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# IMPACT OF MACHINE STIFFNESS AND HEAT TREATMENTS ON CRACK PROPAGATION INSTABILITIES IN AN AL-MG-SI ALLOY

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## DEFINITION

## EXPERIMENTAL INVESTIGATIONS

## INSTABILITY CRITERIA

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 DEFINITION →
 EXPERIMENTAL INVESTIGATIONS
 → Mechanical properties → Fracture mechanisms
 → Mechanical properties → Machine stiffness
 → Mechanical properties → Machine stiffness
 → Mechanical properties → Machine stiffness
 → Mechanical properties → Machine stiffness

Fracture toughness tests

→ "**Pop-in**" = **local instability** leading to **rapid but limited crack propagation** associated with a sudden decrease in load









Impact of machine stiffness and heat treatments on crack propagation instabilities in an Al-Mg-Si alloy INSTA Ce2 → Mechanical properties **DEFINITION → INVESTIGATIONS** → Fracture mechanisms → Machine stiffness 

➡ Aluminium 6061-T6

 $\implies$  Age-hardened alloy  $\rightarrow$  4 aging times (175 °C) to obtain 4 metallurgical states:



Atom Probe Tomography

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➡ Fracture toughness tests:



➡Pop-in appearance after 12 and 16 hours of aging time

 

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### ➡ Fracture toughness tests:



➡ Link between : Low strain hardening ability High strength

#### DEFINITION → EXPERIMENTAL INVESTIGATIONS → Mechanical properties → Fracture mechanisms → Michanical properties → Machine stiffness → Michanical properties → Michanical prop

#### ➡ Fracture mechanisms:

### **No pop-in** (aging: 4 h)





With pop-in (aging : 12 h)



<u>200 µm</u>

#### Scanning electron microscope

- Broken coarse  $Mg_2Si$  in dimples
- Nucleation controlled by **coarse precipitates** (Mg<sub>2</sub>Si & IMF)

- Ductile failure micromechanisms
- Void growth to coalescence by internal necking (and voidsheeting) mechanisms

### No difference in zone with and without pop-in

#### 

#### ➡ Fracture mechanisms:



Scanning electron microscope + EBSD





No preferential localization of coarse particles: mainly transgranular fracture
 Intergranular fracture around the small grains

**INVESTIGATIONS** → Machine stiffness

EXPERIMENTAL

 $\underbrace{Cea}_{\text{DEFINITION}} \rightarrow$ 

➡ Fracture mechanisms:



Tomography: Synchrotron laminography (ESRF, Grenoble)

 $\rightarrow$  Mechanical properties

 $\rightarrow$  Fracture mechanisms

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➡ Ductile failure, very rough crack surface

Heterogeneous presence of large clusters of porosity at the crack tip

No difference in zone with and without pop-in

#### DEFINITION → EXPERIMENTAL INVESTIGATIONS → Mechanical properties → Fracture mechanisms → Mechanical properties → Machine stiffness → Mechanical properties → Machine stiffness → Mechanical properties → Machine stiffness





 

 DEFINITION →
 EXPERIMENTAL INVESTIGATIONS
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→ 5 tests after 8 hours with 5, 7, 8, 10 and 15 washers







DEFINITION →EXPERIMENTAL<br/>INVESTIGATIONS→ Mechanical properties<br/>→ Fracture mechanisms→ INSTABILI<br/>CRITERIA

Instability criterion ? Imp 'Load' approach

$$\frac{\partial P}{\partial u_s^p} \le -K_t(N, u_s^p) \Longrightarrow S(N, u_s^p) = \frac{\partial P}{\partial u_s^p} + K_t(N, u_s^p) \le 0?$$



**Excellent agreement** between the predictions of the criterion and the tests

Instability criterion ? Load 'approach

## → 'J-integral' approach

 $\implies$  Reasoning developed by Paris et al., 1979

 $\implies$  General small-scale yielding case

$$J(P, a) = \frac{K(P, a)^2}{E}$$

$$dJ(P, a) = \frac{\partial J(P, a)}{\partial P} f(P, a) da + \frac{\partial J(P, a)}{\partial a} da$$

$$\frac{dJ}{da}(P, a) = T_{app} = g(P, a)$$

$$T_{mat} = \frac{dJ_{mat}}{da} \le T_{app}(P, a)$$

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 → Michine stiffness
 → Michine stiffness

- $\Rightarrow$  Conclusions :
  - Pop-ins studied are purely mechanical crack growth instabilities
  - Result from the interaction of the **material behavior** (favored by a decrease of tearing modulus) and **imposed loading** (favored by a high compliance of the total system)
  - System stiffness
     POP-IN

• 2 instability criteria



**Crack growth toughness** 

Impact of machine stiffness and heat treatments on crack propagation instabilities in an Al-Mg-Si alloy EXPERIMENTAL INSTABILITY ĽZ → Mechanical properties **DEFINITION → INVESTIGATIONS** → Fracture mechanisms → Machine stiffness **CRITERIA** Finite-element simulation Gurson law Arc-Length method (Riks, 1979) 3000 2000 Load (N) -775 N/mm 1000 1 551 N/mm 2 326 N/mm 3 102 N/mm -77 546 N/mm Pop-in 0 0 1 3 4 Machine displacement (mm) -4e+02 -3e+02 -2e+02 -1e+02 0 1e+02 2e+02 3e+02 4e+02 -5e+02 5e+02

⇒ Spring creates numerical pop-in

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sig22 map:1.00000 time:0.0001

Impact of machine stiffness and heat treatments on crack propagation instabilities in an Al-Mg-Si alloy **EXPERIMENTAL** INSTABILITY ĽZ → Mechanical properties **DEFINITION → INVESTIGATIONS** → Fracture mechanisms → Machine stiffness **CRITERIA** Finite-element simulation Gurson law Arc-Length method (Riks, 1979) 3000 2000 Load (N) -775 N/mm 1000 1 551 N/mm 2 326 N/mm 3 102 N/mm -77 546 N/mm Pop-in 0 0 1 3 4 Machine displacement (mm) -4e+02 -3e+02 -2e+02 -1e+02 0 1e+02 2e+02 3e+02 4e+02 -5e+02 5e+02

Spring creates numerical pop-in

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#### Fracture toughness tests:



decrease in crack initiation toughness J0,2 and crack growth toughness dJ\_mat/da with aging time.





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#### Comparison of keycurve / compliance methods



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➡ General small-scale yielding case

$$J(P,a) = \frac{K(P,a)^2}{E}$$

$$dJ(P,a) = \frac{\partial J(P,a)}{\partial P} dP + \frac{\partial J(P,a)}{\partial a} da$$

$$dJ(P,a) = \frac{\partial J(P,a)}{\partial P} f(P,a) da + \frac{\partial J(P,a)}{\partial a} da$$

$$dJ(P,a) = \frac{\partial J(P,a)}{\partial P} f(P,a) da + \frac{\partial J(P,a)}{\partial a} da$$

$$\frac{dJ}{da}(P,a) = T_{app} = g(P,a)$$

$$T_{mat} = \frac{dJ_{mat}}{da} \le T_{app}(P,a) = g(P,a)$$

$$T_{mat} = \frac{dJ_{mat}}{da} \le T_{app}(P,a_{eff}) = \frac{g(P,a_{eff})}{1 - \frac{E}{\gamma \pi \sigma_y^2} g(P,a_{eff})}$$



$$\frac{\partial J}{\partial P}(P,a) = \frac{2P(2+\frac{a}{W})^2}{BB_N WE\left(1-\frac{a}{W}\right)^3} \sum_{i=0}^4 \alpha_i \left(\frac{a}{W}\right)^i$$

$$\begin{aligned} \frac{\partial J}{\partial a}(P,a) &= \frac{P^2 (2 + \frac{a}{W})}{BB_N WE \left(1 - \frac{a}{W}\right)^3} \sum_{i=0}^4 \alpha_i \left(\frac{a}{W}\right)^i \left[ (2 + \frac{a}{W}) \sum_{i=0}^3 \beta_i \left(\frac{a}{W}\right)^i + \frac{2}{W} \sum_{i=0}^4 \alpha_i \left(\frac{a}{W}\right)^i + \frac{3(2 + \frac{a}{W})}{W(1 - \frac{a}{W})} \sum_{i=0}^4 \alpha_i \left(\frac{a}{W}\right)^i \right] \end{aligned}$$

$$f(P,a) = -BK_m P \frac{\sum_{i=0}^7 \gamma_i W^{7-i} a^i}{BB_N E \sum_{i=0}^3 \delta_i W^{8-i} a^i + BK_m \sum_{i=0}^8 \varepsilon_i W^{8-i} a^i + EB_n^2 \sum_{i=0}^3 \zeta_i W^{8-i} a^i}$$

$$g(P,a) = \frac{P^2 (2 + \frac{a}{W})}{BB_N WE \left(1 - \frac{a}{W}\right)^3} \left[ \sum_{i=0}^4 \alpha_i \left(\frac{a}{W}\right)^i \right]^2 \left[ \frac{2}{W} + \frac{3(2 + \frac{a}{W})}{W(1 - \frac{a}{W})} + \frac{(2 + \frac{a}{W})\sum_{i=0}^3 \beta_i \left(\frac{a}{W}\right)^i}{\sum_{i=0}^4 \alpha_i \left(\frac{a}{W}\right)^i} + \frac{-2BK_m \left(2 + \frac{a}{W}\right)\sum_{i=0}^7 \gamma_i W^{7-i} a^i}{BB_N E \sum_{i=0}^3 \delta_i W^{8-i} a^i + BK_m \sum_{i=0}^8 \varepsilon_i W^{8-i} a^i + EB_n^2 \sum_{i=0}^3 \zeta_i W^{8-i} a^i} \right]$$

	0	1	2	3	4	5	6	7	8
αį	0.886	4.64	-13.32	14.72	-5.6				
β <sub>i</sub>	9.28	-53.28	88.32	-44.8					
γi	11564	13440	-47940	16036	82907	-48357	-38547	26865	
δi	1000	-3000	3000	-1000					
Si.	1403	7355	-6417	-18321	15994	16573	-16353	-5607	5373
<u>Li</u>	-500	1500	-1500	500					



No mobile strain bands
No serration on the stress-strain curve
No reverse sensitivity to strain rate

No PLC effect (contrary to the literature)

No link PLC / pop-in



### ➡ Aluminium 6061-T6

 $\implies$  Age-hardened alloy  $\rightarrow$  4 aging times (175 °C) to obtain 4 metallurgical states:



Atom Probe Tomography





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• Rajout d'un ressort à raideur variable dans la simu 2D :



- Pilotage en longueur d'arc : méthode incrémentale de Riks
- Principe : ajouter aux équations d'équilibre une équation imposant la longueur du vecteur incrémental dans le plan charge/déplacement -> le chargement appliqué devient une variable additionnelle du problème







- Paramètres d'optimisation :
  - $q_1$  (Tvergaard). Potentiel plastique :  $\phi(\sigma_{eq}, \sigma_m, \overline{\sigma}, f) = \left(\frac{\sigma_{eq}}{\overline{\sigma}}\right)^2 + 2q_1 fcosb \left(\frac{3q_2\sigma_m}{2\overline{\sigma}}\right) (1+q_3f)^2 = 0$
  - A<sub>n0</sub>
  - $\sigma_M$
  - fact (facteur géométrique permettant de dilater le maillage fin)



- Zebulon
- Eléments quadrangles (8 noeuds) linéaires à intégration sélective
- Comparaison 2D déf planes 3D validée
- Différents traitements thermiques :
  - Loi élastoplastiques (Voce) différentes
  - Lois d'endommagement (Gurson et nucléation par les contraintes) identiques





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