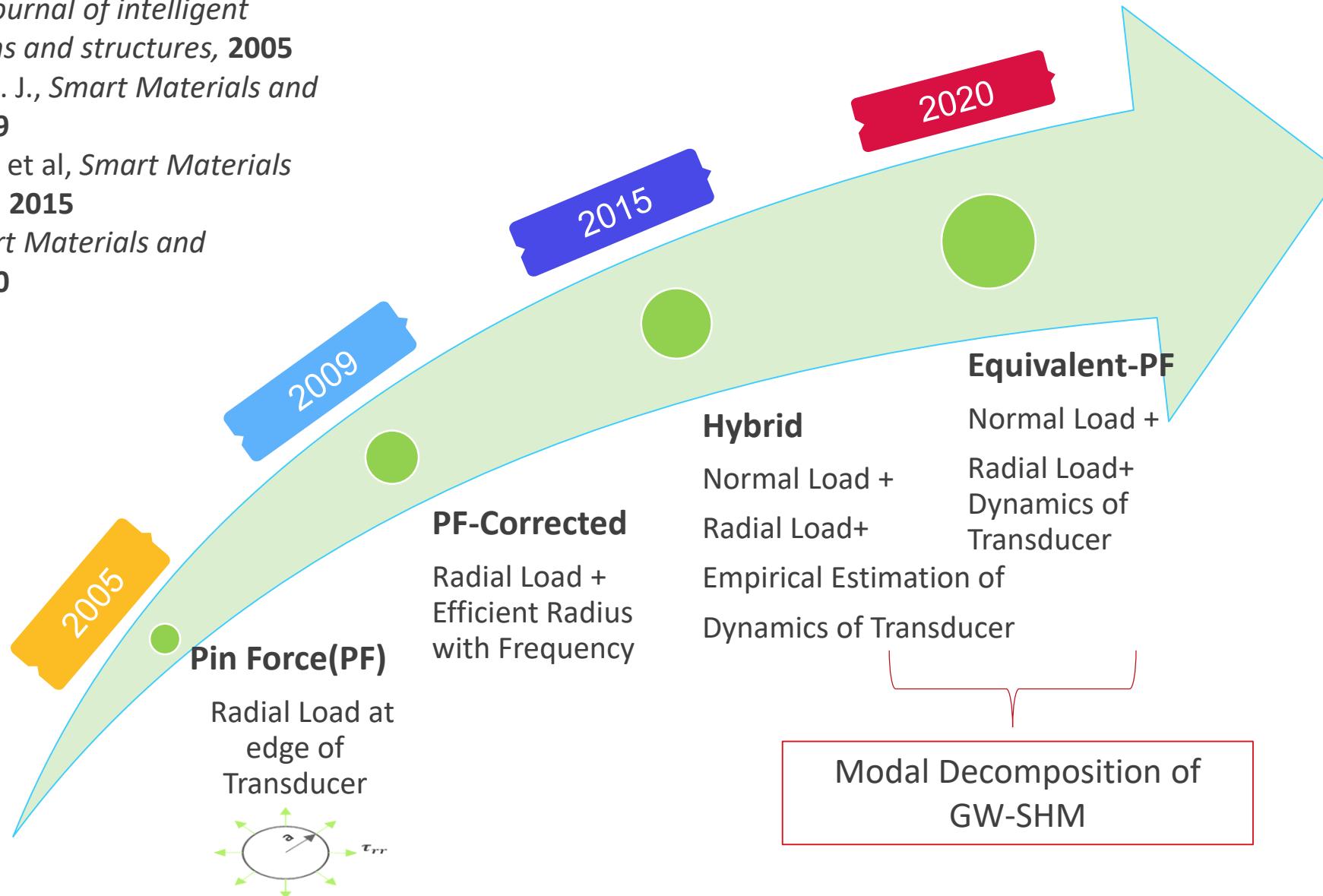
- To improve the transducer model for higher frequency range.

OUTLINE

- State of Art
- Theoretical Formulation
- Validation
- Discussion & Conclusion

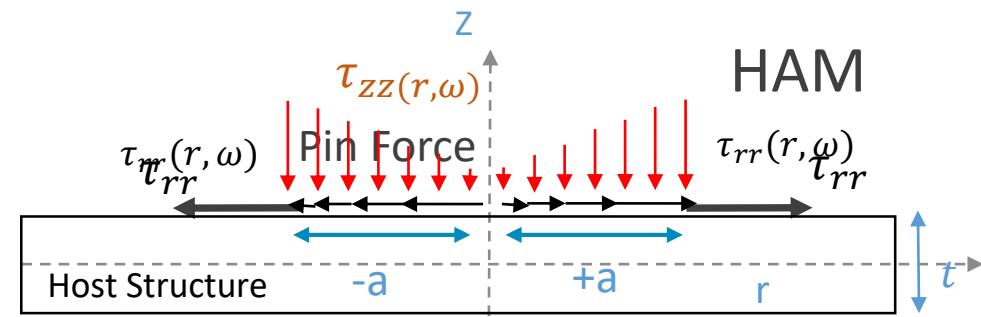
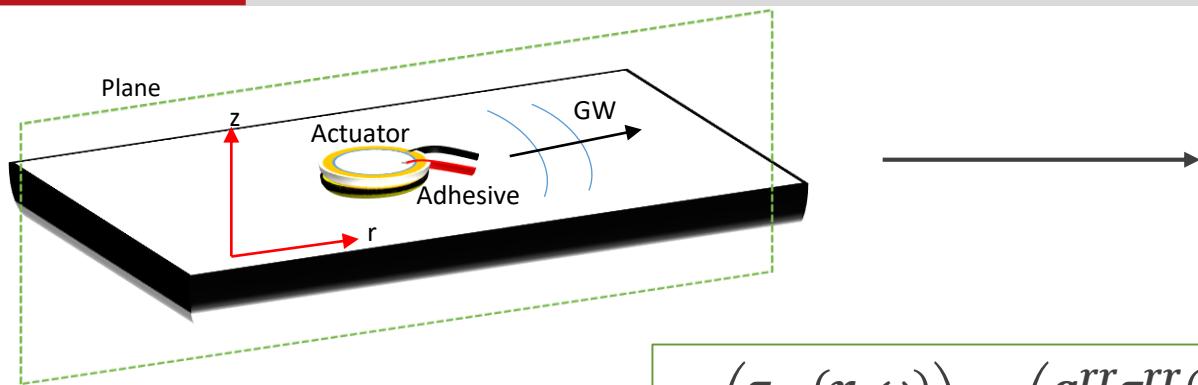
Models for circular transducer for SHM

1. Giurgiutiu, V., *Journal of intelligent material systems and structures*, 2005
2. Sohn, H. et al, S. J., *Smart Materials and Structures*, 2009
3. Quaegebeur, N. et al, *Smart Materials and Structures*, 2015
4. Li, J. et al , *Smart Materials and Structures*, 2020



OUTLINE

- Literature Review
- Theoretical Formulation
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- Discussion & Conclusion



Excitation Functions:

$$\begin{pmatrix} \tau_{rr}(r, \omega) \\ \tau_{zz}(r, \omega) \end{pmatrix} = \begin{pmatrix} a_e^{rr} \tau^{rr}(\omega) \delta(r - a_e^{rr}) \\ a_e^{zz} \tau^{zz}(\omega) \delta(r - a_e^{zz}) \end{pmatrix}$$

Dynamics of Transducer:

$$\begin{pmatrix} \tau^{rr}(\omega) \\ \tau^{zz}(\omega) \end{pmatrix} = \frac{1}{a_e^2} \begin{pmatrix} \int_0^a \tau_{rr}(r, \omega) r dr \\ \int_0^a \tau_{zz}(r, \omega) r dr \end{pmatrix}$$

Estimation of a_e :

$$a_e = \left| \frac{Y_{bondedPiezo}(\omega)}{Y_{freePiezo}(\omega)} \right| a$$

Sohn, H. & Lee, S. J.
Lamb wave tuning curve calibration for surface-bonded piezoelectric transducers
Smart Materials and Structures, IOP Publishing, 2009, 19, 015007

Where :

a = radius of PZT transducer

a_e^{rr}, a_e^{zz} = effective point excitation for the r direction load and z direction load

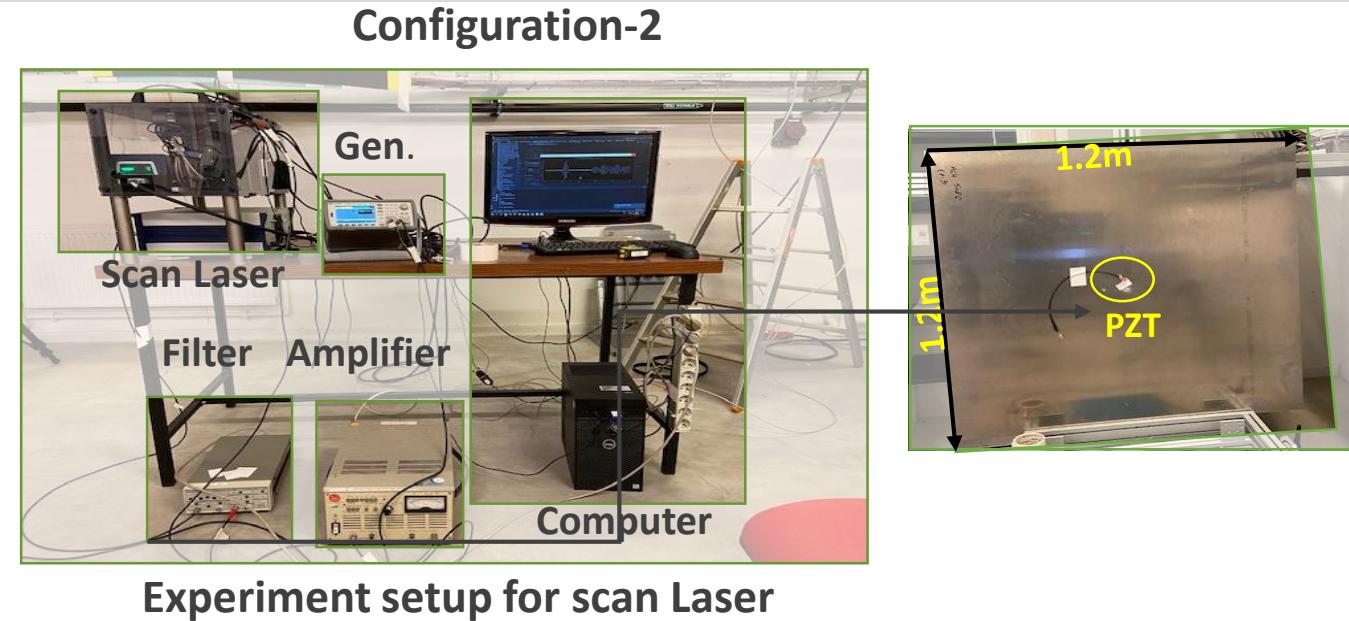
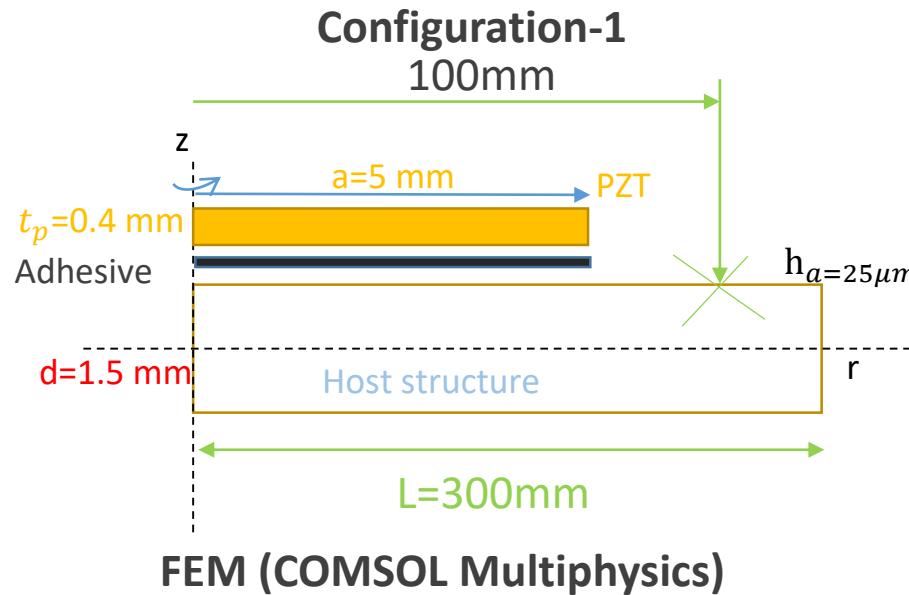
$\tau^{rr}(\omega), \tau^{zz}(\omega)$ = Frequency dependent term for r direction and z direction

$Y_{freePiezo}(\omega)$ = admittance of free Piezo, $Y_{bondedPiezo}(\omega)$ = admittance of bonded piezo

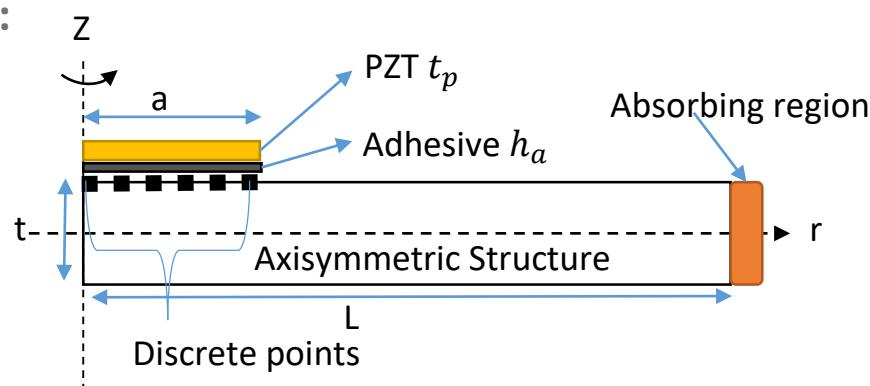
OUTLINE

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Configurations for Validation



Computation of $\tau_{rr}(r, \omega)$ and $\tau_{zz}(r, \omega)$:

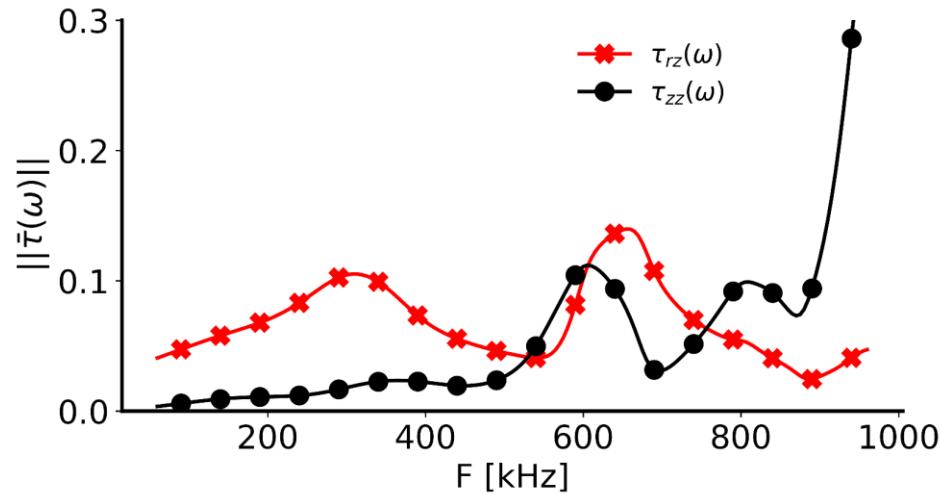


Analysis:

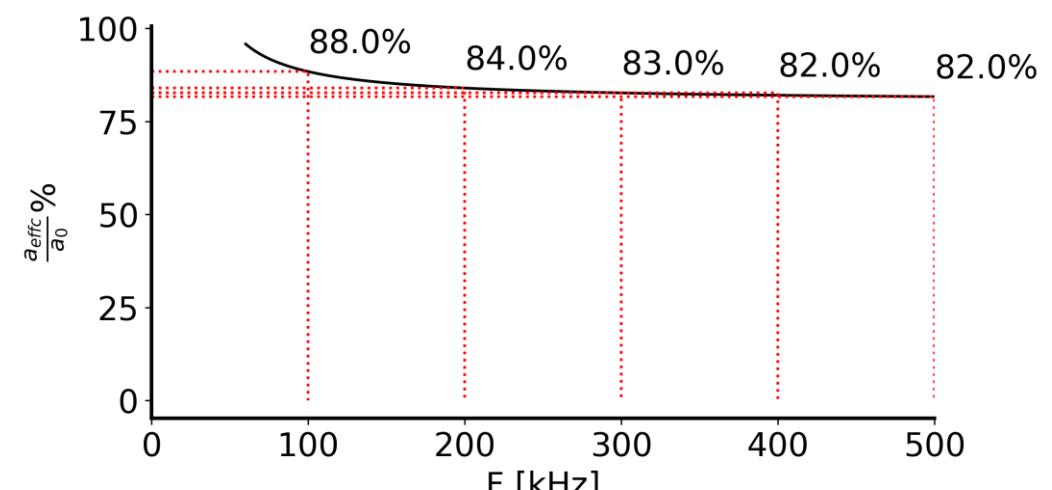
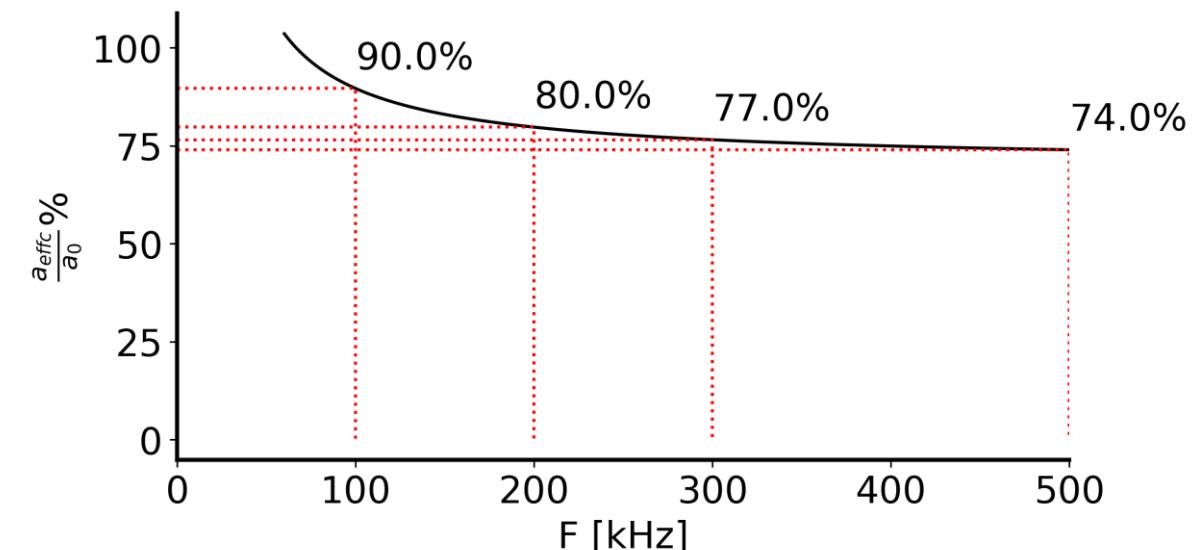
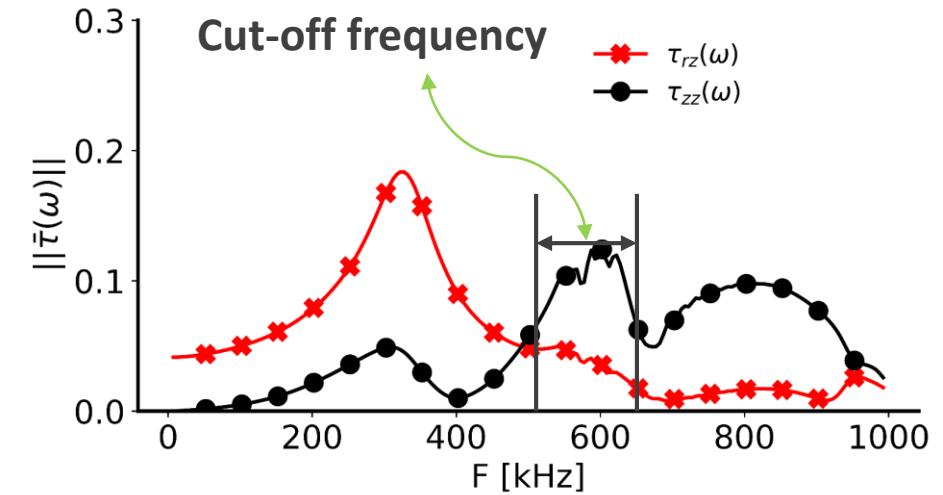
- Frequency range of interest :
 - For each ω_i
- $\tau_{rr}(r, \omega_i)$
- and
- $\tau_{zz}(r, \omega_i)$

$\tau^{rr}(\omega)$ and $\tau^{zz}(\omega)$ & a_e for both the Configurations for HAM

Configuration-1



Configuration-2

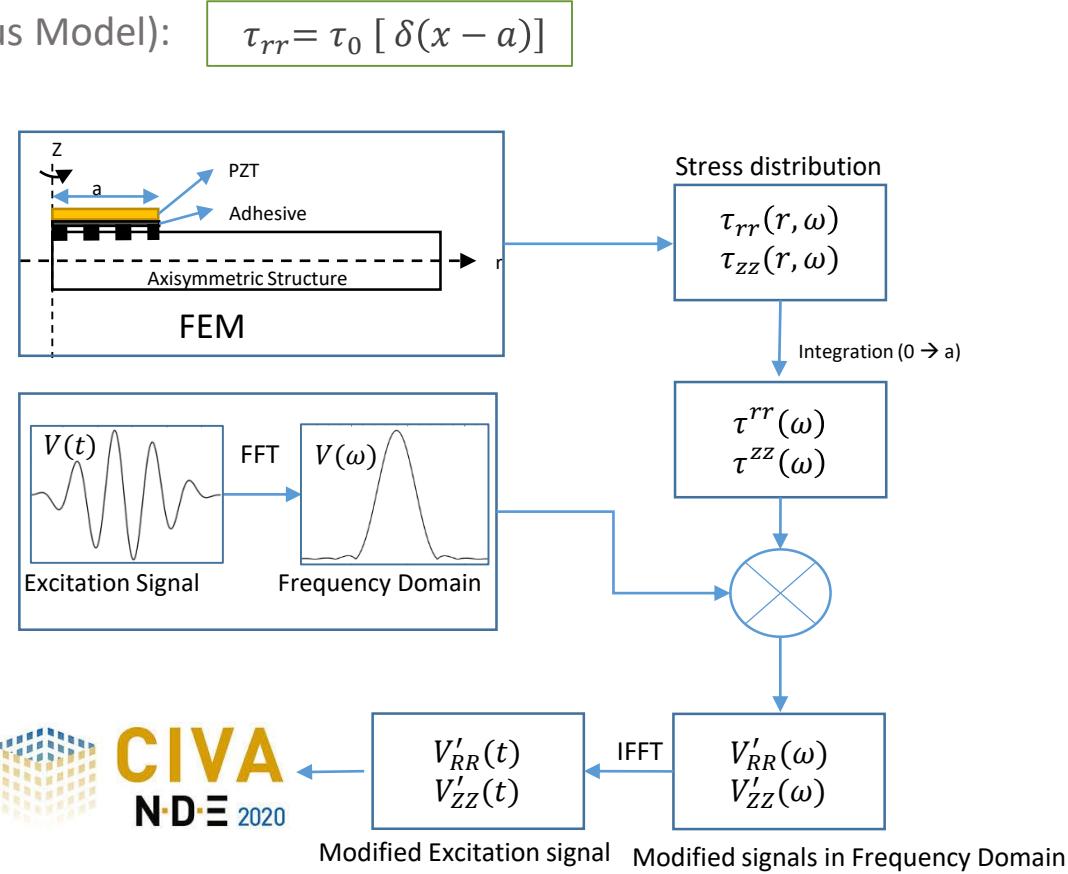


- Transient Spectral Finite Element Simulation (CIVA)

- Input of Excitation Function:

- Pin force Model (Previous Model): $\tau_{rr} = \tau_0 [\delta(x - a)]$

- HAM input:

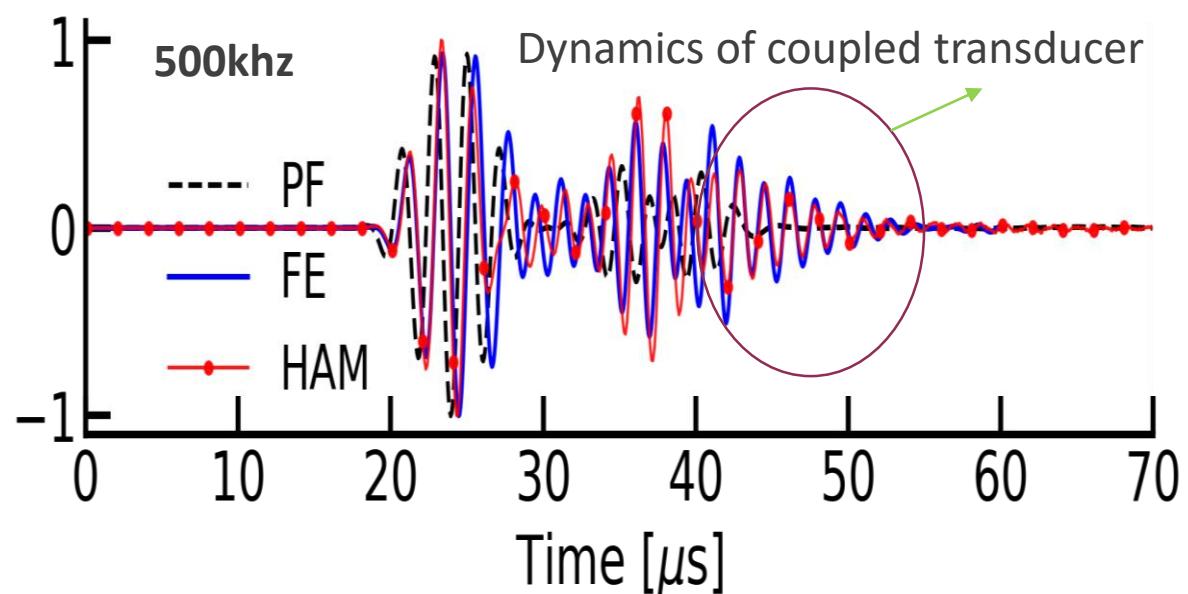
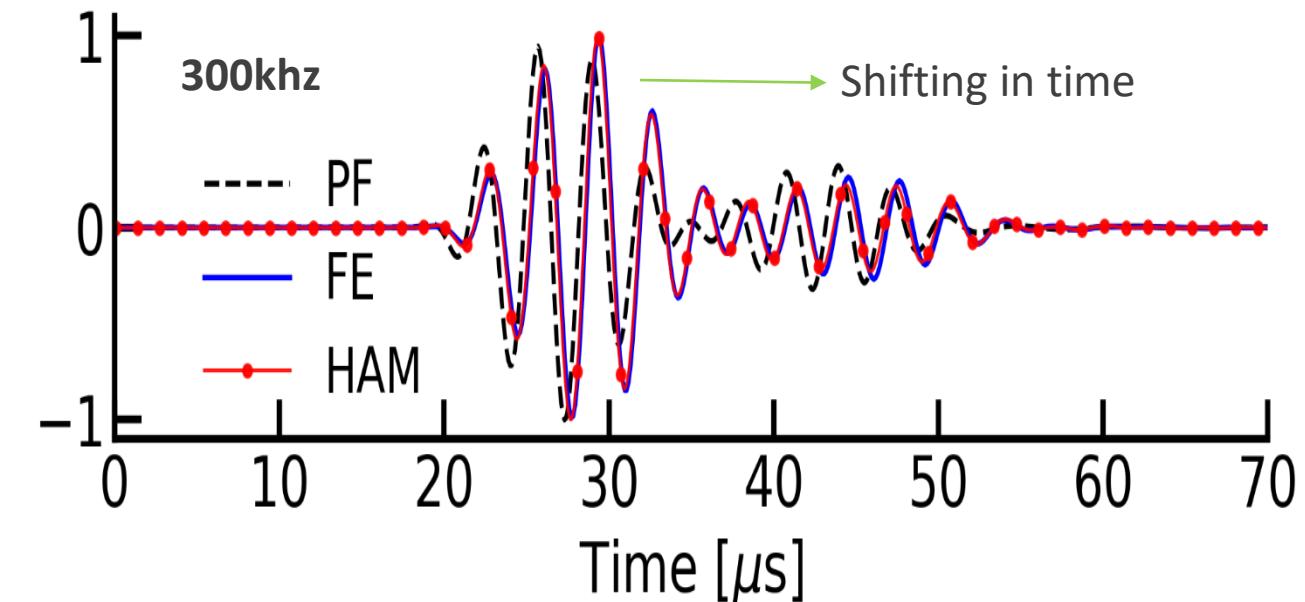
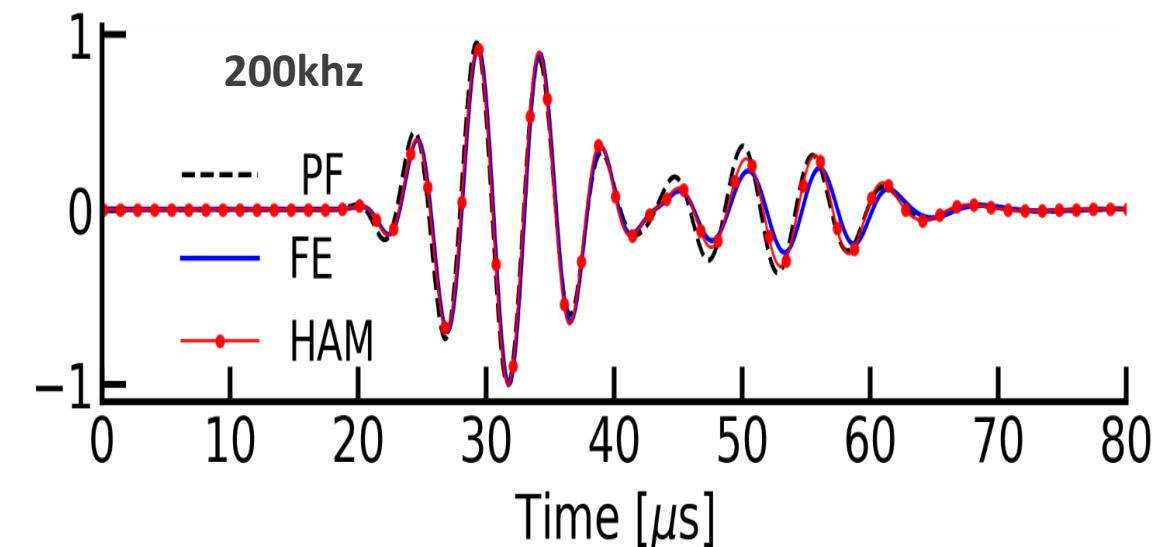
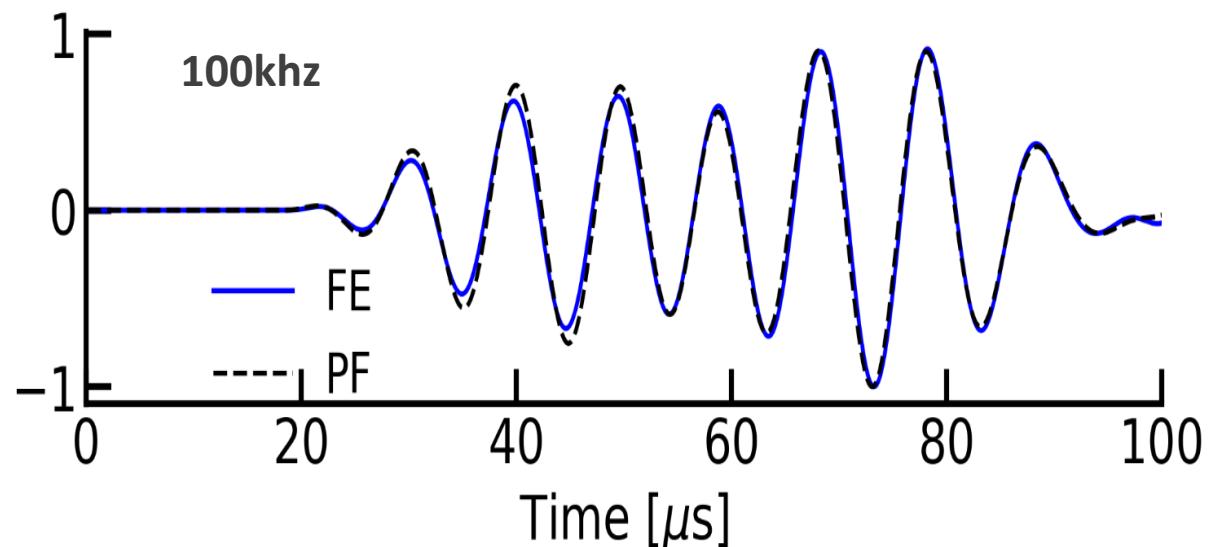


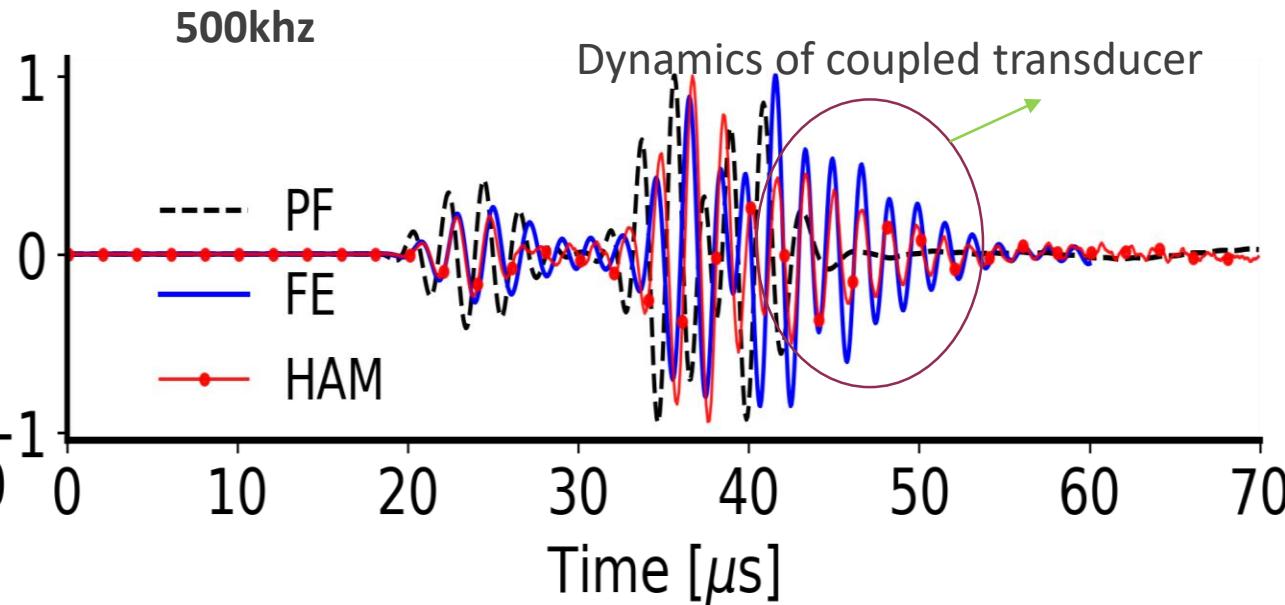
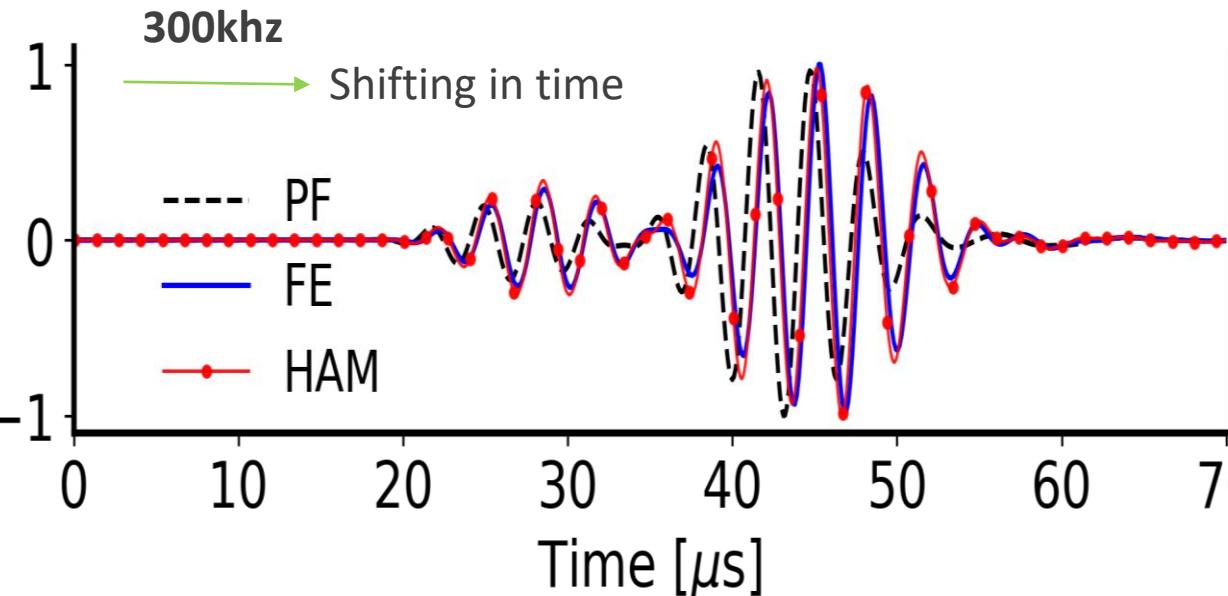
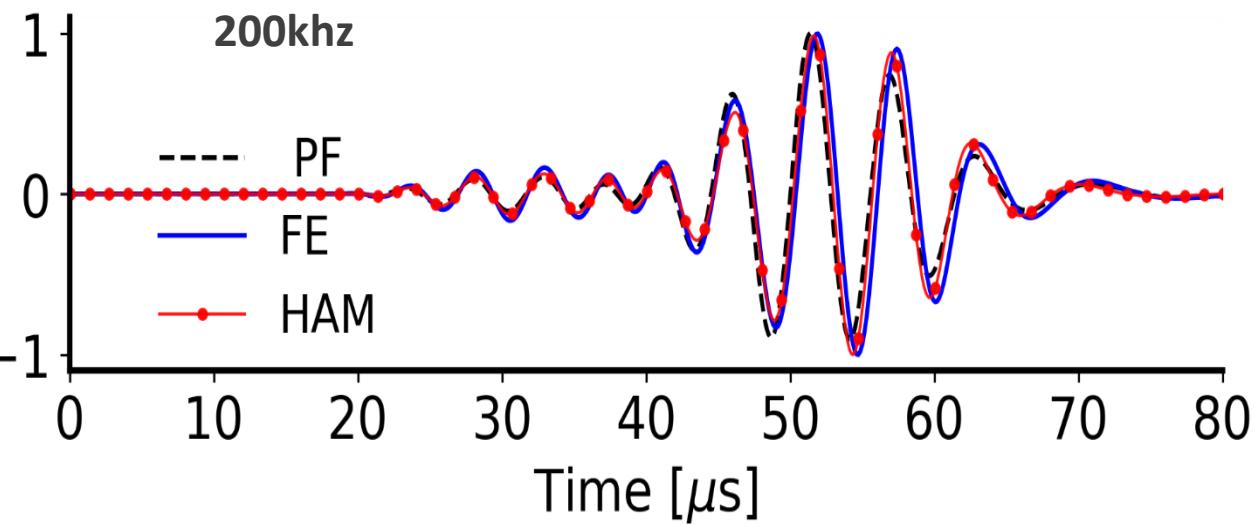
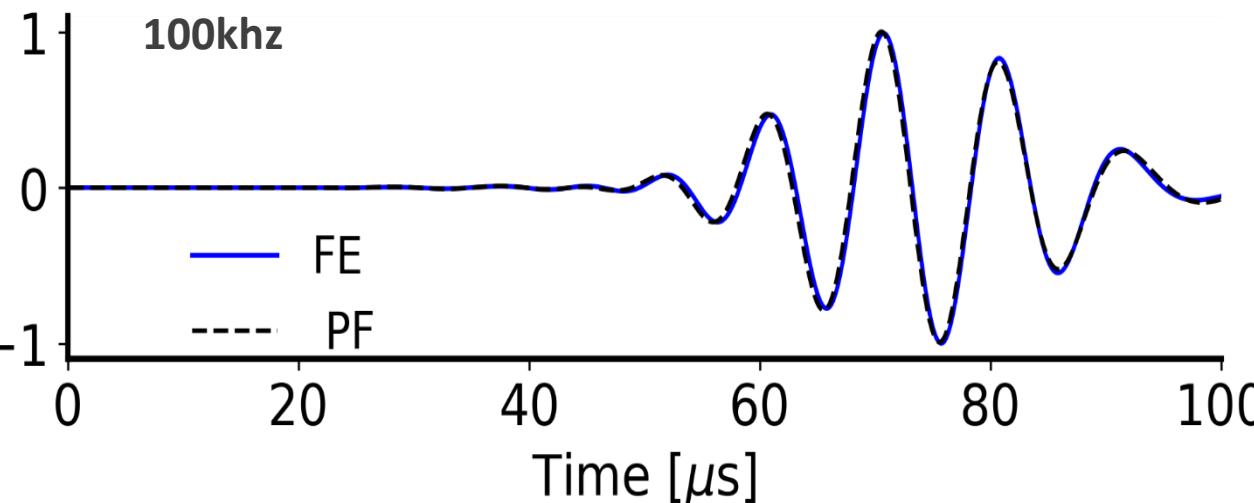
- Study:

- Time domain
- Displacement Field

Numerical Validation

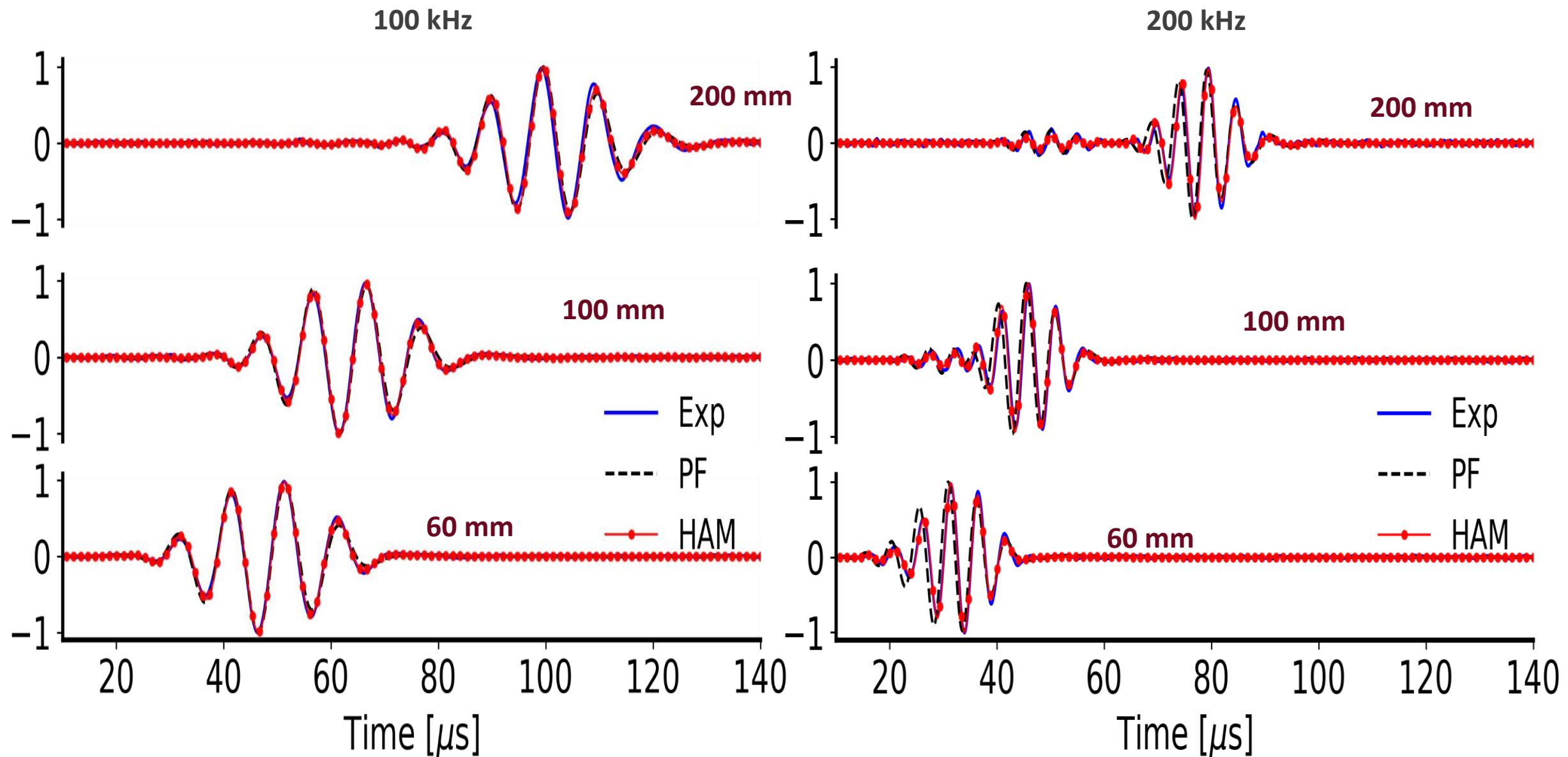
Configuration: 1

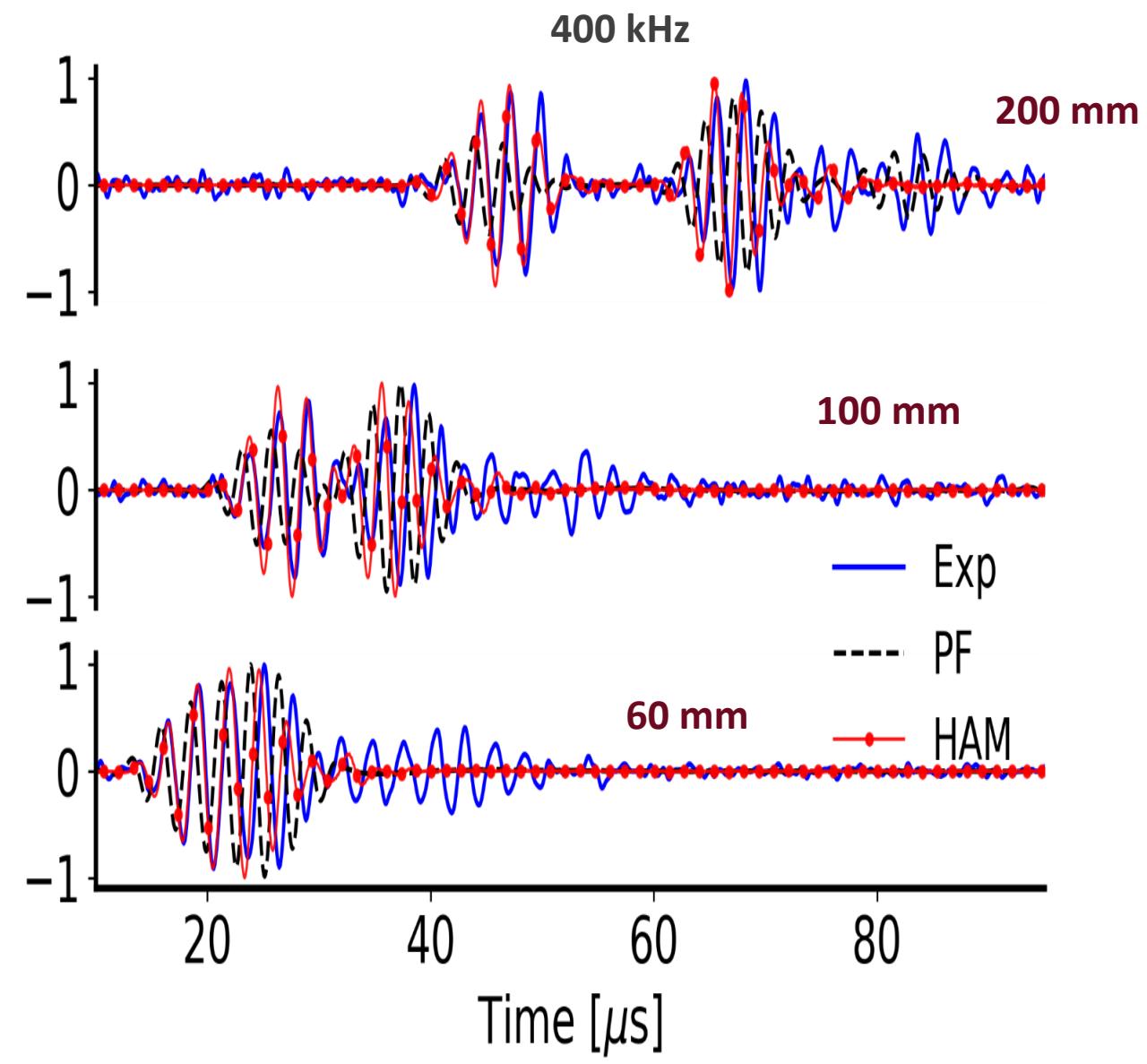
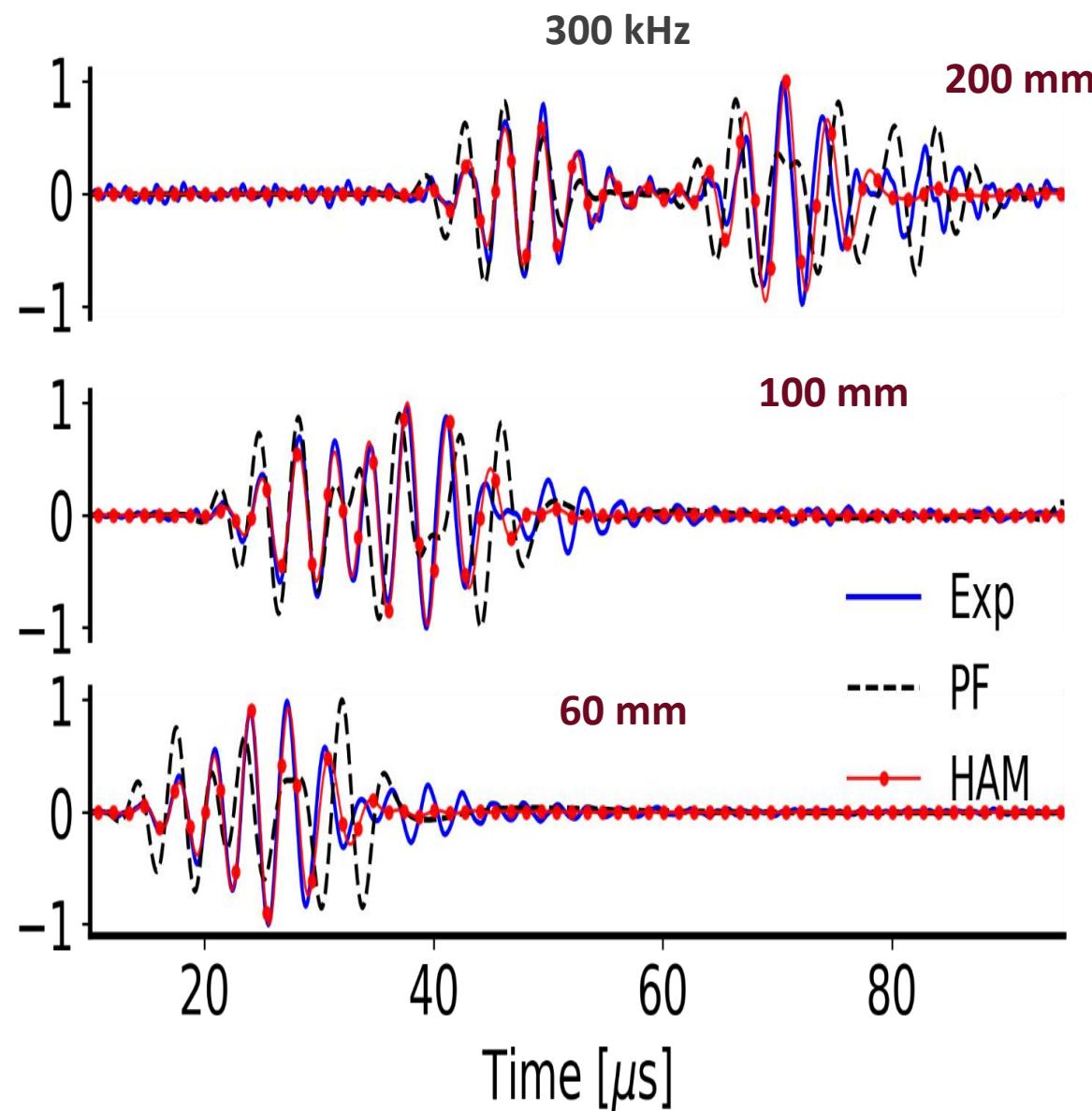
Configuration 1 : Numerical Study : Displacement Field U_{rr} 



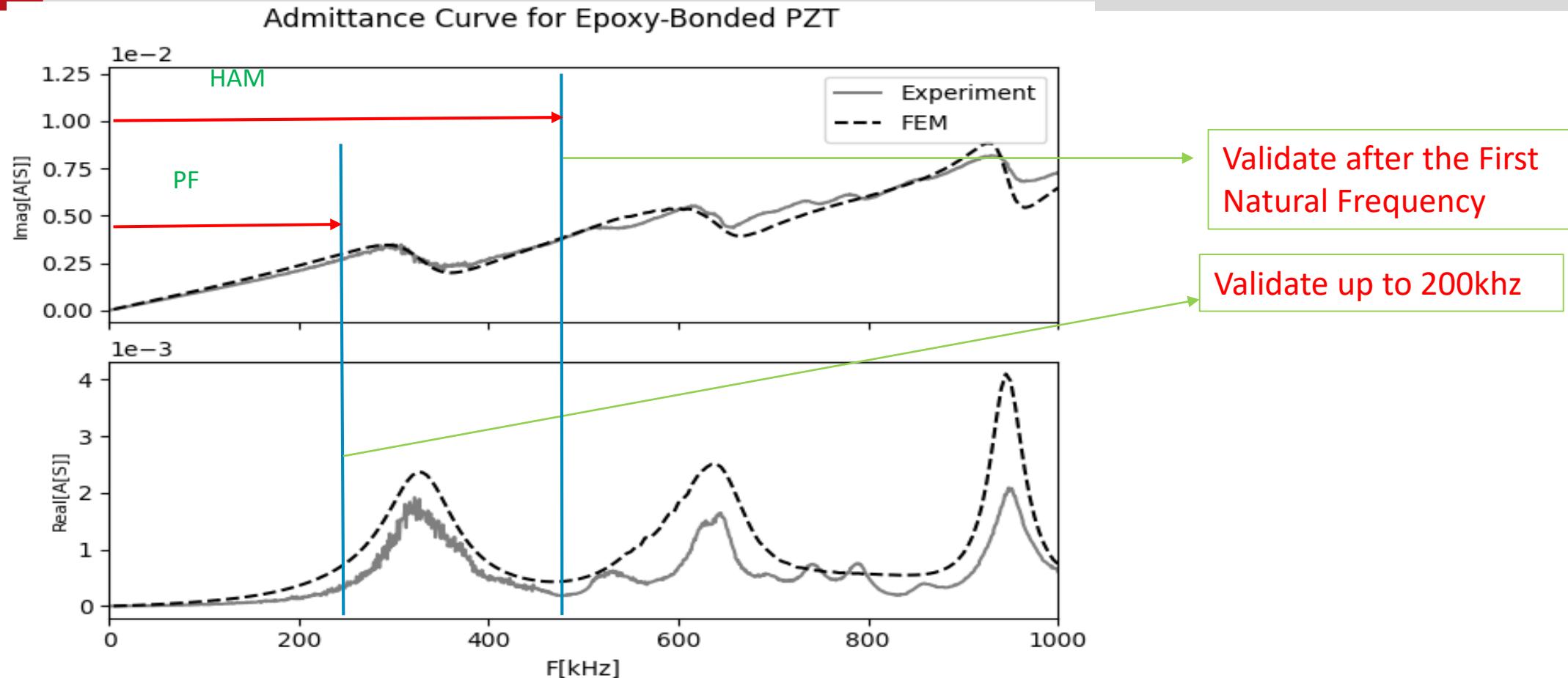
Experimental Validation

Configuration: 2

Configuration 2 : Experimental Study : Displacement Field U_{zz} 



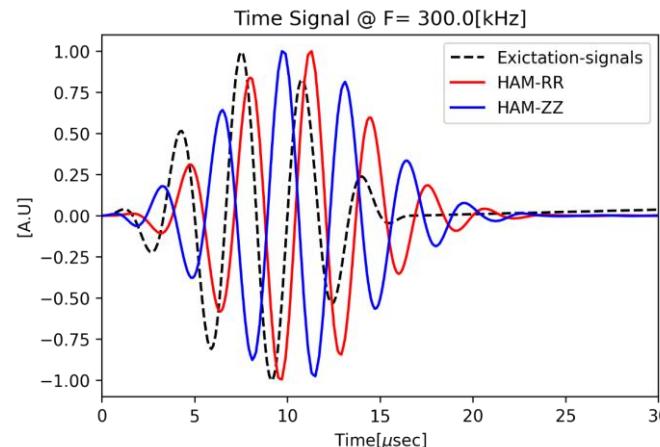
Observation for the HAM



OUTLINE

- Literature Review
- Theoretical Formulation
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- Increased the validation range above the first natural frequency of transducer.
- Transducer-adhesive dynamics → phase shift + amplitude difference
- Coupled transducer dynamics (normal + radial) + effective radius → Improvement of GW signals at higher frequencies (both simulations and experiments)
 - Material properties of the host structure, adhesive, and thickness of adhesive layer → change in admittance



- Future work
 - Model assisted probability of detection



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