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Nuclear Instruments and Methods in Physics Research A



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2	Recent Developments in Nuclear Heating Measurement Methods
3	inside the OSIRIS Reactor
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8 Abstract

9 Nuclear heating inside a Material Testing Reactor (MTR) needs to be known in order to design and to run irradiation 10 experiments that have to fulfill target temperature constraints. To improve the incore nuclear heating knowledge of the French 11 OSIRIS reactor operated by CEA, an innovative calorimetric system CALMOS (French acronym for CALorimètre Mobile OSiris) 12 has been studied, manufactured and tested. This device can be inserted in any in-core experimental location. It is based on a mobile 13 probe moving axially along the core height. First tests of this new probe, offering several ways for the heating evaluation, were 14 performed in the reactor periphery. Then, two complete prototypes dedicated to incore measurements (calorimeter and the 15 associated displacement system) were designed and tested during several reactor cycles. This paper presents a comprehensive 16 analysis of all the results collected during the measurement campaigns carried out between 2013 and 2015 with these new

17 prototypes in various reactor conditions. A comparison is made with previous calorimeters and obtained advantages are 18 emphasized. This new calorimeter has been designed as a real operational measurement system, well suited to characterize the 19 radiation field inside an MTR reactor.

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22 Keywords : Nuclear heating, differential calorimeter, incore measurements, OSIRIS reactor, mobile probe

23 **1. Introduction**

24 Nuclear heating inside an MTR reactor has to be known in order to predict sample temperatures during 25 irradiation experiments and for safety reasons, to demonstrate that the highest temperature inside irradiation 26 devices will not exceed material and thermohydraulic limits. Nuclear heating rate inside an MTR reactor is 27 usually done using calorimeters. A calorimetric measurement in reactors can be done either with a sensor working in adiabatic mode (without heat exchange with the outside and measurement of temperatures in 28 29 evolution), or with a sensor working in permanent mode (heat exchange with outside and stabilized temperatures 30 in the sensor). Homemade calorimeters [1, 2, and 3], working in permanent mode, have been used for many years 31 for the qualification of irradiation locations in the pool type MTR OSIRIS reactor.

Until recent years, OSIRIS calorimeters were designed with a pair of two aluminum cells, fixed onto the same aluminum base. Cells of each pair, both located at the same measurement level in the radiation field, are similar except that one contains a graphite sample while the other one has the corresponding volume filled with nitrogen (See Fig.1).

36



38 Fig.1. Static differential calorimeter previously used for heating measurements inside the OSIRIS reactor.

37

The two pairs of cells are diametrically opposed on the aluminum base to avoid any gradient effect in the calorimeter (heating radial distribution in the reactor). The whole structure is enclosed inside a tube in contact with the external water flow for heat removal. The pedestal, between the upper part of the cell and the base in contact with the external sleeve, plays the role of a thermal resistance through which the energy deposit inside the cell is evacuated towards the base.

The thermal flow difference between the two cells, proportional to the heating rate, is calculated thanks to temperature measurements and a calibration curve. This curve is done prior to any incore measurement, using a heater element located inside each cell and allows simulating the energy deposit by joule effect.

Note that the heating rate is written W/g (C) to emphasise the fact that it is relative to graphite. Devices for OSIRIS in-core measurements consisted of five different probes (each one made of four cells side by side, see cross section in Fig.1), piled-up along the core height leading to five measurement points, from which the heating profile curve was fitted. Inherent drawbacks of these calorimeters came essentially from the static nature of the technology. The heating distribution was plotted from only few measurement points, and the obtained distribution was restricted to the core height. In addition, each measurement point corresponded to a given calorimeter with its own calibration curve. Furthermore, an accurate dimensioning of an experimental device requires as input data, the knowledge of the axial distribution of heating but not restricted to the core itself. In addition, one of the major problems of this static conception came from ageing effects under the radiation field, which can lead to difficulties for detecting the decrease of the calorimeter sensitivity under irradiation.

58 2. New concept of the nuclear heating measurement

To overcome inherent drawbacks of the previous technology, an innovative system has been studied, tested and run in the OSIRIS reactor. The key point of this new sensor is setting two cells (one empty and one equipped with the sample in which we evaluate the energy deposit), piled-up inside a same external sleeve, and then moving the whole in the core with the help of a displacement system [8]. Therefore, advantages of such a new probe, compared to the static one, are:

To get a continuous heating profile instead of one deduced from only some points,

- To extend the axial measurement range above the core, where heating rates still remain high enough to be
 taken into account,
- To suppress entirely the ageing effect, because of a probe being in the radiation field only during
 measurement periods,
- For get all measurements by the same calorimeter, leading to a global consistency in the profile in terms of
 relatives values,
- To have a complete coaxial sensor design, allowing to avoid any asymmetric effect, facilitating any further
 modelling, therefore the comparison with calculation,
- To obtain pointwise measurements and to minimize any gradient effect thanks to a smaller size.

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The new design is displayed in Fig 2. The upper cell contains a graphite sample, whereas the lower one is empty (reference cell). A gas gap (nitrogen) surrounds each cell. They are set on a base inserted inside a stainless external steel in contact with the water flow. A thermocouple (K type) is embedded on the top of each pedestal ("hot

temperature") whereas a second one is located on the external surface of the base or at the bottom of the pedestal ("cold temperature"). Two heating elements composed by a constantan wire embedded inside an alumina pearl, located inside the cells, allow the calibration. The energy deposit in the massive part of the cells is flowing through the pedestal and then through the external sleeve.



83 Fig.2. CALMOS design with its two piled-up cells configuration.

The temperature difference " ΔT sample" (see Fig.2) is proportional to the energy deposit both in graphite and the cell structure, whereas " ΔT reference" is proportional to the only deposit in the empty cell structure. Therefore, in first approximation, if cells are identical, the difference " ΔT sample - ΔT reference" quantity ($\Delta \Delta T$) is proportional to the energy deposit inside the only graphite sample. This new nuclear heating measurement method has been patented [7].

As both cells are superimposed in a same envelope (Fig. 2), measurements are performed in two steps at each altitude in the core, by moving the probe in the radiation field. Along this R&D program, different phases followed each other, before reaching a complete device, which

- 92 allows incore measurements up to the nominal power: 93 Two mock-ups have been successively manufactured and tested in the reactor periphery, up to a 2 W/g(C)94 limited heating rate, to check the probe manufacturing and the measurement protocol, 95 A first complete equipment CALMOS-1 (probe associated to a displacement system) has been tested 96 inside the core in the 2011-2013 period (during 8 cycles) [9, 16, 23] which allowed to have a significant 97 feedback, to highlight the required improvements on this first prototype so as to reach a real operational 98 measuring system, 99 Finally, the CALMOS-2 device [28], has been manufactured, calibrated and tested during the last 3 cycles 100 in 2015. It is the updated version which can be considered as a qualified measurement device for incore 101 measurements. The automatic cell mobility, with a specific software through a Human Machine Interface 102 (HMI) allowed highlighting the different possibilities of this new sensor. 103
- This paper relates the entire R&D program, from the conception, the modelling, the manufacturing, the calibration and the qualification phase inside the core. Thanks to all results collected during the measurement campaigns, a comprehensive analysis is presented.
- 107 However, for detailing the cell configuration, the last upgraded CALMOS-2 version is taken as reference.108

109 **3. Calibration of the calorimeter**

110 Prior to any measurement, a calibration is performed in out of pile conditions [9]. Firstly, the calorimeter behavior

is checked in natural convection, directly into the pool of the reactor. A first calibration curve is done, and the linearityis verified.

113 Secondly, we check that the calibration coefficient remains unchanged when the probe, set on its displacement

114 device, is placed on a bench simulating real thermohydraulic conditions. The slope of each cell (°C/W) is measured.

115 The calibration procedure requires applying different electric powers to heaters (the constantan wire used for heaters 116 limits the applied power to around 5W), and to measure pedestal and base temperatures after stabilization. If we 117 consider that the heat transfer is only made by conduction through the pedestal, and applying the conduction law to 118 calculate ΔT between hot and cold thermocouples (see Fig 2), a K calibration coefficient for the calorimeter is defined 119 (W.g⁻¹.°C⁻¹) by:

120

121
$$K = \frac{1}{M_E P_E + m_V \cdot (P_E - P_V)}$$
(1)

122

Where P_E and P_V are the slopes (°C/W) of sample and reference cells, M_E the graphite sample mass and m_V the total mass of structure (aluminum + heater) above the hot point ("hot temperature"). The term $m_V (P_E - P_V)$ relates to the difference of thermal responses between cells, due to inevitable slight manufacturing differences, and secondly to take into account that bases of the two cells are not exactly in the same environment. If sample and reference cells are in a same radiation field, the total heating rate E_T is given by:

128

129 $E_{T} = K_{C}(E_{T}).K \cdot \Delta \Delta T \qquad (2)$

130

where $\Delta\Delta T$ is defined as $\Delta\Delta T = \Delta T$ sample $-\Delta T$ reference and $K_C(E_T)$ to the nonlinearity coefficient. This latter depends of heat leakages by radiation or conduction in the gas and, on the other hand, on the conductivity dependence of aluminum with temperature. Lower are temperatures reached in the cell, better is the linearity [11]. $K_C(T)$ has been evaluated both by using the finite element model and thanks to measurements up to 13 W.g⁻¹.

135 **4.** Possible measurement ways with the new sensor

136 *4.1 Use of the K coefficient from calibration*







141 Fig.3. Procedure for the nuclear heating measurement in the radiation field of the reactor core.

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Starting from a given static position in the radiation field, temperatures of the sample cell are recorded. Then, taking advantage of the moving system, the whole calorimeter is shifted (moved up or down), in such way that the reference cell position matches with the previous sample cell location. Temperatures of the reference cell are recorded. Then, heating is deduced using (2) when cells are at the same level. As shown in Fig.3 the displacement step by step allows drawing the entire heating profile. Note that the elevation step can be a subdivision of the distance between cells to draw the heating profile as finely as required.

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150 *4.2 Use of the "zero method"*

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In addition to use the calibration phase, advantage of such a calorimetric sensor is offering another nuclear heating measurement so called the "zero method". Fig.4 illustrates the measurement of heating through the "zero method". The two cells being at the same altitude in the core, the nuclear energy deposit inside the sample can be

- 155 evaluated by adjusting an electrical power in the reference cell heater (simulating the energy deposit in the sample by
- 156 radiation) so as to equalize ΔT sample and ΔT reference.







161

162 Then, the heating rate E_T in the sample is deduced from:

163

164
$$E_T = \frac{W_e}{M_E} \cdot K_0 \quad (3)$$

165

Where *We* is the dissipated electric power (W) in the reference cell and M_E the graphite sample mass (g). We note that K_0 is equal to 1 if both slopes are identical. As there are inherent small differences of thermal transfer capabilities (slopes in °C.W⁻¹) between the two cells, a K_0 correction factor is needed (the temperatures equilibrium is made with the reference cell):

171
$$K_0 = \frac{\frac{P_V}{P_E}}{1 - \frac{m_V}{M_E} \cdot (\frac{P_V}{P_E} - 1)}$$
(4)

172

173 With P_V an P_E the slopes in °C/W for the reference and the sample cells respectively, m_V the mass of the cell 174 corresponding to the part located the "hot" thermocouple and M_E the sample mass.

The "zero method" is considered as the most reliable measurement because it is performed without using the preliminary calibration. To improve the reliability of this method, two major improvements have been implemented in the last upgraded CALMOS-2 version [28] (Fig.5).

178

Position of thermocouples: Cells have not the same thermal transfer capability (slope in °C.W⁻¹), so the lower the difference is, the lower the K_0 influence in equation (3) is. The best way to tend K_0 to unity is to limit the thermal resistance between the two measurement points to the only Aluminum cylinder (pedestal, see Figs.5 and 6). The effect is significant. The slopes discrepancy in the last version has been reduced to 0.3 % [28]. The K_0 correction coefficient is now close to 0.99 (0.955 for CALMOS-1). By that way, performing a measurement using the zero method is nearly independent of slopes measurement, i.e of the calibration phase.

185 <u>Power measurement</u>: In addition to considering that the heat dissipation inside the heater element is fully 186 representative of the energy deposit by nuclear heating, we need also to be confident on the power measurement 187 during the equilibrium phase.

Calculations of the *We* energy deposit assume that the effective resistance r of the heater element is well known, and more importantly, that r does not change with ageing, temperature or irradiation conditions. Therefore, to measure more accurately the energy deposit by joule effect, and to avoid any assumption about the resistance evolution in the reference cell, this latter is equipped with a 4-wire element heater element, two wires for the intensity and two for the voltage measurement (Figs. 5, 6).

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- 196 Fig.5. Evolution of thermocouples locations and heater wiring to improve the "zero method" accuracy.
- 197

Therefore, the applied electric power to the heater is measured by $W_e = U I$ (U the voltage, I the intensity) instead of We = r I². Such implementation led to one of the major difficulty in the manufacturing, because the whole wiring has to be inserted inside an overall 17mm diameter, each wire insulated from each other.



- 202
- 203
- Fig.6. CALMOS-2 details: upgraded position of thermocouples located at the top and bottom of the pedestal (left), and implementation of a 4-
- 205 wire resistance inside the reference cell of the calorimeter (right).

206 **5. Numerical modeling of the sensor**

207 5.1 Modelling of the sensor

208

Temperatures inside the probe were required prior experiments for safety reasons. These temperatures were calculated using a Finite Element model of the sensor. This model was built using the FE CAST3M calculation code [24]. The whole probe was modeled using an axisymmetric description. Only very few simplifications were made on the cell description. Main ones are the suppression of the wires connecting the cells to the outside and the suppression of the rhodium SPND inside the lower base. The upper part of the device (sealed passage and above) was somewhat simplified since its plays only a secondary role on the measurement process. Fig. 7 displays the sensor meshing, to be compared with Fig. 9.

For practical reason, a small gap had to exist between each cell base and the external sleeve. It allows inserting the cells inside the sleeve during the sensor manufacturing. This mechanical clearance was determined from dimensional measurements. It is very small (24 micrometers at ambient temperature) but had to be considered in the FE model to get accurate results.



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246	Fig.7. Meshing of the whole calorimeter (left) with focus on the sample cell (right)
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248	Indeed, this gap is filled with nitrogen, which has a very low thermal conductivity (0.026 W.m ⁻¹ K ⁻¹ at 27°C). It
249	insulates the cells from the outside and has an important effect on absolute temperatures inside the cells. In the
250	FE model, the gap width was set to depend on temperatures since thermal dilation coefficients of aluminum (25 x
251	10 ⁻⁶ K ⁻¹ at 25 °C) and stainless steel (16.5 x 10 ⁻⁶ K ⁻¹ at 25 °C) are different. In order to avoid micrometer size
252	meshes (gap between the external surface of aluminum bases and the internal surface of the steel sleeve) aside to
253	millimeter ones (steel sleeve), a local apparent conductivity of the stainless steel located in front of the gap is
254	calculated (postulating a two cylinder serial configuration) and used at different steps of the FE simulation.

255 Physical characteristics of the different materials play a key role on the obtained results. Values of heat 256 capacity (*Cp*), thermal conductivity (λ), coefficient of expansion (α), volumetric mass (ρ) and their dependence 257 with temperature have been taken in literature. As thermal characteristics of aluminum AW1050 have a 258 significant impact on temperatures inside the cells, a specific determination by measurements was ordered to a 259 metrology specialized laboratory [27]. Except for the volumetric mass which is considered constant at 2670 kg.m⁻ 260 ³, other data were used in the last version of the FE model [25, 26]. They are summed up in Table 1.

261

Т	ρ	Ср	λ
(°C)	(kg.m ⁻³)	(J.K ⁻¹ .kg ⁻¹)	(W.m ⁻¹ K ⁻¹⁾
24	2684	886	
100	2668	939	24.8
200	2648	982	25.2
300	2627	1018	25.6
400	2605	1059	26.3
500	2582	1109	27.2

262

In the FE calculation, the thermal power is injected in the device as a specific power (W.g⁻¹). The same specific power is used for all different components of the calorimetric cell regardless the atomic number of their constituting material. This assumption was considered as appropriate considering previous experiments made inside the OSIRIS reactor.

Velocity of water around the probe was measured on an experimental bench before putting the measurement device in real conditions in the reactor. This velocity value was used to calculate the Reynolds number and then the thermal flux exchanged between the probe and the pool using the Dittus Boelter correlation. Water

Table 1. Thermal characteristics of the aluminum AW1050.

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temperature inside the device (internal flow in the displacement system, see Fig. 18) was measured by dedicatedthermocouples.

274 On the other hand, a polished mirror is placed around the cell in the design. That allows to limit heat losses by 275 radiation by adjusting in the cell the internal walls emissivity. Nevertheless, this thermal screen is not perfect. A sensitivity study performed on the CALMOS-1 cell (very similar to CALMOS-2), using an aluminum surface 276 emissivity of $\varepsilon = 0.05$ W.m⁻¹K⁻¹ and $\varepsilon = 0.01$ W.m⁻¹K⁻¹, led to a 1.4 % difference on the calculated heating rate E_T 277 278 (temperature of the graphite is roughly 500 °C). As it is very difficult to determine which coefficient to use, and 279 as the effect remains small, we chose not to take into account radiative thermal losses in the CALMOS-2 model. Fig. 8 shows an example of temperature map obtained for in pile conditions when a 13 W.g⁻¹ heating rate is 280 281 applied in the FE model.



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302	Fig. 8. Example of temperature distribution inside the cells obtained for 13 W/g with FE modelling (left: sample cell; middle: reference cell;
303	right: temperature scale).
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305	5.2 Comparison between calculations and measurements
306	
307	The first comparison is made on experimental results obtained during the calibration process of the probe. As
308	the simulation is concerned, the Joule electric power is injected as a volumetric power applied inside the alumina
309	pearl volume (element heater). Water temperature surrounding the probe is measured during the experiment.
310	Fig.13 shows that calculated results are in very good agreement with experimental data. However, the range of
311	power variation is limited because the total energy applied to the element heater (4.5 W in Fig.13) corresponds
312	roughly to a simulated 5 W.g ⁻¹ heating rate.
313	On the other hand, comparisons were made with measurements performed in real OSIRIS incore conditions.
314	Results agree quite well for low to medium nuclear powers. For highest values, some discrepancies appear
315	leading to a nonlinear behavior between the input nuclear power and the calculated one. One part of these
316	discrepancies could come from the behavior difference between both cells regarding the thermal radiative flux
317	(heat losses by radiation), despite the use of mirror-polished screens located around the cells. Another source of
318	nonlinearity could come from the non-symmetric axial environment of both cells. We tried in other papers to
319	calculate the Kc(E _T) (2) factor in order to correct these non-linearity effects. Nevertheless, even if interesting
320	results are obtained, it is difficult to assert the value and could not confirm the non-linearity evolution, which has
321	been experimentally found and presented in Figs. 23 and 36.

322 **6. Optimized characteristics**

- 323 Fig.9 shows a cross section of the final CALMOS-2 calorimetric probe. Taking into account thermohydraulic
- 324 conditions, mechanical constraints, and incore conditions requirements, optimized values for main dimensions are

325 [28]:

- 326 Base: AW1050 aluminum, 17 mm in diameter, 25 mm height,
- Pedestal: aluminum, 3.8 mm in diameter, 20 mm height, 20 mm between TCs locations,
- 328 Sample: graphite
- Cell upper part: sample weight 1.432 g, 8 mm in diameter, 20 mm height,
- 330 Mass of the cell upper part 1.621 g,
- External sleeve: stainless steel 0.5 mm thick, overall height 210 mm,
- Internal gas: N₂, capsule pressure 1.5 bar,
- Half-screens: stainless steel, 0.2 mm thick,
- Heater: constantan wire, 0.25 mm in diameter, resistance 1.8 Ω , 4-wire resistance for the reference cell, 2
- 335 A maximum,
- Distance between cells: 88 mm,
- SPND: Rhodium emitter 0.5 mm in diameter, 10 mm length.
- 338 The picture in Fig. 10 illustrates the preliminary assembly of both cells, before their insertion inside the
- 339 external sheath, with upper polished half-screens not assembled yet.



341 Fig.9. Overall cross section of final design of the calorimetric cell (CALMOS-2 configuration).



Fig.10. Intermediate step in the CALMOS-2 manufacturing. The two cells are in a temporary guide and thermocouples are put into place,but polished half-screens are not assembled yet.

7. Measurement of the thermal neutron flux

348 Measurement of the conventional thermal neutron flux (flux normalized to the 2200 m/s neutron speed) is 349 made thanks to a Rhodium SPND, especially designed to fit the calorimeter cell geometry. This SPND is similar 350 in terms of material and cross section to the standard one used for many years in OSIRIS reactor, but with a 351 rhodium emitter length reduced to only 10 mm whereas the standard one is 50 mm. The total length is around 20 352 mm allowing its implementation inside the aluminum cell base. In CALMOS-1 the SPND is embedded inside the 353 upper cell (around mid-height of the sensor) whereas for the last version it is embedded inside the lower cell. This change allows extending the accessible length by more than 100 mm in the core axis with CALMOS-2 (Fig. 21). 354 The lowest accessible altitude for the first version is -191 mm/core mid-place against -294 mm for the updated 355 356 one. This improvement is significant with regard to a total fissile height of 640 mm.

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- 360 Fig.11. CALMOS-2: Shaping and introduction of the specific SPND (rhodium emitter 0.5mm in diameter, 10mm length) inside the lower
- base (overall length 20mm).

363 The rhodium emitter offers a good sensitivity, but the capture reaction 103 Rh(n, γ) 104m Rh used for establishing 364 the signal (current intensity) has a response both in thermal and epithermal ranges. The thermal flux measurement 365 needs to be made along the entire mechanical stroke, from -160 mm to +960 mm/core mid-plane. However, the 366 neutron spectrum varies a lot along this range and needs to be calculated for deducing the thermal flux from the 367 delivered intensity.

The epithermal index (epithermal neutron flux/thermal neutron flux) characterizes the spectrum for energies in 368 369 the thermal range and is used to process the SPND signal. It is calculated inside the cell with the TRIPOLI-4® 370 Monte Carlo code at the precise location of the SPND and for any accessible altitude in the core [12, 21]. Fig 12 371 shows the evolution of this index calculated inside the 64 experimental location. Note that the index decreases 372 sharply at the fuel-moderator transition to become ten times lower in water. The relative contribution to the total current of the SPND due to the epithermal contribution is around 5 % in the upper part of the core (in full 373 374 moderator) whereas it can reach around 48 % at the core mid-plane. This shows that the epithermal index 375 knowledge, all along the CALMOS mechanical stroke, is of major importance for using a Rhodium SPND located inside the calorimetric cell. 376





380 Fig.12. Calculated epithermal index (epithermal neutron flux/thermal neutron flux) evolution in the 64 experimental location along the total

381 mechanical stroke of the calorimeter. The associated uncertainty is less than 1 %.

382 8. Results of the calibration

383 The calibration phase (see chapter 3) is performed in no radiation conditions and in both natural and forced 384 convection. The purpose is to determine not only the K calibration coefficient (1), linking the $\Delta\Delta T$ measurement 385 to the nuclear heating rate E_T , but also the time constant of the calorimeter, i.e the time necessary to get a 386 stabilized temperature map inside the calorimetric probe. During the calibration following key points are 387 measured:

- The cell slopes (°C/W) from which K is deduced and the slopes linearity up to a 5 W electric power,

- The independence of both cells. The electrical power is applied in heaters separately or simultaneously to

both reference and sample cells. It is essential to check that there is no influence of cells on each other,

391 - The validation of the K coefficient in forced convection conditions,

- The time constant of the calorimeter, defined in this experiment as the time required to reach 99 % of the
 stabilized signal after a transient. That drives the total time required to draw heating profiles in the reactor.
- 394

Fig. 13 shows the result of the slope measurement of the CALMOS-2 sample cell, illustrating the excellent linearity up to a 4.7 W applied to the heater element. In the same figure is plotted also the determination by calculation performed with the CAST3M finite element model (see chapter 5). The C/M ratio is less than 0.15 %. However, for this low level of power, the whole energy deposit in the upper part of the cell is entirely evacuated by conduction through the pedestal. We do not have any heat leakage (radiation, conduction in gas) to take into account in the modelling.



- 421 retained for the CALMOS-2 exploitation, is the average of the two results obtained in separated and simultaneous
- 422 heating, and in natural convection.

Thermo	Natural		Forced	
hydraulic	convection		convection	
conditions	(≈ 30 °C)		(≈ 40 °C - 1.24 m ³¹)	
Heating mode	Sep.	Sim.	Sep.	Sim.
Ps slope (°C.W ⁻¹)	7.325	7.337	7.418	7.388
P _R slope (°C.W ⁻¹)	7.301	7.294	7.432	7.344
K (W.g ⁻¹ .°C ⁻¹)	0.0950	0.0945	0.0943	0.0939
K Retained value	0.0948			
$(W.g^{-1}.^{\circ}C^{-1})$				

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The second major parameter is the calorimeter response time (or time constant), which is an important criterion. It must be taken into account to define, before starting measurements, the allowed definition (number of steps) compatible to the possible modification of the radiation field (control rods movement) during the expected duration of the total scanning. As this time depends on cooling conditions, it is measured in natural and forced convection [13, 19]. Preliminary tests, performed on the two mock-ups (illustrated in Fig. 14), showed that the response time measured during a temperature rise is slightly higher to the time measured during a decrease (roughly 15 s over a 250 s total time). On the other hand, in natural convection, the presence of the external

⁴²⁵ Table 2. Experimental results of CALMOS-2 calibration.

434 sheath (required for a calorimeter in incore conditions) leads to increase the response time (roughly 8 s over a 250 435 s total time). Indeed, when the calorimeter is inside its external sheath (situation illustrated in Fig.18), the heat 436 extraction is ensured by the only 1.5 mm static water gap surrounding the calorimeter (in natural convection).

437 Such situation occurs when primary pumps stop (no primary flow).

438



439 440

Fig.14. Measurement of the response time on the mock-up N°2. Evolution of temperatures during a power transient, after application and
 shutdown of a 1 A intensity in both element heaters.

443

444 Therefore, the measurement of the time constant of calorimetric cells, when set on their displacement systems (CALMOS-1 and 2), are performed by recording the temperature decrease, first to measure the longest time 445 constant of the whole cell, and secondly to avoid any constraint involved by applying a too much sharp step of 446 power to element heaters. To perform this measurement, a 0.8 A is applied to both heaters until thermal 447 448 equilibrium. After turning off the current, temperatures are recorded (example in Fig. 15). The analysis of Figs. 449 14 and 15 shows that the time response of the sample cell is longer than the reference one, due to the additional thermal inertia induced by the graphite. Table 2 refers to results obtained in natural and forced convection for the 450 451 CALMOS-1 calorimeter, similar to the last version. It gathers measured values corresponding to times required to reach 99 % of the stabilized signal. Obviously, it shows a significant gain of time response when using the 452 453 OSIRIS forced convection.



457 Fig.15. Measurement of the CALMOS-2 calorimeter response time by a decreasing transient.

458

For the OSIRIS thermohydraulic conditions, the response time of the sample cell is close to 2 min 30 s. That value governs the total time required to reach the temperatures stabilization in the whole probe, after any change of position in the reactor radiation field. Table 2 shows also that, when the sensor is used inside the core but without primary flow (measurement at very low reactor power or follow-up of the residual power) the waiting time to make a heating measurement requires a total time at least 30 % longer.

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	Natural	Forced	Discrepancy	
Conditions	convection	convection	(N-F/N)	
Sample				
cell	210 s	155 s	-26%	
Reference				
cell	150 s	90 s	-40%	

465

466 Table 3. Experimental results of the response time measurement on the CALMOS-1 calorimeter.

468 Note also that using the AW1050 Aluminum alloy for the cells allowed reducing the response time due to its
469 higher thermal conductivity. (230 W.m⁻¹.K⁻¹ against 130 W.m⁻¹.K⁻¹ for the AW 5754 alloy at around 100 °C)[26,
470 27].

471 9. Generalities about the OSIRIS reactor

OSIRIS was a pool type light water reactor with an open core. The core itself is a compact unit, with an horizontal section of 60 cm × 70 cm and a height of 70 cm. The core housing contains a rack of 56 cells. This rack is loaded with 38 standard fuel elements, 6 control elements and up to 7 beryllium elements. At least two experimental locations (22 and 26) are dedicated to radioisotopes production for medical application (MOLY devices). Remaining locations (24, 44 and 64) receive experiments, and are equipped with water boxes (82 mm x 82 mm) which can contain up to 4 experiment rigs (37 mm in diameter) (see Fig. 16).



479

478

480 Fig.16. Horizontal cross-section of the OSIRIS core

481

Purpose of the CALMOS device is making measurements in 24, 44 and 64 locations. The core configuration is such that the heating level is higher when we go from the south to the north, i.e 24 then 44 and finally 64. All measurements carried out from 2013 to 2015 with CALMOS-1 and CALMOS-2, and detailed hereafter, were

carried out in various core conditions (start-up, steady state, shutdown, core loading, rods positions and
configuration of experimental devices).

487 **10. Description of the displacement system**

The study of the displacement system, allowing the movement of the calorimetric cell inside the core is as important as the development of the calorimetric cell itself. This device needs to answer not only to conditions for performing a measurement inside the core, but also as a standard incore experiment, to meet all conditions in terms of reactor safety.

492 Main purpose of this paper is not detailing this part of the R&D program. However, a short description is 493 given hereafter to illustrate the working mode, objectives, limits, and difficulties for moving a probe inside an 494 experimental reactor. The challenge to cope with was to get incore axial distributions while preserving 495 permanently both same measurement conditions and the required safety margins.

The complete device is in two parts: the calorimetric cell and the displacement system. The device is set inside the core before reactor start-up, and taken out after the end of the cycle. It is inserted into a water box (reactor equipment) and inside one of the four available experimental locations (Fig. 17).

499 The displacement system is mainly made of an external sleeve (composed of aluminum and stainless steel) 500 inside which the calorimetric probe moves along a 1150 mm mechanical stroke corresponding to the core fissile 501 height and 510 mm above fuel elements, as shown in Fig. 17. Inside the connection box (link between out of pile 502 and in pile cables), placed above the pool surface 7 m away from the upper part of the displacement system (not 503 visible on Fig. 17), an electric engine rotates a cable inside its own sheath (mechanical transmission). This 504 rotation movement is transferred from the connection box to the submerged box. Inside this latter, located at the 505 top of the displacement system (around 4 m above the core mid-plane), a mechanical connection is made thanks 506 to a gearing set between the cable and a connecting rod, itself linked to the mobile equipment. From the bottom to 507 the top, the mobile equipment of CALMOS is made of the probe itself linked to the insertion tubes, themselves 508 connected to a screw nut system, itself connected to the connecting rod. By rotation on its axis, the cable moves

- the whole vertically inside the external sheath. Two flexible hoses connect the submerged box to the upper connection box (Fig. 8), the first being dedicated to the mechanical transmission (cable in rotation) and the
- 511 second one to the cell signals (thermocouples and rhodium SPND).
- 512



514 Fig.17. Main components of the displacement system equipped with the calorimetric probe (in blue and red according to the position).

- 515
- 516 Main requirements for the displacement system are:

517

Ensuring a relevant heating measurement, as close as possible to the actual heating inside a standard 519 experiment used for material irradiation. The material composition on the 37 mm cross section (water + 520 external sleeve + calorimeter) must be as close as possible to the standard experimental capsule,

Ensuring a displacement range as large as possible; the total mechanical stroke is 1150 mm 521 522 corresponding to the fissile height of fuel elements and a sufficient height above,

523 Offering a rest position for the calorimeter. The highest altitude of the cell is around 900 mm with regard to the core mid-plane (see Fig. 17). At this position, the estimated residual heating rate is less than 30 524 mW.g⁻¹ and the thermal neutron flux level less than 10¹¹ n.cm⁻².s⁻¹, avoiding any significant ageing effect 525 526 on the probe,

527 Centring the calorimetric cell (18 mm in diameter) along the vertical axis which has a 37 mm internal diameter, 528

- Ensuring the role of guide and housing for all the cables required for measuring the signals. That was the 529 major difficulty in the design. The cables, with mineral insulation and stainless steel sheath (1mm in 530 diameter), are twisted together in a spring shape so as to accommodate the 1150 mm total stroke by 531 532 successive stretching and compression,
- Ensuring appropriate cooling conditions of the probe whatever its altitude in the core. If ΔT sample and 533 ΔT reference temperature differences do not depend on the water cooling temperature and the water flow 534 535 (but only to the heating rate), absolute temperatures reached inside the cells depend directly on cooling conditions. The hottest allowed temperature inside the cell structure is fixed to 500 °C in order to keep a 536 537 sufficient margin against aluminum melting [26]. Therefore, it is essential to ensure a good cooling. The 538 design allows to cool both the external sheath (external flow) and the mobile equipment (internal flow). This internal cooling flow enters the sheath tube through its base (located under the fissile height of the 539 540 core) and exits through several holes located above the probe rest position (Fig. 15). In nominal 541 conditions, the internal flow is 1.35 m³·h⁻¹ (measured on a specific hydraulic bench representative of 542 OSIRIS conditions) corresponding to a 3.2 m.s⁻¹ linear speed around the probe. The cooling flow

variation does not exceed 12 % for a probe running from the top to the bottom of the total mechanicalstroke.

545 In addition, the system has to meet the safety requirements in terms of reactivity. The insertion of the 546 mobile equipment in the sleeve changes the local composition of the water box as the descent 547 progresses, involving a reactivity effect on the core.

548



551

549

550

552 Fig.18. Cooling water flows inside the CALMOS device, when located inside an experimental location of the OSIRIS core.

Therefore, this effect has to be evaluated to check that, first, it does not disturb reactor operation in terms of safety and, secondly, that the control rods movement for compensating this effect does not modify the radiation field we are measuring. Results of this study are:

- Calculation showed that, whatever the experimental location, the reactivity effect induced by the total
 insertion of the mobile equipment does not exceed 70 pcm. Such low impact complies with OSIRIS
 safety requirements,
- To avoid any disturbance on the reactor, the vertical speed of the probe during the insertion phase is limited to 5 mm.s⁻¹, leading to a reactivity effect less than 0.5 pcm.s⁻¹. In practice, to add a margin, the vertical speed was further limited to 1 mm.s⁻¹ when the cell goes through the fissile height of the core. As a result, no disturbance on the reactor operation was noticed during measurement campaigns,
- The double monitoring of the radiation field by two devices located side-by-side in the same 64 location
 (detailed in § 18), showed that the disturbance led by one calorimeter progression inside its own sheath,
 does not involve significant changes in the close vicinity i.e in adjacent locations in the same water box.

567 **11. Generalities about incore measurement campaigns**

For each CALMOS device, a comprehensive measurement campaign has been carried out inside the core. The CALMOS-1 measurement campaign lasted 10 OSIRIS cycles, corresponding to 8 cycles for the prototype itself and 2 additional ones for the comparison with the updated CALMOS-2 version. Taking into account the scheduled final shutdown of the reactor, planned at the end of 2015, the development, manufacturing, calibration and all the tests of this last configuration had to be done during the only last 3 cycles of OSIRIS reactor. To qualify CALMOS devices, the following kind of tests were carried out:

- 574 Three incore locations, 24, 44 and 64 (in ascending order of heating rate), were measured. We remind 575 that a single location can be investigated per cycle,
- 576 For the only device CALMOS-2, 21 complete automatic scanning were performed,
- 577 Follow-up of the reactor start-up with the probe located at the core mid-plane,

	32	Nuclear Instruments and Methods in Physics Research A
578	-	Follow-up of the residual power decay with the probe located at the core mid-plane,
579	-	Measurement of the mutual influence, in terms of heating and thermal flux, between both devices when
580		they are placed side-by-side in a same location,
581	-	Comparison of CALMOS and MEREVER devices in terms of thermal neutron flux,
582	-	Measurement of the reactivity effect consequently to the insertion of the mobile equipment inside the
583		core,
584	-	Influence of the probe displacement speed on the core reactivity,
585	-	Performing various measurements with the zero method, covering the 0-4 W.g ⁻¹ heating range,
586	-	Measurement of separated distributions (nuclear heating or thermal neutron flux),
587	-	Measurement of simultaneous distributions (nuclear heating and thermal neutron flux),
588	-	Test of all possibilities offered by the HMI system to set the parameters before the scanning (scan step
589		from 88 to 11mm, moving-up or moving-down, waiting time at each step, data acquisition for a long
590		time).
591		
592	All thes	e tests required, for the only CALMOS-2 device, the total following durations:
593	-	3 monitored cycles (F282, F283 and F284),
594	-	A total 14 hours recording time of the start-up phase, from 0 to the nominal power,
595	-	A 74 hours total duration of automatic scanning time, thanks to the specific software and the human
596		machine interface (HMI),
597	-	More than 19 days monitoring time of the residual power decay.
598		



Fig. 19. Moving down of the loaded water box, equipped with both CALMOS devices, with the handling crane inside the 64 experimentallocation.

603

Fig 19 shows the F284 loading phase (with CALMOS devices in the same water box which is being put into place but not completely inserted yet), while Fig.20 shows a top view of the final configuration after the loading completion, just before reactor start-up.

607



610 Fig. 20. Loading configuration of the core during the last F284 OSIRIS cycle. Both CALMOS prototypes are located side-by-side in the

611 incore 64 experimental location (respectively 64NW and 64 NE positions). In addition, the MEREVER device dedicated to thermal flux

612 measurement is in the same location in 64South-East position.

613 **12. Establishment of the nuclear heating profile inside the core**

To illustrate the way of performing the heating profile in the core, Fig. 21 shows an example of signal acquisition in the 24North-East location. On the same graph are plotted at each scan step (here 48 mm) ΔT sample, ΔT reference and their difference $\Delta \Delta T$, from which the nuclear heating is calculated (2). In case of CALMOS-1, the lowest position (under -139 mm) is not accessible with the sample cell, whereas above the core the highest position (above +906 mm) is not accessible with the reference cell, due to the probe configuration made up of a cell superimposed to another one with a 95 mm separation distance (88mm for CALMOS-2). Magnification scale (on right) permits to observe variations above the core.

621 In Fig. 22 are plotted together normalized values (to unity) of ΔT sample, ΔT reference and $\Delta \Delta T$ the difference 622 among them. If the only quantity representative of the energy deposit in the sample graphite is $\Delta \Delta T$, the relative 623 distribution can be obtained by each ΔT measurement (sample, reference or their difference).



624

625

626 Fig. 21. Example of signals acquisition in 24North-East location of the core. Temperatures of ΔT sample and ΔT reference are recorded along

627 the 1150mm total stroke. The core fissile height is between +/- 320 mm vs the core mid-plane (zoom in right scale).

The three distributions are very close to each other. That is an important remark. That allows deducing the absolute distribution of heating in the reactor with only one measurement at a given altitude and with one of the three possible relative distributions.

632



633 634

Fig. 22. Distributions normalized to unity of ΔT sample, ΔT reference and $\Delta \Delta T$ in the 24North-East location of the core obtained by CALMOS-1 (zoom in right scale).

637

638

639 On the other hand, that allows extending the heating profile on highest and on lowest altitudes (blue and red 640 circles in Fig. 21), for which it is impossible to measure the $\Delta\Delta T$ quantity due to the two superimposed cells 641 configuration (Fig. 2). The highest altitudes are inaccessible to the empty cell, whereas lowest attitudes are 642 inaccessible to the sample one.

643 **13. Test of the zero method and evaluation of the nonlinearity**

644 The "zero method" is the research of the equilibrium between cells, by balancing the nuclear energy deposit in 645 the sample by a joule effect in the reference one. This method is considered as a reference (illustrated in § 4.2). 646 However, it cannot be used in routine to establish the complete heating distribution inside the core, due to the 647 time required for reaching the temperatures equilibrium. Secondly, it is only applicable in upper part of the distribution where heating levels remain under around 4 W.g⁻¹, due to the maximum current intensity (2 A) 648 649 applicable to heater wires. Nevertheless, as considered as the best approach of an absolute measurement, it 650 enables to confirm results obtained by the calibration curve. In addition, the zero method is a way to study the 651 loss of linearity as the heating rate increases. Therefore, an intensive use of this procedure was made during the 2015 measurement campaign of CALMOS-2. Fig. 23 gathers 21 heating measurements obtained by both 652 calibration and zero methods on the 0-4 W.g⁻¹ range. All measurements are obtained by the 4-wire technique 653 leading to a very accurate power measurement (§ 4.2). Note that the zero method can require a significant 654 measurement time because, close to the equilibrium, after each power adjustment we are dependent to the 655 656 calorimeter time constant.

Fig. 23 gathers all results. The observed dispersion at very low heating rate (9 measurements under 700 mW.g⁻ ¹), is not considered as relevant. However, the figure shows that the discrepancy is within 2% up to around a 2.5 W.g⁻¹ heating range. Accounting experimental uncertainties (see § 16), we consider that no loss of linearity is highlighted and both methods are very close to each other up to that point. Beyond, the zero method provides values slightly higher than those obtained by calibration. That leads to a first experimental evaluation of the K_c correction factor to apply in equation (2), but limited to the 0-4 W.g⁻¹ range:

663

664

$$K_{\rm C}({\rm E_T}) \approx 0.00268 {\rm E_T}^2 + 0.00374 {\rm E_T} + 1$$
 (5)

665

666 Therefore, the correction is close to 4% at 3.5 W.g⁻¹ and 5 % at 4 W.g⁻¹.



668

Fig. 23. Results discrepancy between "zero method" and "K calibration" methods up to a 4 W.g⁻¹ nuclear heating rate.

670

The remaining problem is evaluating the loss of linearity beyond 4 W.g^{-1} , i.e up to heating rates at the nominal power. That requires a reference measurement on which we can refer to follow accurately the proportional increase of the local power close to the calorimeter vicinity (see § 17.6).

674 14. Comparison between CALMOS and previous calorimeters

As any device in the core is loaded before the reactor start-up and withdrawn only after shutdown, it is impossible to compare two devices at the same location during the same cycle. Therefore, to qualify the transposition of the previous calorimeters geometry to the CALMOS one, the inter-comparison has been made in the excore area where insertion or removal of devices are allowed when the reactor is operating.

A first comparison was carried out in various excore locations with the second mock-up of CALMOS (very similar to the final geometry) and classical calorimeters. Table 4 shows the inter-comparison with a standard equipment (as described in Fig.1), made at three different locations and at the mid-plane.

Excore	Calmos	Calor.	Ratio
location	(2 nd mock-up)	N°30	(Calmos/N°30)

	(W/g)	(W/g)	
J1	1.22	1.14	1.07
H10	0.96	1.04	0.92
H9	1.90	1.67	1.14

683

684 Table. 4 – Comparison of a previous calorimeter (N°30) and the CALMOS mock-up in excore locations at the core mid-plane.

685

Despite some differences between measurement systems (aluminum alloys, external diameter, and gas
volume), this comparison shows a relative good agreement within 15 % for a heating up to 1.7 W.g⁻¹.
Nevertheless, this comparison must only retained as an indication.

689 A global comparison was made also for incore locations.

690

Incore location	Orientation	5-stage (W.g ⁻¹)	CALMOS (W.g ⁻¹)	Ratio (Calm/ 5-stage)	
24	East	-	4.31	1.01	
South	West	3.55	-	1.21	
24	East	-	5.89	0.07	
North	West	6.12	-	0.96	
	North-East	7.20	-	1.10	
44	South-West	-	7.90	1.10	
64	East	10.7	-	0.00	
South	West	-	9.60	0.90	

691

692 Table. 5 – Comparison between CALMOS-1 and the 5-stage calorimeter for incore locations.

693

- Table 5 brings together some incore measurements, obtained by both the 5-stage calorimeter and CALMOS-1
- 695 along different cycles. Unfortunately, like in excore area, the comparison is only indicative:

696 - The reactor cycle is not the same, leading to a difference in the core loading,
697 - The location is the same, not the orientation,
698 - For 44 and 64 locations, measurements with CALMOS-1 are obtained just after the reactor start-up,

699 during the fast evolution of control rods,

Finally, differences in terms of geometry between both calorimeters are significant, essentially the gas
 volume and the presence of the external sheath for CALMOS-1.

For the three locations (24North, 44, and 64) the discrepancy does not exceed 10%, but is higher for the

24North location. Despite these differences, a relative good agreement is obtained between the two experimentaldevices.

705 15. Comparison with Monte Carlo calculations

- 706 15.1 Nuclear heating calculation scheme
- 707

708 To evaluate the nuclear heating in devices irradiated in the OSIRIS reactor, a three-dimensional coupled 709 neutron-photon calculation scheme has been set up. The calculation scheme architecture is presented in Figure 710 24. It is based mainly on the TRIPOLI-4 Monte Carlo transport code [10, 14, 20, 22] which has been extensively 711 validated against experimental results from neutron flux measurements performed in ex-core and in-core experiments [15, 18, 21]. As shown in Fig. 24, two-step TRIPOLI-4 simulations are needed to estimate the total 712 713 nuclear heating. The first one is a coupled neutron-photon critical simulation for the calculation of the nuclear 714 heating due to neutrons and prompt photons. The second one is a photon fixed- source simulation devoted for the 715 transport of the fission-product decay gammas. These two main steps need upcoming data: nuclear data which 716 represent the physics of simulations and irradiation data for setting up geometry and compositions of the core. 717 The calculation scheme uses nuclear data from the CEAV5_1.1 library, based mainly on the nuclear data library 718 JEFF3.1.1 [6].



Fig. 24. Nuclear heating evaluation scheme architecture based on TRIPOLI-4 two-step neutron-photon simulations.

722

720

40

723 The user either gives irradiation data (control rods positions, loading of experimental devices...) or computes

them by some deterministic calculation codes, in particular to obtain the isotopic compositions and the decay-

725 gamma sources of the OSIRIS fuel elements.

The five-stage calorimeter (see Fig. 1) and the CALMOS-1 device were modelled thanks to the technical

727 drawings as close as reasonably possible. Figures 25 and 26 show the axial and radial cross sections of the

- 728 TRIPOLI-4 geometry modelling of the CALMOS device.
- 729





731

732 Fig. 25. Axial cross section of a TRIPOLI-4 modelling of the CALMOS-1 device





736 Fig. 26. Radial cross section of the TRIPOLI-4 geometry modelling of the CALMOS-1 device

737

The modelling of the OSIRIS core geometry is also as close as possible to technical drawings. Each fuel plate is modelled in the lattice, control rods can be modeled at their real axial position, and the axial discretization of fuel element compositions can be modified.

To ensure Monte Carlo standard deviations less than 1% for all calculated tallies (for fluxes or nuclear heating
for neutrons, prompt and decay photons), each TRIPOLI-4 simulation was carried out using one hundred
processors during about ten days.

744

745 15.2 Results

746

Several comparisons between calculations and measurements were performed with the five-stage calorimeter
 and the CALMOS-1 experimental device when irradiated in different positions and during different cycles of the
 OSIRIS reactor.



Fig. 27. Axial profile of nuclear heating: calculation-measurement comparison for the CALMOS-1 device (64SW location, cycle F265)



- Fig. 28 Axial profile of the thermal neutron flux: calculation-measurement comparison for the CALMOS-1 device (64SW location, F265
 cycle).
- 757

Figures 27 and 28 show examples of typical calculated and measured axial profiles of nuclear heating (in the graphite sample) and thermal neutron flux (at the rhodium SPND location) for the CALMOS-1 device.

Results shown in these figures correspond to the F265 cycle and the 64 South-West experimental location,
normalized at the 70MW rated power.

762 Globally, we have good consistency between axial profiles of nuclear heating and thermal neutron flux 763 obtained both by calculations and by measurements. However, calculated values systematically underestimate 764 those measured. Discrepancies between calculation and measurements are about -15% at the core mid-plane 765 level. According to measurement uncertainties (see §16), we can consider that the calculated values are close to 766 measurement results within 2σ of measurement. A first possible reason of the observed discrepancies between experiments and simulations could be the lack of knowledge of the exact composition of the fuel elements 767 768 (determined by preliminary calculations). Another assumption could be a lack in terms of photon production nuclear data. The use of recent nuclear data evaluations such JEFF3.3 or ENDF/B-VIII will be investigated. 769

The nuclear heating calculation scheme is a useful tool for analysis and understanding. That allowed quantifying a "geometric effect" of 6% in terms of measured nuclear heating, between the five-stage calorimeter and CALMOS, when both devices are irradiated exactly in the same incore position.

773 Measurements performed by the two calorimeters cannot really be directly compared. This would have 774 required identical irradiation conditions in a same core i.e in terms of core loading and control rods positions (see 775 §14 and Table 5). Therefore, the simulation can be here a good help to perform a fully relevant comparison.

In addition, with the presented calculation scheme, we have access at each component taking part in the nuclear heating in the samples: Neutron energy deposition (about 15%), prompt photon energy deposition (about 65%), and decay photon energy deposition (about 20%). The most part of nuclear heating being due to photons (about 85%). The contribution of neutrons (essentially fast neutrons above 1 MeV) is not negligible.

781 **16. Uncertainties evaluation**

782 *16.1 Nuclear heating measurement*

783

Uncertainties associated to nuclear heating measurements are established when the preliminary calibration (2) is used in routine to perform the measurement (use of the K coefficient). However, such evaluation is made accurately only for the 0-4 W.g⁻¹ heating range, for which the zero method could be taken as reference. In that range, the K_c coefficient defining the loss of linearity could be evaluated quite precisely thanks to the 4-wire technique measurement (§ 13). We can consider that the K calibration, the $\Delta\Delta T$ temperature difference and the K_c correction coefficient of (2) are independent:

790 - The uncertainty associated to K depends on the cell slopes determination made during the preliminary 791 calibration (°C.W⁻¹). It is evaluated at 3.8 % at one standard deviation (1 σ) and is independent of the heating 792 level,

793- The ΔΔT value comes from the measurement of four temperatures. The uncertainty of each thermocouple794(calibration certificate) and those coming from the temperature measurement device, lead to total795uncertainties decreasing with ΔΔT rise: 12 % for 5 °C, 5.5 % for 11 °C and 1.9 % for 42 °C ΔΔT (1 σ),

796- Kc is evaluated thanks to the zero method and the CAST3M Finite Element Model [28]. The only797experimental process is kept in the present evaluation. Despite of the low measurements we could perform in798the core, obtained points fit well with the K_C curve in Fig. 23. An analytical approach allows assessing for799Kc a global uncertainty to 2 % (1 σ).

800

Heating W.g ⁻¹ (graphite)	0.5	1	2	4
$\sigma E_T/E_T$ at 1 σ (%)	12.7	7.0	5.4	4.7

802

804

805 Therefore, if the measurement is made with the preliminary calibration and within a 0 to 4 $W.g^{-1}$ range, expected 806 uncertainties are those of Table 6, as a function of the heating rate. Beyond a 4 $W.g^{-1}$ heating rate, the number of 807 available measurements did not allow to assess the definitive associated uncertainty. However, it is expected to be no 808 less than 15 % (1 σ) at 12 W.g⁻¹.

809

810 *16.2 Conventional thermal neutron flux*

811

812 Measurement of the thermal neutron flux thanks to the specific rhodium SPND requires to suppress the epithermal 813 response of the emitter (See § 7). That is the preliminary step to deduce the thermal neutron flux from the measured current. Therefore, the axial distribution of the epithermal flux/thermal flux ratio has been calculated by the TRIPOLI-814 815 4 Monte Carlo for the four typical experimental locations inside the core, i.e 24South, 24North, 44, and 64 (sub-816 locations for central 44 and 64 locations do not need to be distinguished in terms of spectra). The epithermal index 817 was calculated for all accessible altitudes with the calorimeter taking into account the real geometry (sensor + cooling 818 water layers + external sheath), the rods position and the actual core loading. Therefore, the following terms are taken 819 into account for the uncertainty evaluation: The calculated epithermal index by TRIPOLI4, 820

- 821 The thermal sensitivity of the rhodium SPND,
- 822 The measured intensity delivered by the SPND.
- Finally, the global uncertainty associated to the conventional thermal flux measurement by this rhodium SPND, in

824 CALMOS-2 configuration, is 8 % at 1 σ [17].

⁸⁰³ Table 6 – Uncertainties on heating measurements when deduced from the calibration and up to a 4 W.g⁻¹ heating rate

825 17. Characterization of the OSIRIS incore radiation field thanks to CALMOS devices

- 826 17.1 Comparison of heating and thermal flux profiles in the core
- 827
- The probe allows measuring separately the nuclear heating, the thermal neutron flux or both at the same time. Fig. 29 shows an example with 32 simultaneous measurement points, heating and thermal flux, performed in the 44NorthWest location during the F283 cycle with CALMOS-2, which allows observing behaviors of both
- 831 quantities along the scanning height (distributions normalized to unity).



833

- 834 Fig.29 Simultaneous measurement of heating and thermal neutron flux in the 44North-East location. Values are normalized to unity.
- 835

- At the core-moderator transition area centered around +320 mm/mid-plane, we observe a significant rise
 of thermal neutron flux (slope break), whereas this transition has no effect on the nuclear heating
- 840 evolution,

Fig. 29 shows that in the middle part of the core, distributions of heating and neutron flux have roughly thesame shape. However, differences of behavior are measured above:

841 Above the core (zoomed part on right scale of Fig. 29) the heating attenuation is quite different from the 842 thermal flux one. The thermal flux decreases faster than the heating, with a measured ratio of 2 each 40 mm against 80 mm for heating. 843 844 17.2 Fine analysis of thermal neutron flux behavior at the core-moderator transition 845 846 847 Fig. 30, which relates to the only thermal flux in absolute values, shows the possibilities offered by the HMI 848 automatic displacement system, allowing to refine deeply the obtained profiles for given areas in the total stroke. At 849 the core-moderator transitions (here in the upper part around +320 mm/mid-plane), the scan step has been reduced to

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the 11 mm minimum value, detailing the slope break in the thermal flux evolution.



46





855

856 17.3 Checking of consistency between both CALMOS devices responses

858 To check the consistency between CALMOS-1 and CALMOS-2 prototypes, both devices were loaded side-859 by-side (37 mm distance) in the two north positions of the 64 location during the F284 cycle (Fig. 31). Distributions of nuclear heating and thermal neutron flux were obtained with each device, but operated 860 861 separately, to avoid any influence on each other. During the scans, made at the 70 MWth nominal power, among 862 the four control rods surrounding the location, only BC3 (in brown) in the south part of the core is in operation and moving in the lower part of its stroke. Such configuration allows approximating same irradiation conditions 863 864 in north part of the 64 location. Fig. 31 illustrates also the CALMOS configuration with regard to the control rod 865 in operation.

866 Fig. 31 shows that heating profiles are almost identical, with a slight discrepancy in the mid-plane region in 867 which the CALMOS-2 signal (red curve) is around 3 % higher.

868



871 Fig. 31 - Distributions of nuclear heating obtained with both prototypes located in the 64 North location

872

873 Such results show that both devices give coherent responses in spite of a significant difference between

874 sensitivities (K calibration discrepancy is 16.6 % between each other).





Fig. 32 – Distributions of the thermal neutron flux obtained in 64 location with CALMOS-1 (blue) CALMOS-2 (red) and the MEREVER device
 (green) equipped with standard rhodium SPNDs

880

The comparison made for the thermal neutron flux is illustrated in Fig. 32. At mid-plane, measurements by CALMOS-2 (red curve) are also higher around 6 % than CALMOS-1 (blue curve). However, conversely to the heating, we note a thermal flux in CALMOS-1 remaining lower even in the fissile-moderator transition (brownblue transition on Fig. 32).

In addition, a static device called MEREVER is located also in the same 64SE location (in green). Used for many years in the OSIRIS reactor for thermal flux measurements and qualified, it is instrumented with 10 rhodium standard SPNDs (50 mm emitter length) inside an aluminum rod and allows to plot the flux profile with 5 axial measurements points covering +/-260 mm/mid-plane. In comparison with those obtained with CALMOS devices, we observe that profiles are very similar, except for low altitudes under the mid-plane (green curve), demonstrating that the thermal neutron flux at the MEREVER position is influenced by the rod position, closer to this device.

892 The global consistency in thermal flux measurement found between CALMOS and MEREVER devices, shows
893 that the 10mm short emitter SPND, especially developed for the CALMOS program, is qualified.



895 17.4 Surveillance of the heating evolution during a reactor cycle

To follow the evolution of the heating distribution along the entire reactor F283 cycle, the CALMOS-2 device is placed inside the 44North-West location. Eight different scans are successively performed (reactor power unchanged), spread from the beginning of the cycle to the reactor shutdown.

900



Fig. 33 – Follow-up during the whole F283 reactor cycle of the nuclear heating distribution obtained with the CALMOS-2 device placed in the 44
 North-West location. Three distributions corresponding to three representative control rods positions along the cycle.

905

901 902

The three most relevant distributions obtained are plotted in Fig. 33, well representative of the whole control rods evolution during the cycle going from the position "rods inserted" (blue curve) to the rods position at shutdown time, with one rod completely extracted (red curve).

909 The complete recording along the cycle permits to measure at this location, not only a 12 % increase of the

- 910 heating rate at the core mid-plane, but also to observe and to measure the axial displacement of the position of the
- 911 maximum flux plane (moving from -40 mm, 0 and moving down again -40 mm/MP at shutdown time).

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- 912 Such information is of major importance to predict the total heat deposition in any experimental device in the 913 core.
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17.5 Heating distribution with very high definition

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917 To measure a relevant distribution in the core (heating or neutron flux), the control rods axial displacement 918 (rise movement) must be very short during the whole scan duration, i.e involving a negligible effect on measured 919 distributions. That can be the case only at mid-cycle, because rods are in the middle of their mechanical stroke, 920 therefore at their maximum efficiency. Fig. 34 shows an example of a complete scanning, covering the whole 921 calorimeter stroke, performed with the 11 mm minimum scanning step, offering the best definition. Taking into 922 account the time response of the calorimeter (2min 30s), added to the time required to move the probe, the total 923 measurement time is 4min 30s per point. A 7 h 30 min scanning time is required to perform the 97 measurement 924 points necessary to cover the whole calorimeter stroke. That shows the ability of such calorimeter, thanks to the 925 automatic displacement system, to refine the profile definition as deeply as necessary.

926 Obviously, the measurement is a compromise between the definition and the acceptable scanning time. To 927 keep relevant, the modification of the radiation field must be considered as negligible over the total time required 928 to draw its distribution.





Fig. 34. Test of the highest definition. Nuclear heating distribution in the 64North-Esat location during the F284 cycle. The whole scanning height is
covered by 97 measurements points for a total scanning time of 7 hr 30 min.

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935 17.6 Reactor start-up monitoring

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For monitoring the complete divergence of the reactor during the F284 cycle, the CALMOS-2 calorimeter (sample cell) is placed at the core mid-plane altitude before start-up. The 64-water box loading is as described in Figs. 31 and 32, with CALMOS-2 in 64North-East and the MEREVER device in 64South-Est location, with only a 37 mm distance between both devices. During the reactor power rise, from the divergence to nominal power, the only two BC6 and BC4 control rods are operating. Other rods are either fully up or fully inserted i.e without any effect on the axial heating distribution. Relative positions between these two rods and devices appear in Fig. 32.

Among the ten rhodium SPNDs inside the MEREVER device, two SPNDs (N°5 and N°6) are side by side and exactly at the core mid-plane i.e very close to the sample cell of the calorimeter. During the power rise, we can make the following assumptions regarding positions of the sample cell and that of these two SPNDs: During the power rise, up to around 50 MW, first the BC6 rod is moving up in the upper part of its stroke
between 430 and 550 mm, i.e in an area clearly above the mid-plane. Then, the second rod is moving up in
the lower part of its stroke, from 50 MW to nominal power, between 0 and 170 mm i.e clearly under the
mid-plane. These two areas are far away enough from the core mid-plane vicinity to consider that, in a
first approach, there is no significant effect on the flux gradient between 64NE and 64SE positions,

- As there is no change of environment at the mid-plane vicinity (control rods in operation, static position of
 the CALMOS calorimeter), the spectrum does not change with reactor power i.e the gamma spectrum, the
 neutron spectrum and the ratio among them remain unchanged.
- 955

Such situation allows assuming, and that was the researched objective, that the nuclear heating (CALMOS-2 monitoring) and the thermal neutron flux (MEREVER monitoring) follow the same relative evolution from the divergence to the nominal power. Therefore, signals recorded from N°5 and N°6 SPNDs of the MEREVER device can be taken as reference to monitor the calorimeter linearity from 0 to 70 MW.



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- 963 Fig. 35- CALMOS-2 in 64North-East location: Recording of nuclear heating evolution along the F284 reactor start-up from 0 to 69.37 MW. The
- 964 MEREVER device is in 64South-East location. The reactor power rise is made with 9 steps allowing the recording of stabilized signals.
- 965

Fig. 35 shows the evolution of the measured heating (deduced from the calibration) with the CALMOS-2 966 967 calorimeter along the whole F284 OSIRIS divergence. Nine steps during the power rise allow to record stabilized 968 signals of the calorimeter and those provided by SPNDs. The results processing allows deducing a second estimation of the linearity loss for heating measurements up to the 969 970 nominal power. To do it, the heating measured at 5 MW is taken as reference then, all other measurements are recalibrated thanks to the relative evolution of MEREVER SPNDs. We note that the obtained correction is identical 971 972 whatever the SPND taken as reference (N°5 or N°6). Fig. 36 shows the deduced experimental evolution of $K_C(E_T)$ (ratio between recalibrated and measured values) between 0 and 70 MW i.e covering the 0 to 11 W.g⁻¹ heating range: 973 974 975 $K_{\rm C}({\rm E}_{\rm T}) \approx 0.0006 {\rm E}_{\rm T}^2 + 0.0082 {\rm E}_{\rm T} + 1$ (6) 976 977 Results show that the correction is not negligible and close to 10 % at 8 W/g and close to 14 % at 10 W.g⁻¹.



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981 Fig. 36 – CALMOS-2 at the core mid-plane in the 64North-East location: Loss of linearity up to the nominal power during the F284 OSIRIS start-

982 up. Recalibration of heating measuremets thanks to the MEREVER rodium SPNDs in close vicintity.

On the same figure are plotted also, the first experimental evaluation of $K_C(E_T)$ deduced from the zero method comparison (see § 12). Fig. 36 shows that the trend previously obtained, for the correction coefficient limited to a 0-4 W/g heating range, is in correct agreement with these latest measurements.

To reinforce such result, the processing of measured heating levels has been made also with the reactor power taken as reference. In that case, we need to consider that any variation of the reactor global power involves a same relative variation of the local power at the mid-plane vicinity. The same trend is obtained with a correction close to 14 % at 10.4 W.g⁻¹ against 15 % found in Fig. 36. Therefore, for nuclear heating measurements obtained from the calibration in CALMOS-2, the K_C expression of (6) is applied.

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993 17.7 Recording of the residual power decay after shutdown

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The CALMOS calorimeter has been tested also to follow the residual power decay after the reactor shutdown. Fig. 37 shows a 10 hours recording performed after shutdown at the end of the F283 cycle. Just after shutdown, the residual power drops sharply to almost 10% of the nominal value, before decreasing more slowly. After an 8 hours elapsed time, the measured $\Delta\Delta T$ is only 1.63 °C leading to a residual heating level to around 150 mW.g⁻¹. At this time, the reactor procedure requires to stop the primary pumps, involving a change of cooling conditions for the calorimeter, switching from the forced convection to the natural convection regime.







Fig. 37 – Decay of the residual power after the end of the F283 OSIRIS cycle. Recording during 10 hours after shutdown. The signal behaviour
 before and after the change of cooling regime appears in the zoomed part (upper right corner).

The zoomed part in Fig. 37 (upper right corner) shows that the signal is disturbed at the pump stop and the noise becomes stronger in natural convection. However, the signal decay is still coherent because, after this event, it follows the same slope of decay, demonstrating that the calorimeter remains reliable even in natural convection regime, established inside the water gap between the calorimetric probe and the internal surface of the sleeve. This result is of major importance because that shows that the CALMOS calorimeter keeps its ability to monitor the residual power independently of OSIRIS thermohydraulic conditions.

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1014 17.8 Establishment of the core residual power distribution 18 days after shutdown

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1016 At the end of the F284 cycle, the monitoring of the power residual decay was extended up to 18 days after the 1017 reactor shutdown. At this time, when the CALMOS probe is located at the core mid-plane, the measured $\Delta\Delta T$ is

1018 reduced to 0.31 °C leading to a nuclear heating rate of about 29 mW.g⁻¹ (C).

1019 Despite this very low signal, a scanning is attempted to establish the axial distribution of the residual power in 1020 the core, in 64North-East location, with a step reduced to 22 mm and a 5 min measurement time at each altitude. 1021 Fig. 38 shows the obtained recording of $\Delta\Delta T$ raw values. Despite some discrepancies, the nuclear heating 1022 distribution is still coherent and measurable.





1024 1025

Fig. 38 – Axial distribution of raw ΔΔT values of the CALMOS-2 calorimeter, in the 64NE expertimental location, 18 days after shutdown of the
 F284 OSIRIS cycle.

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We remind that the study of the calorimetric cell response shows clearly that, even though $\Delta\Delta T$ is the only quantity well representative of nuclear heating, the relative distribution can be deduced from each cell ΔT as demonstrated in Fig. 22. Taking advantage of this property, for plotting the complete curve of the final residual power in the core, we retain only the absolute measurement of heating at the core mid-plane. Then, the rest of the distribution is deduced from the relative response of the " Δt sample" showing a much weaker dispersion. Results appear in Fig.39.



Fig. 39 – Axial distribution of the core residual power, plotted by the CALMOS-2 measurement device 18 days after shutdown of the OSIRIS F284
 cycle.

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1041 That demonstrates that it is of prior importance, during the manufacturing, to choose the thermocouples 1042 accurately to enable the very low ΔT measurements. They must provide the lowest dispersion as possible in a 1043 same temperature field (importance of preliminary calibration). Each thermocouple embedded in the cell base 1044 ("cold temperature") is calibrated with two reference points, melting ice and boiling of water, whereas each 1045 thermocouple embedded in the pedestal ("hot temperature") is calibrated with four references, boiling of water 1046 and melting points of Tin (232 °C), Lead (327 °C), and Zinc (420 °C). After selection, the lower the dispersion is, 1047 the lower the required correction is (or negligible) for very low heating rates. For the four thermocouples of the 1048 CALMOS-2 calorimetric cell, the preselection led to a very low discrepancy among them, measured to 0.2 °C 1049 over the 420 °C total range of the calibration. 1050

Obtained results show the ability of the CALMOS device to establish the nuclear heating distribution in the core, from the nominal power up to after 18 days of cooling time after shutdown. Therefore, we can consider that the calorimetric cell offers 3-decade dynamic range.

1053 **18. Mutual perturbation between the two CALMOS devices in a same experimental location**

Inside an experimental reactor, it is essential to check that the measurement we are performing is relevant. That requires checking that any potential modification in the environment (control rod, experimental device...) does not affect significantly the radiation field we are measuring. That is the case if we want to use the two CALMOS devices in the same water box to characterize the same location. Moving down or moving up the mobile equipment of a system along its main axis can disturb the other one.

1059 During the last F284 cycle, CALMOS-1 and CALMOS-2 were placed side-by-side, respectively in the

1060 64North-West and the 64 North-East locations of the core.

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1064 Fig. 40 – CALMOS-2: Discrepancy in nuclear heating measurement among the 4 measurements corresponding to the 4 positions of the CALMOS-1

1065 probe insertion in the core.

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1067 1068

Fig. 41 – CALMOS-2: Discrepancy in thermal neutron flux measurement among 4 measurements corresponding to 4 positions of the CALMOS-1
 probe insertion in the core.

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Four successive complete scanning were performed with CALMOS-2 (nuclear heating + neutron flux measurements, 88mm scan step each) for four fixed positions of the CALMOS-1 calorimetric probe, corresponding to the rest position (+1001mm), the entrance of the core (+320 mm), the core mid-plane (0mm), and at the bottom (-139 mm). These four positions are representative of the potential perturbation.

1076 Figs. 40 and 41 gather all maximum measured discrepancies, evaluated at eight altitudes of CALMOS-2 1077 calorimeter, for both heating and neutron flux measurements. Results show that, inside the core, the maximum 1078 perturbation involved by the presence of the CALMOS-1 probe in CALMOS-2 vicinity remains very low, 1079 respectively less than 3 % for heating measurement and less than 4% for the thermal neutron flux. Considering 1080 experimental uncertainties, such results led us to assume that, in first approximation, any scanning performed by 1081 one displacement system does not disturb the measurements acquisition carried out by any other similar device, 1082 for both nuclear heating or for thermal neutron flux measurements. Both devices can work together 1083 independently.

1084 **19. Conclusion**

1085 From the first idea in 2002 to the completion of a real qualified measurement prototype suited to an MTR 1086 reactor, followed by the comprehensive analysis of obtained results, the CALMOS R&D program took place over 1087 a period of 15 years. The development and the qualification of the whole measurement system required a 1088 succession of thermohydraulic, neutron, and mechanical studies. Among them, the modelling of the calorimetric 1089 probe, answering to OSIRIS incore thermohydraulic conditions, permitted to design a cell geometry well suited to 1090 nuclear heating rates inside the core. Two mock-ups tested in the excore area allowed to validate the 1091 measurement protocol for this innovative superimposed geometry. Then, the transposition to incore 1092 measurements needed the development of a specific displacement system to obtain axial nuclear heating 1093 distributions inside the core while ensuring the cooling conditions of the probe and matching with OSIRIS safety 1094 requirements. The whole measurement campaign in real incore conditions by both CALMOS devices ran from 1095 2013 to 2015, covering 11 reactor cycles, around 22 days each.

1096 About the calorimetric probe working, the main results are as follows:

1097 - Using the zero method, almost independent of the calibration phase, allows reducing the number of 1098 assumptions in the heating measurement process. The most important improvement brought in the last 1099 version is the implementation of the 4-wire technique in the reference cell, which allows suppressing any 1100 assumption about the heater element ageing. That enables to reduce the associated uncertainty to heating 1101 measurements at 4.7 % at 1 σ for a 4 W.g⁻¹ (C) heating rate,

The entire absolute axial distribution in the core can be obtained by performing a single absolute
 measurement at a given altitude, the rest of the curve is deduced thanks to the relative response of any of
 the cells,

The zero method is used as a reference measurement for the probe non-linearity assessment.
 Determination of the cells slope in °C.W⁻¹ shows that the response is almost linear within a 0-5 W.g⁻¹
 heating range, with a measured discrepancy not exceeding 4 %,

- The global sensitivity has around a 3-decade dynamic range, offering the possibility not only to follow the
 core residual power up to 2 weeks after shutdown, but also after this cooling time to draw its axial
 distribution.
- 1111

The CALMOS-1 device has been tested during ten reactor cycles. Despite the short irradiation campaign of the CALMOS-2 upgraded version, carried out during the last three cycles of the OSIRIS reactor due to its final shutdown scheduled in December 2015, many tests were performed in different core conditions. That highlighted the various possibilities offered by the new displacement system when associated with the complete automatic driving system to characterize the incore radiation field. Among major results, we note:

- The automatic probe mobility, programmed through a Human Machine Interface thanks to a specific software, allows obtaining very well defined profiles both for nuclear heating and for thermal neutron flux measurements. The scanning step and partial and/or total measurement times can be adjusted as required, focused on given target regions and to the reactor conditions in order to keep a relevant measurement with regard to the control rods evolution,
- The programming of measurement sequences helps a lot in monitoring the radiation field evolution
 throughout the reactor cycle, because it can be adapted to reactor conditions,
- For the most critical situation, a CALMOS device closer as possible to the control rod in operation, the complete withdrawal of the mobile equipment from its external sheath induces a 45 pcm positive reactivity on the core. Therefore, the adopted displacement speed of 1 mm.s⁻¹ in the core involves a reactivity effect less than 0.1 pcm.s⁻¹, fully compatible with reactor control rules.
- 1128

However, the global feedback of the CALMOS program leads us to some improvement perspectives. In that program, the main purpose was to obtain a calorimeter answering to a very large nuclear heating range, ranging from 13 W.g⁻¹ at the core mid-plane at nominal power to the residual heating at 1 m above the core. Therefore, the sensitivity was a compromise. It must be high enough for a measureable $\Delta\Delta T$ in the lower part of the heating range, but sufficiently low at high level to limit absolute temperatures in the cell, because leading to heat losses by radiation and conduction in gas. Therefore, in the upper heating range, the loss of the linearity is significant. So, as main prospect, another design would be optimizing the geometry so as to limit the sensitivity, therefore the maximum temperature of inner walls inside the cell, to suppress as drastically as possible heat losses by radiation, which are very difficult to assess by calculation and to suppress in the design.

Secondly, even though it cannot be used in routine for establishing any axial distribution, results showed the importance of the zero method, considered as the best approach of an absolute measurement. That leads to the second major improvement, which would be to design a heater element able to simulate the energy deposit up to highest heating levels in the core, to perform an absolute measurement for assessing more accurately the loss of linearity when using the calibration coefficient.

The intensive use of CALMOS-2 in the core, cumulating a total 70 hours automatic scanning time, has demonstrated its reliability for OSIRIS in-core conditions up to a 12 W.g⁻¹ heating rate and up to a 2.5×10^{14} n.cm⁻².s⁻¹ thermal neutron flux. While meeting the reactor safety requirements, the CALMOS device becomes an operational equipment suited to the surveillance and the qualification of the incore radiation field in an MTR reactor, a key data for the dimensioning and the surveillance of any experimental device irradiated inside.

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