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▶ To cite this version:

R Varennes, X Garbet, L Vermare, Y Sarazin, V Grandgirard, et al.. Impact of non-axisymmetric magnetic field perturbations on flows. 25th Joint EU-US TTF Meeting - EU-US Transport Task Force, Sep 2021, E-Conference, United Kingdom. . cea-03350020

HAL Id: cea-03350020 https://cea.hal.science/cea-03350020

Submitted on 21 Sep 2021

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Impact of non-axisymmetric magnetic field perturbations on flows



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Introduction

- Plasma rotation plays a key role in plasma confinement [1][2];
- Control of plasma rotation in reactor-sized tokamak is challenging [3];
- Intrinsic bulk plasma rotation is driven by turbulence and *Neoclassical Toroidal Viscosity* **(NTV)**;
- Magnetic field ripple is responsible for the NTV.

Objective: Understand the competition/synergy between turbulence and NTV with gyrokinetic simulations.

Theoretical model

 \blacksquare A reduced model based on the mean toroidal velocity V_T reads :

$$\frac{\partial V_T}{\partial t} = \text{Neoclassical Toroidal Viscosity} + \text{Turbulent torque}$$

Ripple constrains V_T through neoclassical friction ν_{ω}

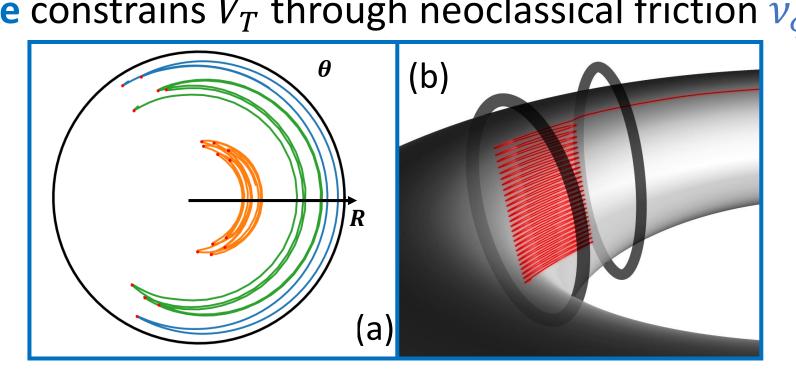


FIG.1 – Kinetic effects induced by ripple : drift of banana bounce points (a) and toroidal trapping between coils (b). Neoclassical friction ν_{φ} comes from the collisions between trapped populations.

Turbulence constrains V_T through turbulent viscosity χ_{turb}

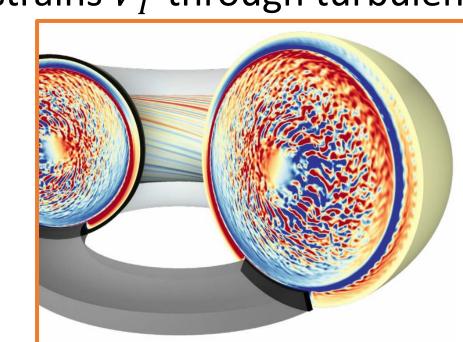


FIG.2 – Snapshot of the turbulent structures seen through a colormap on the electric potential. From rest, V_T grows due to wave-particle interactions.

Goal: Obtain coefficients of turbulent momentum transport from simulations and use neoclassical friction u_{φ} predictions to find the ripple amplitude threshold for which neoclassical effects overcome turbulence.

Turbulent momentum transport

- Turbulence impacts V_T through the toroidal Reynold's stress Π_{ω}
- -Axisymmetric theory [4][5]: $\Pi_{\varphi} = -\chi_{\mathrm{turb}} \frac{\partial V_T}{\partial r} + \mathcal{V}V_T + \Pi_{res}$ (Eq.1) Viscosity Pinch Residual
- Obtention of χ_{turb} , \mathcal{V} and Π_{res} using gyrokinetic simulations:
 - Simulations of turbulent plasma without ripple with different initial toroidal velocity \rightarrow FIG.3 shows the dominance of the viscosity : $-\chi_{\text{turb}} \frac{\partial V_T}{\partial r}$;
 - Eq.1 defines a plane in the $(V_T, \partial_r V_T, \Pi_{\varphi})$ space;
 - Mean square plane fit using simulations output gives an estimation of χ_{turb} within a radial range (see FIG.4 for an example).

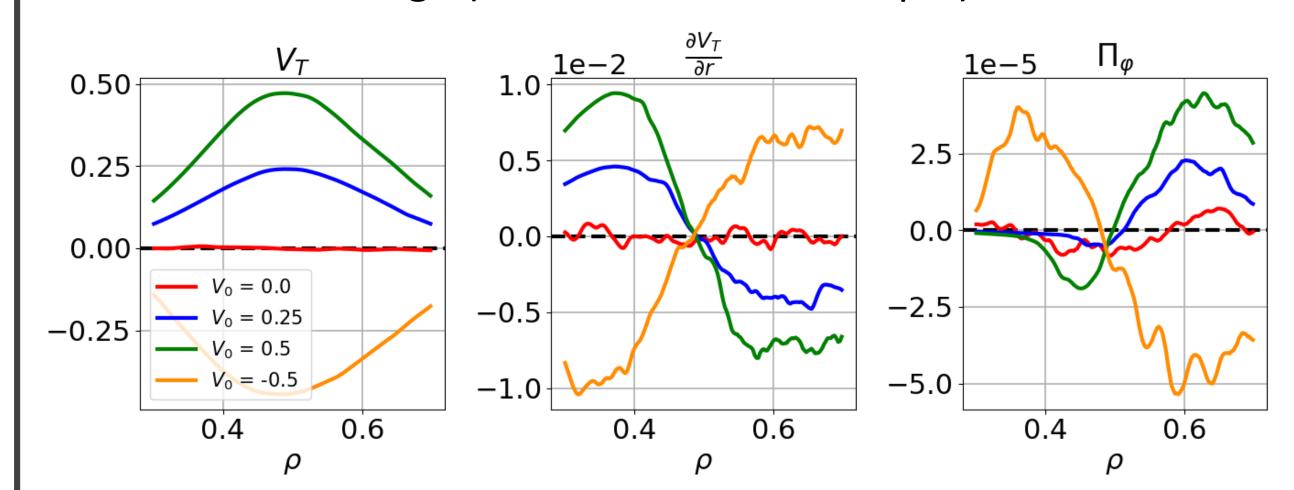


FIG.3 - Radial profiles of V_T , $\partial_r V_T$ and Π_{φ} taken at turbulent saturation for simulations initialized at different toroidal velocity $V_T(t=0) = V_0 e^{4(\rho-0.5)^2}$

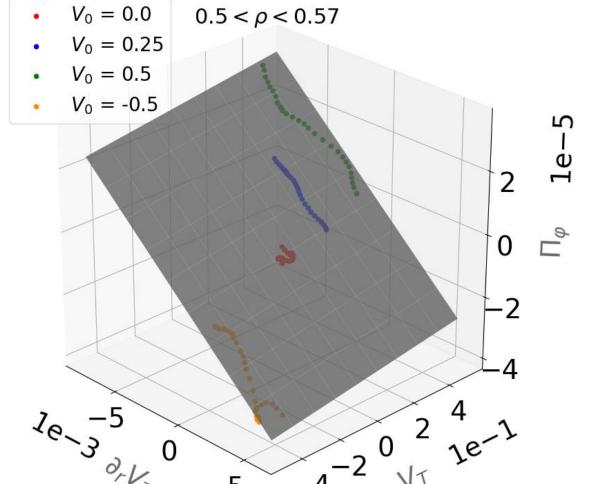


FIG.4 - Plane fit of Π_{φ} using point cloud from simulations giving an estimation of the turbulent viscosity within a radial range.

Neoclassical friction

- Ripple is responsible for magnetic braking M in the toroidal direction: the NTV;
- Neoclassical theory [6][7] with ripple gives :

$$m = -v_{\varphi} \left(V_T - k_T \frac{\nabla T}{eB_P} \right)$$
 Friction Thermal drive

- GYSELA code shows good agreement with neoclassical predictions;
- $-\nu_{\omega}$ increases with the ripple amplitude.

Conclusion

- Ripple is responsible for a neoclassical friction that constrains the toroidal velocity;
- Turbulence is a source of intrinsic rotation;
- Evolution of mean toroidal flow ruled by competing turbulent stress and ripple drag forces;
- The radial electric field grows in response to the modification of the toroidal velocity;
- Simulations suggest that neoclassic drag overcomes turbulent stress for typical realistic ripple amplitudes in WEST;
- Future work taking into account boundary physics with realistic WEST ripple amplitude is necessary to understand the shape of $\frac{dE_{\gamma}}{dr}$ and the transition toward high-confinement modes.

Competition ripple/turbulence

Complete model reads :

 V_T relaxation time

V_T gradient's length

■ Boundary physics not in the model → radially gaussian ripple (cf FIG.5)

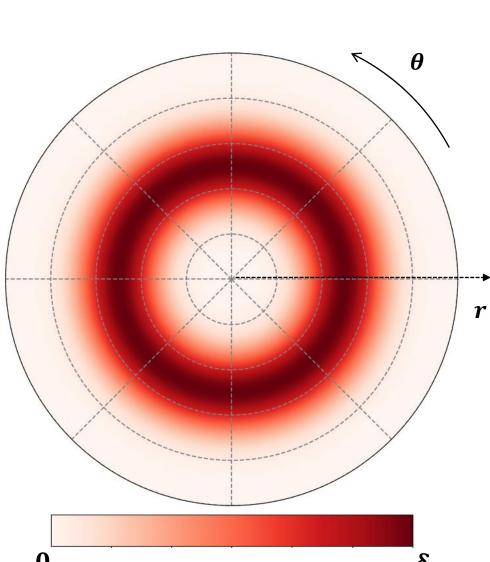
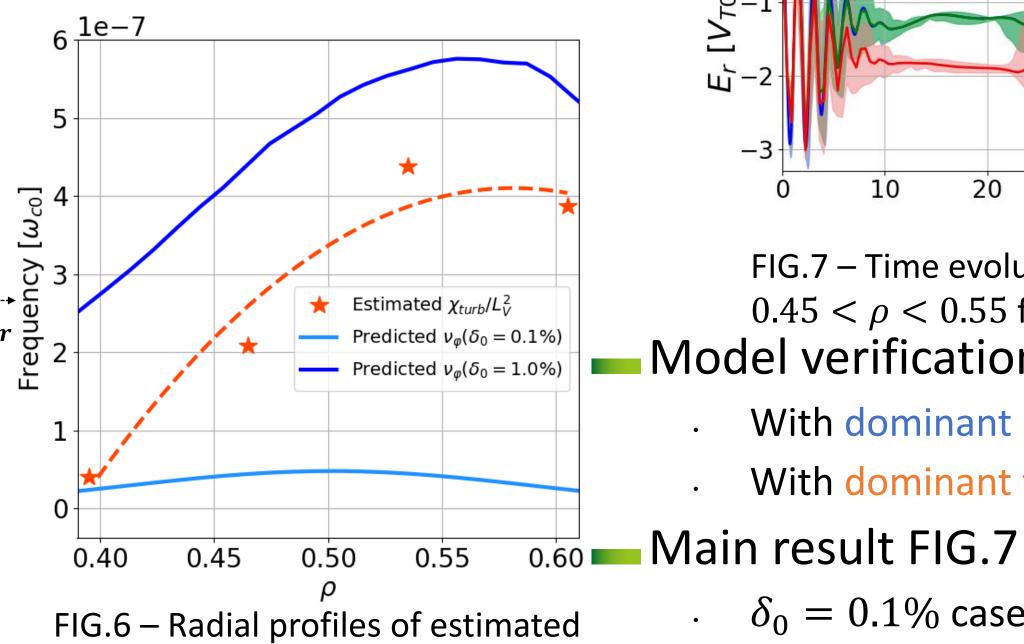


FIG.5 – Polar map of the ripple amplitude used for simulations.



turbulent relaxation frequency and

predicted neoclassical frictions.

-- $\delta_0 = 1\%$ Time $[\omega_c^{-1}]$

FIG.7 – Time evolution of V_T and E_r in the range $0.45 < \rho < 0.55$ for different ripple amplitudes.

- Model verification using 2 simulations: With dominant neoclassical friction
 - With dominant turbulent viscosity
 - $\delta_0 = 0.1\%$ case dominated by turbulence

 \rightarrow increase of E_r to fulfill force balance

 $\delta_0 = 1.0\%$ case driven by neoclassical friction

References

See FIG.6

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