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VERTICAL DISTRIBUTION OF THE VOID FRACTION, USING X-RAY ATTENUATION MEASUREMENTS, FOR DIFFERENT FLOW REGIMES IN A HORIZONTAL PIPE

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ABSTRACT

METERO is an experimental facility built by the French Atomic Energy Commission (CEA) aimed at studying adiabatic air-water flows in horizontal pipes. The physical insight and the experimental data provided by METERO experiments support the validation of MCFD (NEPTUNE CFD) and System (CATHARE-3) codes as a part of the NEPTUNE project developed jointly by EDF, CEA, AREVA NP and IRSN. [Bottin et al International Journal of Multiphase Flow 60 (2014) 161–179] have proposed a flow map of the different regimes encountered in the METERO experiments, i.e. stratified flows, slug flows, plug flows, stratified dispersed bubbly flows and dispersed bubbly flows. Following this work, we investigate the vertical distribution of void fraction integrated horizontally using X-ray attenuation measurements.

After a description of the experiments and the measurements' method, we discuss the evolution of the vertical distribution of the void fraction in horizontal pipes and derived statistics such as the ratio of the air and water phase velocities. Different flow regimes and their transitions (e.g. slug, plug, and bubbly regimes) are explored by varying the water and air superficial velocities.

KEYWORDS

FLOW REGIME, X-RAY MEASUREMENTS, VOID FRACTION, HORIZONTAL PIPE

1. INTRODUCTION

Vertical bubbly flows have been extensively studied, e.g. [1, 2, 3, 4, 5] whilst less literature can be found about multiphase flows in horizontal pipes, e.g. [6, 7, 8]. The dynamic of multiphase flows in horizontal pipes differs from the one observed in vertical pipes due to the fact that gravity is perpendicular to the mean flow and not parallel. The buoyancy forces tend to have bubbles moving up. They then support the accumulation of air in the upper part of the pipe which favours the coalescence of bubbles. The turbulence is amenable to disperse bubbles and to provoke the coalescence and break up of bubbles. The competition between buoyancy and turbulent forces in horizontal pipes results in different flow regimes from stratified flows to dispersed bubbly flows [8].

The pipes' lengths of nuclear power plant are generally (primary circuit) about ten times their diameters. Potential multiphase flows in such short pipes would not reach a fully developed stage. The knowledge, modelling and simulation of transient horizontal two-phase flows are therefore important for safety studies of nuclear power plant. Existing literature and experimental data need to be completed by experiments in relatively short pipes.

METERO is an experimental facility built by the French Atomic Energy Commission (CEA) aimed at studying adiabatic air-water flows in horizontal pipes. The physical insight and the experimental data provided by METERO experiments support the validation of MCFD and CATHARE-3 codes as a part of the NEPTUNE project developed jointly by EDF, CEA, AREVA NP and IRSN. The main purpose of

METERO experiments is to help improving the accuracy of numerical tools by providing new physical insights and data for validation.

Measurements using X-ray attenuation are amenable to indicate the structures of multiphase flows where the phases' attenuations are different, e.g. [9, 10, 11, 12, 13]. The void fraction within air-water flows can then be measured using X-ray attenuation. Using such measurements, the present manuscript focuses on the vertical distribution of the void fraction and deduces physical quantities such as air and water phase velocities.

The manuscript is articulated as follows. First the experimental rig, the measurement methods and the flows' parameters investigated are introduced. Then results obtained from measurements performed over different flow regimes and at different longitudinal positions ($10.4D$, $20.6D$ and $41.3D$) are presented and discussed.

2. EXPERIMENTAL DESCRIPTION

2.1. Experimental setup

METERO is an experimental rig dedicated to the study of turbulent mixing of air and water in horizontal flows. Extensive descriptions of METERO can be found in [14, 15, 8].

The pipe is of circular shape and is assembled from different modules made in Perspex. The Perspex walls are 10mm thick. The inside diameter of the pipe, i.e. the diameter of the flow cross section, is $D=100\text{mm}$. D is chosen as the reference length scale. Dimensionless length scales, according to D , are noted with a superscript star, e.g. $y^* = y/D$. Fig. 1a is a photo of METERO's test section.

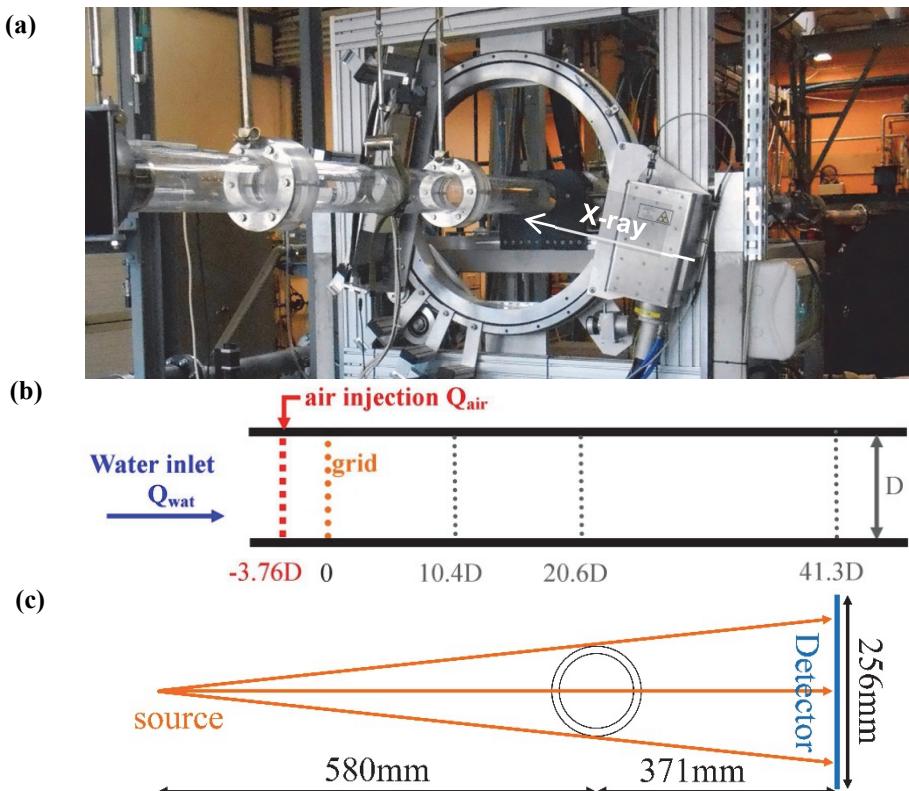


Figure 1: (a) photo of the test section with the encapsulated X-ray source and of the X-ray detector mounted on a rotating device; (b) schematic of the test section with relevant longitudinal positions; (c) schema of the X-ray source and the angular distribution of X-ray beams crossing the test section.

The water flow rate within the pipe section is noted Q_{wat} . It is measured using either MHD (electromagnetic) or Coriolis flow meters according to the flow intensity. At the entrance of the test section, the air is regularly injected in space over 37 nozzles with inside diameters of 1.2mm. The air flow rate is measured using mass flow meters and is noted Q_{air} . 3.76D downstream the injection, a turbulent grid (mesh of 2.71mm with wires of 0.71mm diameter) mixes the flow and breaks air bubbles. The longitudinal (or flow) direction along the pipe is noted x and the vertical direction is noted y. The position of the grid is chosen as the x axis origin. The axis of the pipe is chosen as the origin of y. Fig. 1b illustrates these positions and notations. Downstream the test section, a water tank at atmospheric pressure is used to separate the air from the water. This black tank is visible on the right of figure Fig. 1a.

The X-ray beams are emitted from a localised source at 160kV and 18.75mA. It is collimated so as to illuminate a plane perpendicular to the axis of the test section. Fig. 1 shows a photo of the encapsulated source and the detector along with a schematic of the emitted X-ray beams. The X-ray intensity is recorded by the Hamamatsu C9750-10TC detector. This linear detector possesses 1280 pixels of 0.2mm with a 12bits depth. The dark image of the detector (signal with X-ray turned off) is removed from the recorded signal. The resulting signal level is proportional to the amount of X-ray received by the detector.¹ The X-ray source and detector are mounted on a rotating system so as to vary the angles of the measurements.

2.2. Void fraction measurements using X-ray attenuation

Void fraction measurements using X-ray attenuation relies on the difference of attenuation of the incident X-ray beam between the gas and liquid phases.

The attenuation of a X-ray along a material line is modelled as:

$$dI_X = -\mu I_{X_0} dx \quad (1)$$

This leads to Beer-Lambert law for X-ray attenuation for a given material

$$I_X = I_{X_0} e^{-\mu x} \quad (2)$$

I_{X_0} is the initial intensity of the beam, I_X is the intensity of the X-ray beam transmitted through the material, μ [in m-1] is the linear attenuation of the material and x [in m] is the thickness of the material crossed by the X-ray beam.

Successive attenuations through different materials lead to successive multiplications by $e^{-\mu_i x_i}$ where $\mu_i x_i$ is the attenuation coefficient of the i^{th} material crossed. The X-ray intensity transmitted through successive elements is:

$$I_X = I_{X_0} \prod_i e^{-\mu_i x_i} \quad (3)$$

In METERO experiments, the X-ray successively crosses the air, the Perspex, the flow, the Perspex and the air before reaching the X-ray detector. This is illustrated in Fig. 2. The attenuation of the X-ray beam can then be written as:

$$I_X = I_{X_0} e^{-(\mu_{\text{air}} x_{\text{air}} + \mu_p x_p)} e^{-(\mu_w x_w + \mu_b x_b)} \quad (4)$$

where $\mu_{\text{air}} x_{\text{air}}$ is the attenuation from the air outside the test section, $\mu_p x_p$ is the attenuation due to the Perspex, $\mu_w x_w$ and $\mu_b x_b$ are respectively the attenuation due to the water and the air within the test section.

The void fraction along the X-ray path, inside the flow section, is noted α and is defined by:

$$\alpha = \frac{x_b}{x_b + x_w} = \frac{x_b}{l_{\text{xray}}} \quad (5)$$

¹ The zero crossing linearity of the signal with variations of the exposure time has been checked.

$l_{xray} = x_b + x_w$ is the length of the path of the X-ray beam within the flow.

The combination of equations (4) and (5) leads to:

$$\ln\left(\frac{I_x}{I_{x_0}}\right) = \underbrace{-l_{xray}(\mu_b - \mu_w)}_A \alpha - \underbrace{(\mu_{air}x_{air} + \mu_p x_p + l_{xray}\mu_w)}_B$$

$$\ln\left(\frac{I_x}{I_{x_0}}\right) = A\alpha + B \quad (6)$$

The measurement of the void fraction using X-ray attenuation relies on the determination of the constants A and B through calibration. In practice, A and B are estimated using measurements with the pipe full of air and water.²

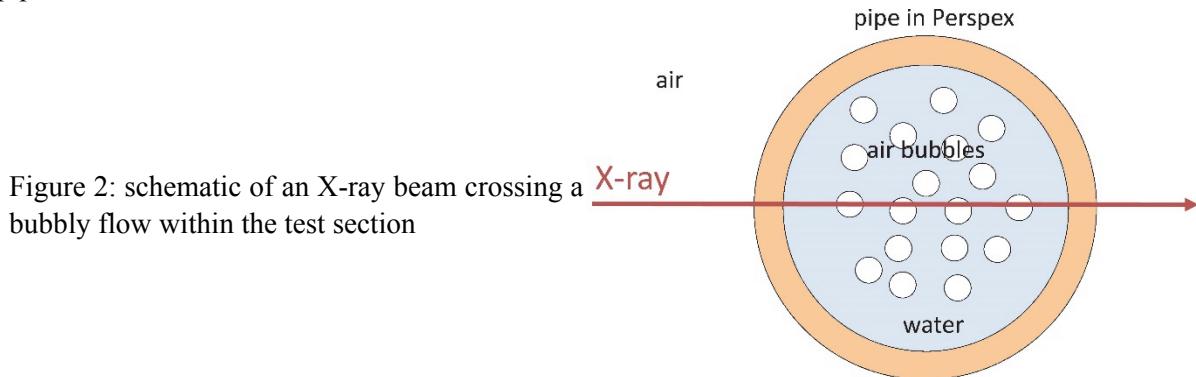


Figure 2: schematic of an X-ray beam crossing a bubbly flow within the test section

Fig. 3a illustrates the temporal average of the signals obtained for the pipe full of air, full of water and for a slug flow. This permits to measure the void fraction along the path of the X-ray beam during each exposition of the detector. For this slug flow, Fig. 3b gives a pictorial illustration of such temporal measurements during 2.816s. Each column of the picture represents one measure of the 1D X-ray sensor and the picture is made of 1280 columns.

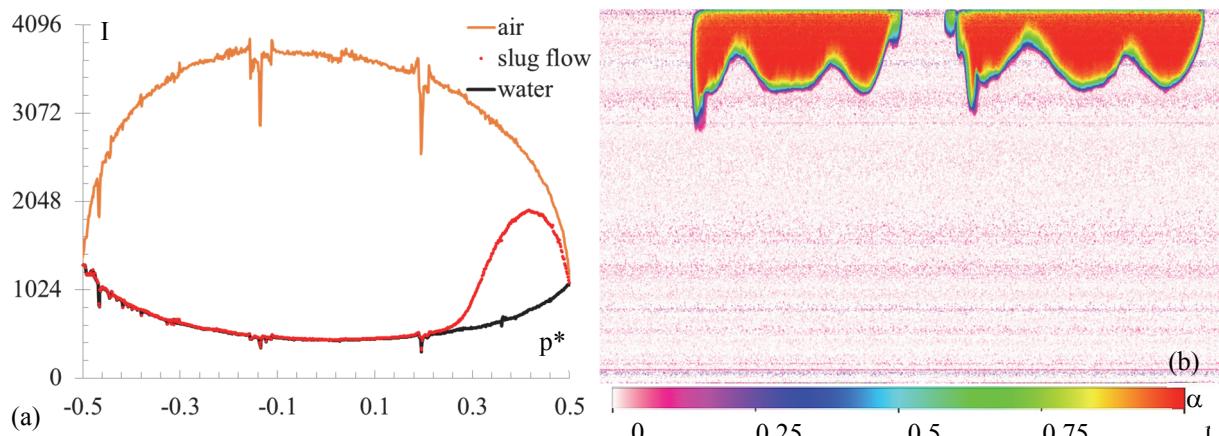


Figure 3: (a) average recorded signal for the pipe full of air, the pipe full of water and a slug flow. The abscissa is the dimensionless projection of the pipe on the detector, noted p^* . (b) Illustration of temporal void fraction measurements (the color scale shows α) for a slug flow and a duration of 2.816s. The columns of the picture correspond to 1280 consecutive 1D measurements. For (a) and (b) the X-ray sensor is vertical, which corresponds to the position referred as 0°.

The accuracy of void fraction measurements is checked by varying the water depth within the pipe while the flow is at rest. The measured void fraction can then be estimated from simplified geometrical

² This linear relation between α and $\ln(I_x/I_0)$ supposes that the effects of the hardening of the X-ray beams spectrum are negligible. The validity of this hypothesis is confirmed later.

consideration based on the level of the free surface.

Fig. 4a illustrates the comparison between measured and theoretical void fraction. The average of the root mean square of the differences between measured and theoretical values is about 0.013. This result indicates the accuracy of the void fraction measurements performed.

Fig. 4b gives the measured void fraction versus the theoretical values along the median vertical axis of the pipe. There is a good agreement between these values which follows the straight line $\alpha_{\text{meas}} = \alpha_{\text{theo}}$. Moreover, the linearity of this result shows that the relation between $\ln(I_x/I_0)$ and α can well be considered as linear with negligible effects of the hardening of the X-ray beams spectrum in these experiments. This is thanks to the increase in voltage, i.e. X-ray energy, since previous works at 40kV [16] demonstrated such a hardening effect.

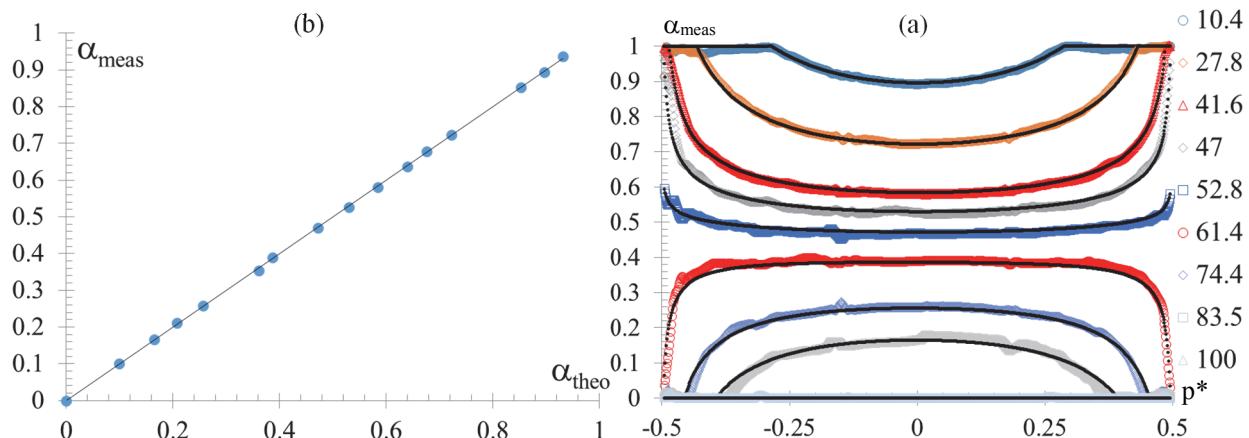


Figure 4: void fraction measurements for different water levels within the pipe. (a) void fraction measured, noted α_{meas} , versus the projection of the pipe on the detector in abscissa, noted p^* . The legend indicates the water level in mm. The black dots correspond to theoretical estimations on a simplified geometry. (b) Measured void fraction, α_{meas} , versus theoretical void fraction, α_{theo} , along the median vertical axis of the pipe.

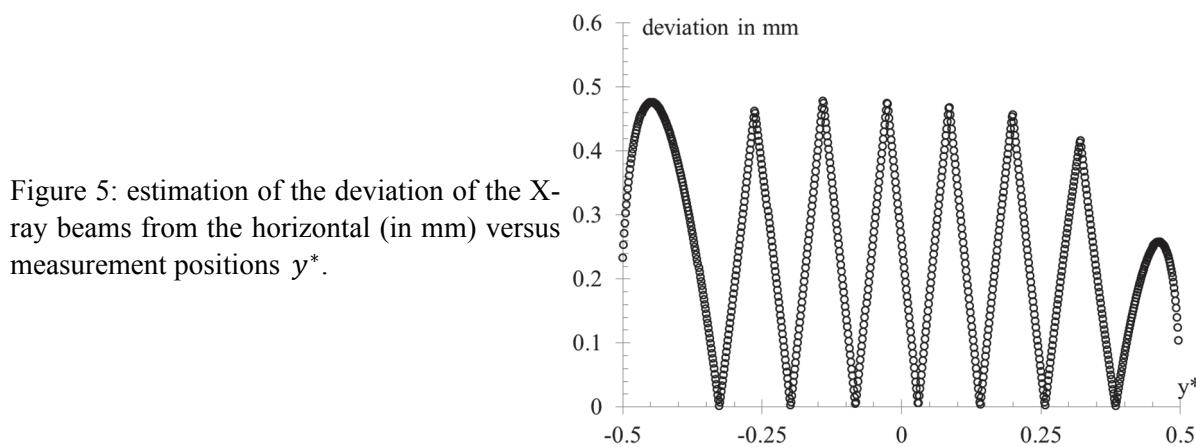


Figure 5: estimation of the deviation of the X-ray beams from the horizontal (in mm) versus measurement positions y^* .

To build the vertical distribution of the void fraction within the pipe, several angular positions of the source-detector pair are needed. Indeed, the void fraction is measured along the path of the X-ray beams and these beams are not all parallel to the horizontal. To ensure deviations from the horizontal smaller than 0.5mm, between the two extremities of the flow cross section along the X-ray path, seven angular positions are needed. These positions are -3.5° , -2.25° , -1.1° , 0° , 1.1° , 2.25° and 3.5° . The vertical distribution of the void fraction is then built from these seven measurements by selecting the results minimizing the deviation from the horizontal. It can be indicated that, with this set of angles, the mean

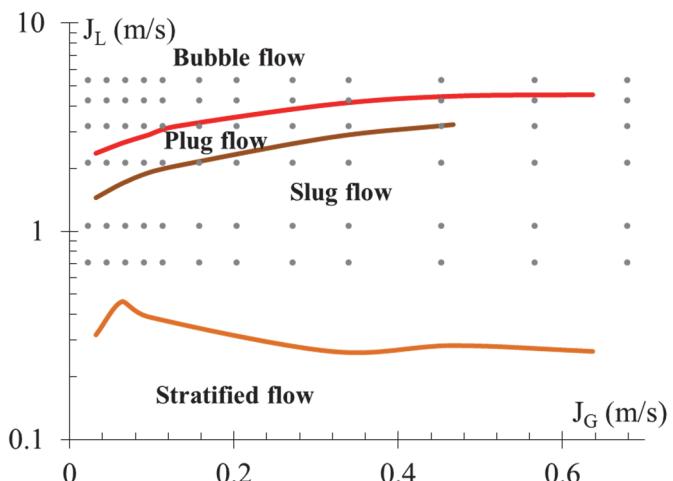
deviation from horizontal is 0.24mm with a standard deviation of 0.14mm. This discretisation over seven angles sounds sufficient as it is about the pixel resolution of the detector and it is smaller than the targeted 0.01D resolution of the measurement. The Fig. 5 gives the estimation of these deviation from the horizontal versus the measurements positions y^* . The seven minima observed, with deviations equals to zero, occur when the horizontal X-ray beams cross the corresponding measurement points.³

2.3. Experimental investigations

Experimental investigations are conducted at different axial positions downstream the grid (10.4D, 20.6D and 41.3D) and for different air and water flow rates. Experiments are performed at 18.05°C⁴ and atmospheric pressure.

METERO's flow map according to the liquid and gas superficial velocities, respectively $J_L = Q_{wat}/S$ and $J_G = Q_{air}/S$ where S is the flow cross section, has been established in [8] at about 40D downstream the grid. Fig. 6 gives the distribution of investigated flow parameters according to METERO's flow map (at 40D) while table 1 gives corresponding numerical values. ReL refers to the liquid Reynolds number, $Re_L = J_L D / \nu$ where ν is the kinematic viscosity of the liquid.

Figure 6: distribution of the experimental data according to METERO's flow map [8] at 40D.



Water						
Q _{wat} [m ³ /h]	20	30	60	90	120	150
ReL	71 000	110 000	210 000	320 000	420 000	530 000
J _L [m/s]	0.71	1.06	2.12	3.18	4.24	5.31
Air						
Q _{air} [Nl/min]	10	20	30	40	50	70
J _G [m/s]	0.023	0.045	0.068	0.091	0.11	0.16
						0.20
						0.27
						0.34
						0.45
						0.57
						0.68

Table 1: flow parameters varied in the experiments. Nl/min corresponds to the conversion of the measured mass flow rate in l/min for 0°C and 1atm.

³ The position of the minimum of deviation corresponding to the angle 0° is close to $y^* = 0$ but slightly different. This is due to the position of the pipe's axis which is a slightly higher than the axis of the measurement device.

⁴ The variance of the recorded temperature is 0.76°C.

3. RESULTS AND DISCUSSION

To help comparing different flow cases an inlet void fraction, noted α_Q , is built as:

$$\alpha_Q = \frac{Q_{air}}{Q_{air} + Q_{wat}} \quad (7)$$

3.1. Vertical distribution of the horizontal void fraction at 41.3D

First the profile of vertical distributions of the void fraction, α , varying Q_{air} for the Reynolds number 420 000 and 110 000 are given in Fig. 7 at 41.3D.

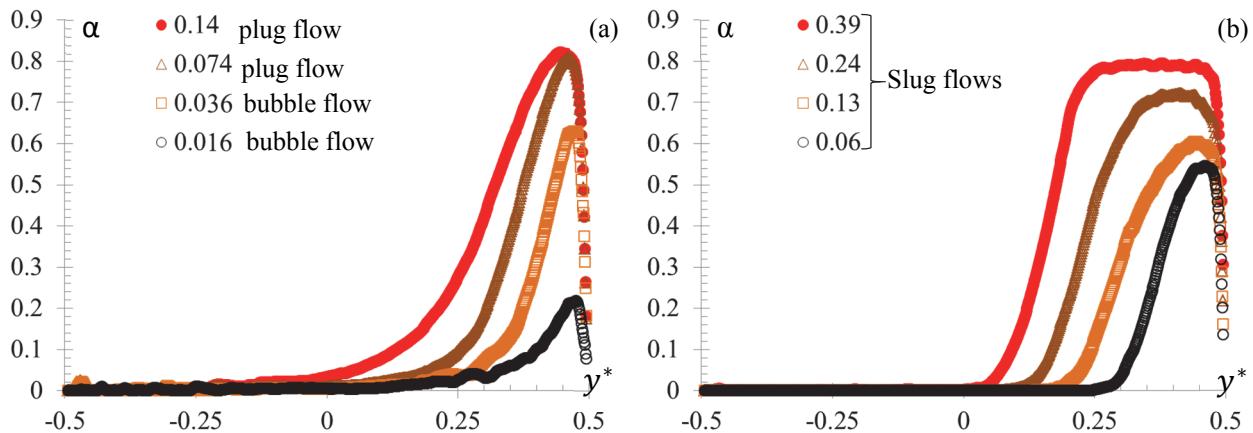


Figure 7: vertical distribution of the void fraction α versus y^* for J_G values of 0.68, 0.34, 0.16 and 0.068 m/s for (a) Re_L 420 000 and (b) Re_L 110 000. The corresponding values of α_Q (0.14, 0.074, 0.036, 0.016 and 0.39, 0.24, 0.13, 0.06) are indicated in the symbols' legend. $x=41.3D$.

For $Re_L=420\,000$, the flows change from the bubble to the plug flow regime when increasing the air flow rate. For all cases, the air accumulates in the upper part of the pipe. When increasing the air flow rate, the maxima of the void fraction increase toward a maximum value of about 0.8. It can be noted that for the plug flows the maximal value of α varies slightly and the main effect is an increase in the size of the plug and of the domain where the void fraction is significant, i.e. $\alpha \geq 0.02$.

For $Re_L=110\,000$, the flow stays in the slug flow regime when increasing the air flow rate. The increasing of α_Q leads to an increase of the maxima of α and an increase of the domain where the void fraction is significant. The appearance of plateaus of increasing length for the maximal values is also an indication of the increase of the height of the slugs within the pipe.

Second, the profile of vertical distributions of the void fraction, α , varying Q_{wat} for the J_G values of 0.068 and 0.68 are given in Fig. 8 at 41.3D.

For $J_G=0.68$ the flows change from slug to plug and bubble flow regimes when increasing the water flow rate. As previously discussed, the slug flow cases present a plateau with an increase of the maxima values and of the domain of significant void fraction with the increase of α_Q . Two new points are interesting to note: i) the transition from slug flow to plug flow leads to an increase of the maximum value of α combined with the disappearance of the plateau; ii) the transition from plug to bubble flow regimes leads to a sharpening of the profile close to the maxima values of α and an increase of the domain where the void fraction is significant. This can be related to the dispersion of bubbles within the core of the flow [8].

For $J_G=0.068$ the flows also change from slug to plug and bubble flow regimes when increasing the water flow rate. This case complements the case $J_G=0.68$ by focusing on cases with low values of α_Q . It can be noted that the bubble flow (which also corresponds to the highest Reynolds number) presents values of α larger than the other flow regimes in the core part of the flow, in particular for $0 \leq y^* < 0.3$.

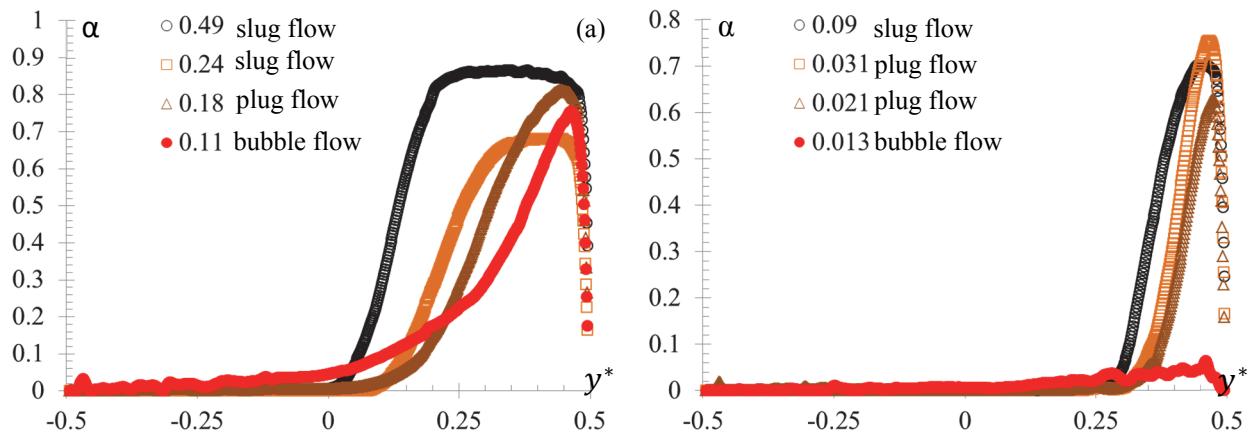


Figure 8: vertical distribution of the void fraction α versus y^* for J_L values of 0.71, 2.12, 3.18 and 5.31 m/s for (a) $J_G=0.68$ and (b) $J_G=0.068$. The corresponding values of α_Q (0.49, 0.24, 0.18, 0.11 and 0.09, 0.031, 0.021, 0.013) are indicated in the symbols' legend. $x=41.3D$.

3.2. Changes of α distribution with the development of the flow

3.2.1. Bubble flows

Fig. 9 shows the changes in the distribution of the void fraction with the longitudinal development of two bubble flows with α_Q close to 0.116. With the longitudinal development of the flow, the void fraction increases in the upper part of the pipe while it decreases in the bottom part for both cases. It is interesting to note that the results obtained for $J_L=4.24\text{m/s}$ and 5.31m/s looks similar for $41.3D$ and $20.6D$ respectively.

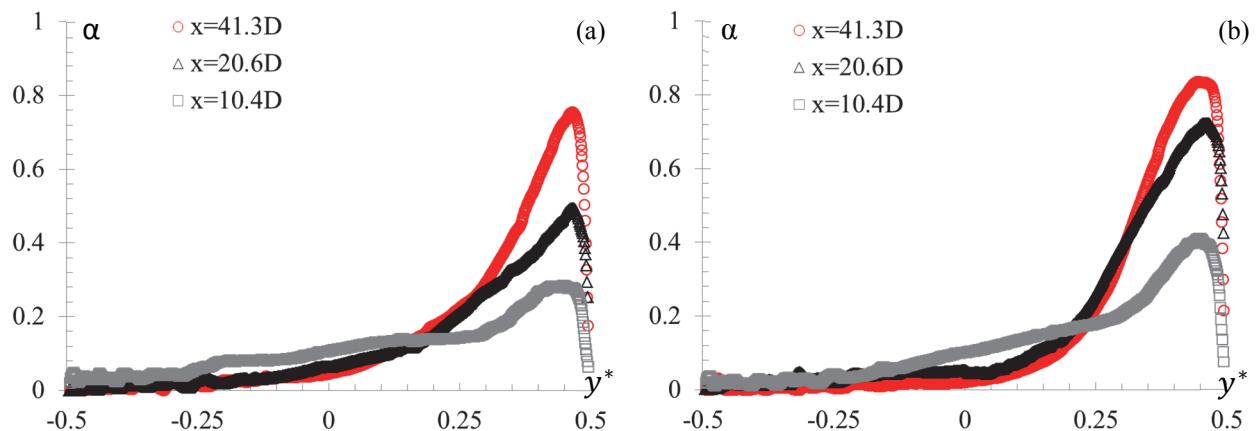


Figure 9: α versus y^* at positions $10.4D$, $20.6D$ and $41.3D$ for α_Q about 0.116. J_L values are 5.31m/s (a) and 4.24m/s (b) which respectively correspond to Re_L numbers of 530 000 and 420 000.

Fig. 10a directly compares these two cases while 10b compares the same cases at positions $20.6D$ and $10.4D$. These results are relatively close. This may support that the temporal integration of buoyancy effects has evolved similarly for both cases. Fig. 10c shows the comparison between $J_L=4.24\text{m/s}$ and 3.18m/s for α_Q about 0.021 at positions $10.4D$ and $41.3D$. Again the two results are close.

It is important to note that the time scales during which the buoyancy effects are integrated, i.e. the travelling time of the flow between the considered cross section and the inlet conditions for a given flow rate, are significantly different. The ratio of these durations are about 1.6 for Fig. 10a and Fig. 10b whilst it is about 3 for Fig. 10c. This highlights the impact of the turbulence on the void distribution and importance of nonlinear processes in the development of turbulent multiphase flows.

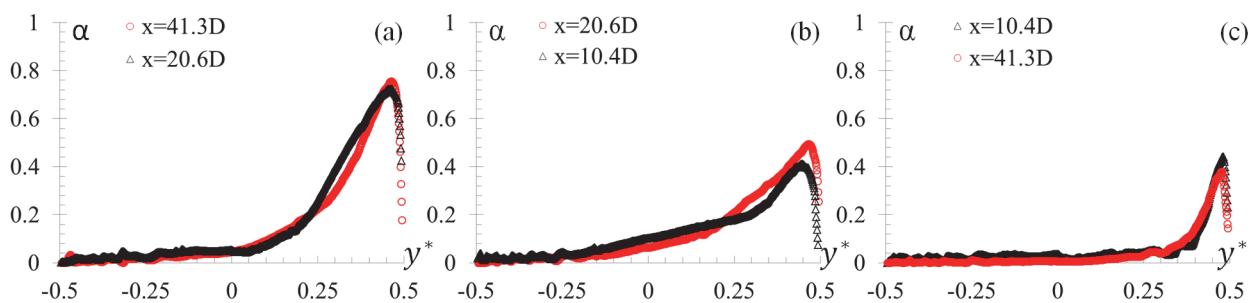


Figure 10: vertical distribution of the void fraction α versus y^* ; (a,b) α_Q about 0.116 (a) $J_L=4.24\text{m/s}$ at $20.6D$ and $J_L=5.31\text{ m/s}$ at $41.3D$, (b) $J_L=4.24\text{m/s}$ at $10.4D$ and $J_L=5.31\text{ m/s}$ at $20.6D$; (c) $\alpha_Q=0.021$ $J_L=4.24\text{m/s}$ at $41.3D$ and $J_L=3.18\text{ m/s}$ at $10.4D$.

3.2.2. Slug flows and complex transitions

Fig. 11 shows the evolution of the profile of α versus y^* at positions $10.4D$, $20.6D$ and $41.3D$ for $\alpha_Q=0.113$, $J_L=2.12\text{m/s}$ and $J_L=0.71\text{m/s}$. It can be noted that as opposed to the bubble flows cases, the void fraction maxima decreases with the longitudinal development of the flow. Two different reasons can be highlighted: i) in the case of Fig. 11a the flow regime changes from position $10.4D$ to $41.3D$. At $10.4D$ the flow looks like a bubble flow with a continuous plug (or foam) at the top. At $41.3D$ the flow has evolved toward a slug flow; ii) In the case of Fig. 11b, the flow regime is similar to a slug flow for the three positions. What is observed is an increase of the height of the slugs with a decrease of their frequency.

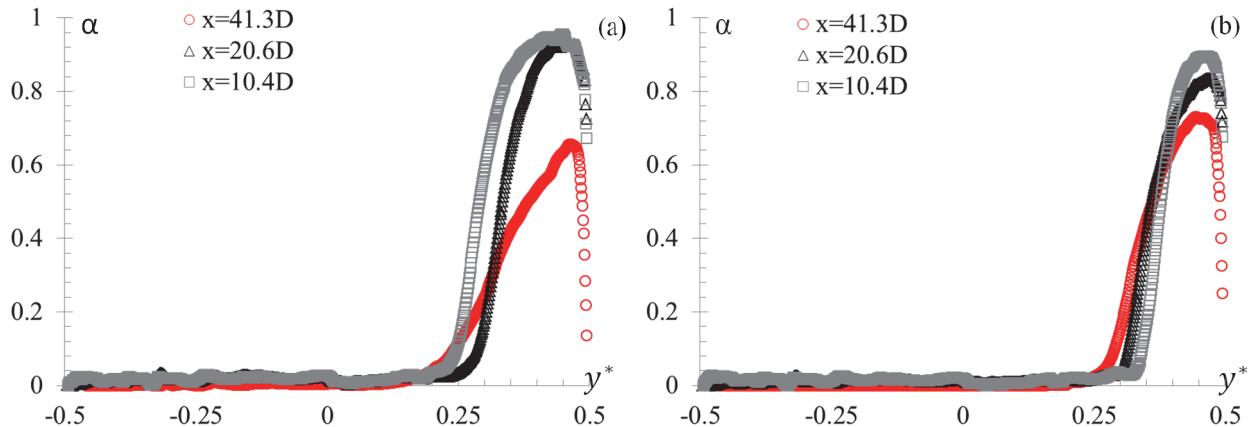


Figure 11: α versus y^* at positions $10.4D$, $20.6D$ and $41.3D$ for α_Q about 0.113. J_L values are 2.12m/s (a) and 0.71m/s (b) which respectively correspond to Re_L numbers of 210 000 and 71 000.

3.3. Void fraction in the flow cross-section versus α_Q and relative phase velocities

The void fraction in the flow cross-section is estimated by integrating the horizontal void fraction over y^* :

$$\alpha_S = \frac{1}{S} \int_{-0.5}^{0.5} \alpha l_{y^*} D dy^* \quad (8)$$

where S is the area of the flow cross-section, l_{y^*} is the horizontal chord length at the height y^* .

Fig. 12a gives α_S versus α_Q at $41.3D$. It can be noted that α_S is closer to α_Q for bubble flows than for slug flows. It is observed that for bubble flows $\alpha_S \sim \alpha_Q$ and that for slug flows $\alpha_S \sim \frac{3}{5} \alpha_Q$.

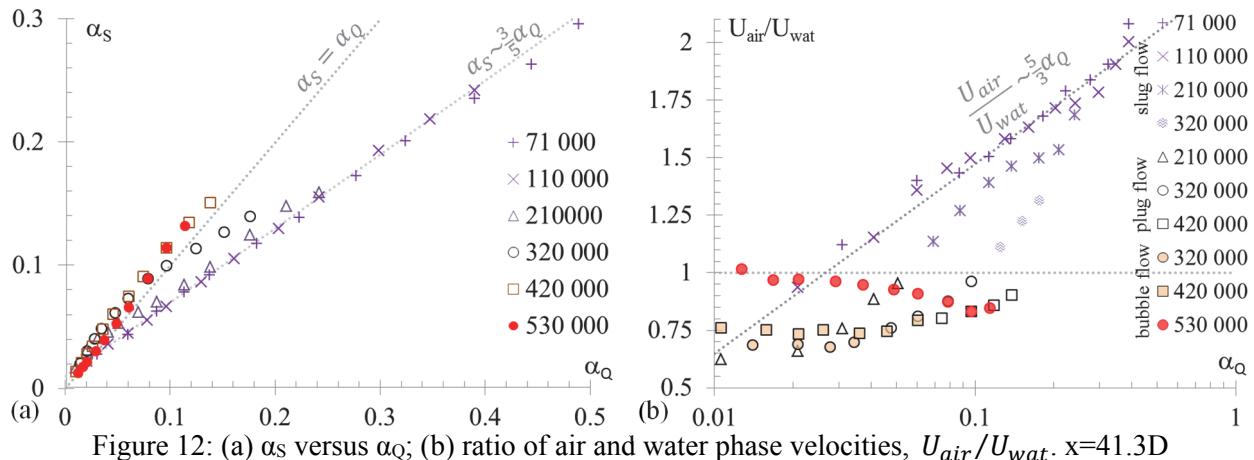
The average cross section of air and water can be calculated using α_S . The mean air and water velocities, i.e. phase velocities of air and water, respectively noted U_{air} and U_{wat} are be estimated as:

$$U_{air} = \frac{Q_{air}}{\alpha_S S} = \frac{J_G}{\alpha_S} \quad (9)$$

$$U_{wat} = \frac{Q_{wat}}{(1-\alpha_S)S} = \frac{J_L}{1-\alpha_S} \quad (10)$$

Fig. 12b shows U_{air}/U_{wat} versus α_Q at position 41.3D. It can be shown that the slugs of air are generally moving faster than the water with variations of U_{air}/U_{wat} observed to vary like $\frac{5}{3}\alpha_Q$. For the bubble and plug flow, the mean speed of air is generally observed to be smaller than the mean speed of water. This is due to the accumulation of air in the upper part of the flow where the increase of friction leads to a local decrease of the flow speed whilst the flow speed increases in the lower part of the pipe when compared to the upper part and/or to the single-phase water flow [8]. U_{air}/U_{wat} is closer to 1 for the highest Reynolds number than for the two others. This is due to a larger turbulence dispersion of bubbles leading to a higher void fraction on (and below) the pipe axis in the case of the highest turbulent intensity.

For plug flows it is generally observed that the mean velocity of air is smaller than the mean velocity of water for similar reasons than for the bubble flow cases.



4. CONCLUSIONS

The basics of void fraction measurements using X-ray attenuation have been exposed. The construction of the vertical distribution of the void fraction measured over horizontal lines has been discussed before presenting results obtained from multiphase flows in a horizontal pipe. The vertical void fraction profiles are discussed accordingly to flows Reynolds numbers, injected void fraction α_Q and the development of the multiphase flows along the pipe. Positions investigated are 10.4D, 20.6D and 41.3D⁵.

The accumulation of void fraction in the upper part of the pipe is set in evidence in all cases.

The non-linearity of the evolution of the void fraction profiles with the flows travelling time is also highlighted for similar α_Q . This is attributed to the importance of non-linear coupling between the effects of buoyancy forces and turbulence over the settling of multiphase flows.

Using the integration of α over the pipe height, the void fraction within the cross section α_S is estimated for measurements obtained at 41.6D. It is observed that for bubble flows $\alpha_S \sim \alpha_Q$ and that for slug flows $\alpha_S \sim \frac{3}{5}\alpha_Q$.

⁵ Current works include the extension of X-ray measurements to the position 1D to complement the description the void fraction along the pipe.

The phase velocities are deduced from superficial velocities and α_S . It is observed that due to the accumulation of bubbles in the upper part of the flow (where the flow is going slowly than in the bottom part [8]) the air phase velocity is generally smaller than the water phase velocity for bubble and plug flows. On the contrary, the air phase velocity is generally higher than the water phase velocity for slug flows. In addition, it is observed that U_{air}/U_{wat} varies like $\frac{5}{3}\alpha_Q$ for slug flows.

Current works include the studies of optical probe and PIV measurements performed within the same experimental conditions than the present X-ray measurements. Results from these studies could be integrated in the conference presentation so as to complement the flow's description.

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