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DIGITAL IN-LINE HOLOGRAPHY FOR NEAR FIELD OBSERVATION OF LIQUID-LIQUID FLOWS UNDER ASTIGMATIC CONDITIONS

Matthias PL SENTIS¹, Fabrice LAMADIE^{1*}, Laurent BRUEL²

¹ CEA, DEN, DTEC, SGCS, F-30207 Bagnols-sur-Cèze, France

² CEA, DEN, DTEC, SEPE, F-30207 Bagnols-sur-Cèze, France

*Corresponding author: fabrice.lamadie@cea.fr

Abstract

Several processes used in nuclear research and industry are based on liquid-liquid extraction. This method is designed for selective separation of products in a mixture.

As the transfer occurs at the contact surface between both phases, the characterization of the dispersed phase of the emulsion (size distribution of droplets, shape, etc.) is fundamental. Numerous imaging techniques can be used to measure, but one of them, digital holography (DH) is particularly relevant as it determines simultaneously the size, shape and 3D positions of particles using a single camera. Because the droplets are millimeter size, a near-field diffraction regime is observed and adapted numerical solutions are required. In a previous work [1], an effective focusing method has been validated on an experimental cuboid-shape setup designed to produce droplets of known diameter and velocity as well as an unknown polydisperse droplet population. However, the standard shapes of liquid-liquid extraction apparatus are cylindrical, inducing a strong astigmatism and preventing the direct use of classical focusing methods.

In this communication, we proposed a survey of two approaches, based respectively on Generalized Huygens-Fresnel Transform (GHFT) and Fractional Fourier Transform (FrFT), which allows overpassing this issue. Using these tools induce a supplementary quadratic phase term, which must be corrected in order to use automatic focalisation methods.

1 Introduction

Digital Holography (DH), is well-known for allowing complete reconstruction of information about a 3D Flow in a single shot. Accordingly, DH has been increasingly used in a broad spectrum of applications, such as holographic PIV/PTV [2–4], live cell imaging [5] or holographic microscopy [6]. More recently DH has been directly applied to a dispersed phase for the characterization of particle motion in a two-phase flow [7]. Finally it has been demonstrated that DH can be used for measuring size and 3D positioning of fast-moving droplets and bubbles in air-water and oil-water mixture flows [8].

As proved by Lamadie *et al.* [1], DH involves a very simple and stable measurement setup particularly suitable for the characterization of liquid-liquid flows. Feasibility of such measurements in cuboid-shape geometry has been demonstrated [1]. However, several standard devices

designed for chemical engineering (for instance pulsed columns, centrifugal extractor, etc.) exhibit a cylindrical shaft inducing astigmatism. Due to this latter, the classical hologram simulation and focusing methods become inadequate.

Two main approaches allow taking into account this astigmatism. The first one, introduced by Collins *et al.* in 1970 [9] is a general expression of the Rayleigh-Sommerfeld integral, including optical system in paraxial approximation thanks to an ABCD transfer matrix. It gives the relationship between the output and input of the complex amplitude distributions of the light field passing through an ABCD optical system. In this context, Rayleigh-Sommerfeld diffraction integral could be analytically expressed, as proved by Verrier *et al.* [11] or used through a generalised Huygens-Fresnel propagator as described by Palma *et al.* [12]. The second one, introduced by Ozaktas *et al.* [10], operates the Fractional Fourier Transform (FrFT) properties. According to [10], all quadratic phase systems (QPS) can be interpreted as a magnified FrFT with a phase curvature.

In this communication, we propose a comparison of the two approaches on numerical and experimental astigmatic holograms. The first paragraph is dedicated to hologram's numerical simulation, both with GHFT and FrFT. Regarding automatic focalisation, a key issue is the quadratic phase correction, it will be introduced in the second paragraph. Finally some experimental results will be presented.

2 Hologram simulation in anamorphic optical system

In DH, several focusing methods involve a numerical model for hologram's simulation. In free space, this point is easily achieved by using Fresnel Transfer Function or Impulse Response Propagator [13]. Switch between the two propagators is related to sampling of the phase of the propagator at the edge of the field. As mentioned in the introduction, in the paraxial approximation, all optical systems can be described by an ABCD matrix. For a DH setup, regarding one particle, we have to consider two propagations along the optical axis z , one between the light source and the particle (represented by transfer matrices $ABCD_{1,x}$ and $ABCD_{1,y}$) and one between the particle and the sensor (represented by transfer matrices

$ABCD_{2x}$ and $ABCD_{2y}$), allowing to consider different optical characteristics along the x and y axes.

According to the Collins formula, the wave amplitude A_z after propagating in such system [9, 12] is described by:

$$A_z(x, y) = \frac{\exp(ikz)}{i\lambda\sqrt{B_x B_y}} \iint_{\square^2} A(u, v) \exp\left(i\pi \frac{A_x u^2 - 2xu + D_x x^2}{\lambda B_x}\right) \times \exp\left(i\pi \frac{A_y v^2 - 2yv + D_y y^2}{\lambda B_y}\right) dudv \quad (1)$$

with $A(u, v)$ the complex amplitude distributions of the light field in the z-particle position, A_x, B_x, C_x, D_x and A_y, B_y, C_y, D_y the coefficients of the ABCD transfer matrix in x and y direction respectively. λ is the wavelength, z the distance of propagation along the optical axis and k the wave number.

Considering the classical transmission model used in DH, which assimilates a droplet to an opaque disk (hypothesis acceptable for micrometric particles but not for millimeter particles [1]), the simulation of the recorded intensity is performed by three simple operations:

- (i) propagation of the incident wave from the source to the particle plane using equation (1) and $ABCD_x = ABCD_{1x}$, $ABCD_y = ABCD_{1y}$ matrices,
- (ii) multiplication of the calculated field, at z-particle position, by the particle transmission function,
- (iii) propagation of the resulting field from the particle plane to the sensor position using equation (1) and $ABCD_x = ABCD_{2x}$, $ABCD_y = ABCD_{2y}$ matrices.

As demonstrated, by Verrier *et al.*, $A(u, v)$ can be calculated thanks to an analytical solution by considering an incident gaussian beam profile and a gaussian decomposition of the opaque particle [11]. The Figure 1(a) shows the intensity recording by a sensor calculated with this analytical solution for an experimental setup with a cylindrical curvature along the x-axis detailed in [1].

According to Palma *et al.*, GHFT integral can be expressed as a Fourier transformation. In this case, Eq.1 can be rewritten as :

$$A_z(x, y) = \exp\left(\frac{i\pi C_x}{\lambda A_x} x^2 + \frac{i\pi C_y}{\lambda A_y} y^2\right) \times F^{-1}\left(\sqrt{A_x A_y} \exp\left(-i\pi\lambda(A_x B_x f_x^2 + A_y B_y f_y^2)\right) F(A(u, v))(x, y)\right) \quad (2)$$

with $f_x = x/(\lambda A_x B_x)$, $f_y = y/(\lambda A_y B_y)$ the spatial frequencies along x and y respectively.

Required sampling conditions, regarding Shannon theorem, bring sampling issues that can be addressed by considering a general system taking into account the two initial ABCD systems. A comparison between Verrier approach and GHFT approach is presented in Figure 1.

The results are very close regarding the intensity profile comparison in Figure 1(c). Finally, as demonstrated by Ozaktas *et al.* [10], all QPS can be interpreted as a magnified FrFT with a phase curvature. This third approach has been applied successfully for free space propagation and still under study for ABCD systems.

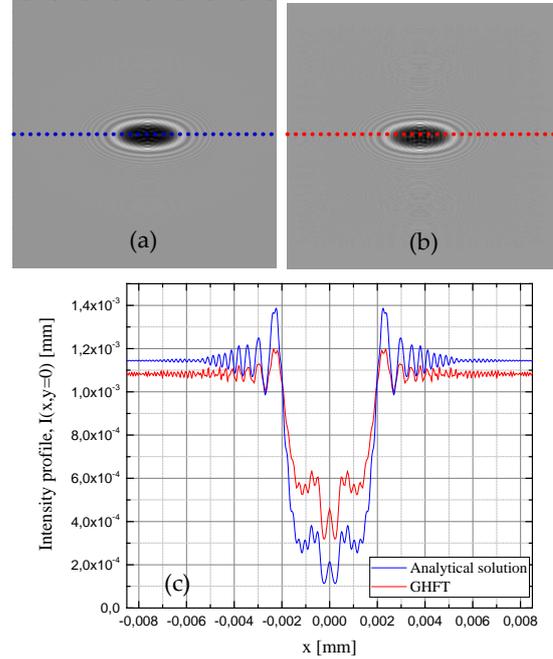


Figure 1: Intensity recorded for a 1mm diameter TPH droplets in water (experimental setup described in [1]) - Analytical solution (a) - GHFT (b) and (c) Intensity profile comparison

3 Hologram focusing

Positioning on the optical axis (z-axis) is certainly one of the most critical aspects of DH. The challenge is to find the optimum focus plane for each particle detected in the hologram. Various automatic detection criteria have been reported in the literature, while some authors prefer empirical methods based on visual analysis of the reconstructed holograms. In cuboid-shape configuration, the most accurate positioning is obtained using exclusively the imaginary part of the reconstructed field. For instance, the position of the particle could be determined by using the minimum of the variance of the imaginary part of the reconstructed field in the neighbourhood of the particle [14].

Coëtmellec has proved that hologram restitution in anamorphic optical system can be successfully performed with FrFT [15]. As an example, the Figure 2 shows a cross section of modulus of the reconstructed field of an experimental hologram with FrFT at several propagation distances. For each reconstruction plane, fractional orders are calculated according to Verrier [11] which allows to reduce the computation time. The expected refraction effect for particles with refractive index higher than one,

i.e. a “hot spot” close to the particle center position, is clearly observed (Figure 2).

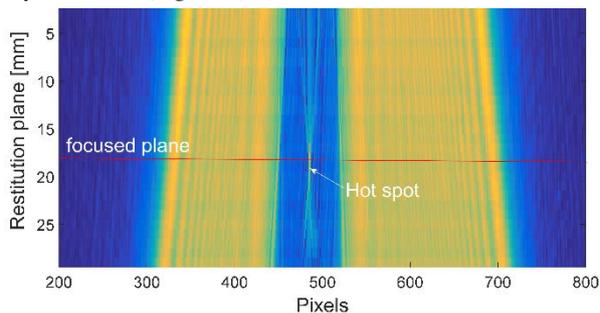


Figure 2 : Cross section of modulus of the field reconstructed with FrFT (the section plane passes through the center of the droplet and contains the z axis)

An example of the imaginary part of the reconstructed field with FrFT is displayed in Figure 3(a). The figure exhibits additional quadratic phase inherent to FrFT. The variance induced by this quadratic phase is far more significantly than the variance induced by the phase of the droplet, preventing the use of the focus function. Figure 3(b) shows the imaginary part of the reconstructed field with FrFT after quadratic phase corrections. The variance induced by the quadratic phase has totally disappeared and focalisation, thanks to a merit function, remains available as proved in Figure 4. This process is validated for isolated droplet hologram and under study for polydisperse droplets distributions.

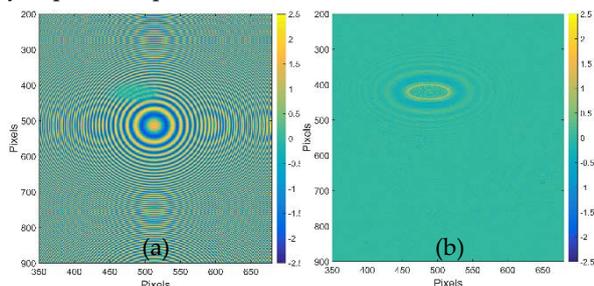


Figure 3: Imaginary part of the focused field by FrFT at z = 40mm with (a) supplementary FrFT phase (b) phase correction

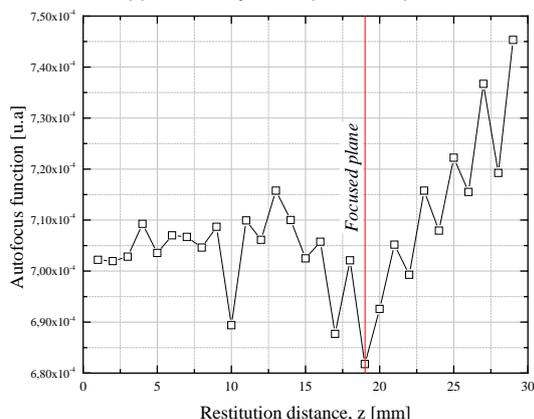


Figure 4: Autofocus function of the imaginary part of the reconstructed field versus the reconstruction distance z — the local minimum indicates the focus position

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